

MAN.1857

Prime Computer Microcoders Handbook

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M I C R O C O D E R S

H A N D B O O K

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COMPUTER, INC.

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SECTION 1

INTRODUCTION

1.1 SCOPE OF DOCUMENT

The intent of this document is to present enough information to permit a person with a solid assembly language and machine language programming background to prepare complete microcode programs. This includes a study of what is feasible through the use of microcode; the algorithms that are appropriate; and a discussion of good practices for coding, assembling, debugging, and executing microcode. The largest body of material to be covered is a detailed description of the way that the microcode controls the individual hardware components in the machine. The document begins with the simplest description of microcode control and slowly builds on that description until the complete capability of the 64-bit microcode word is demonstrated.

1.2 WHY MICROCODE

The fundamental reason for implementing an algorithm or functionality in writable control store rather than in standard users' software is to gain an increase in performance. Execution speeds of microcode algorithms versus software algorithms can be expected to be at least twice and perhaps as many as ten times as fast. Secondly, there are capabilities that exist in microcoding that simply are not available to the standard user-level software. Examples of these capabilities include: the ability to build custom high-speed I/O disciplines, the ability to implement different memory management techniques other than the virtual memory which is available standardly, and the ability to do byte operations directly on memory. Examples when microcoding may be justifiable include (1) customer algorithms, (2) emulating a different machine architecture, (3) adding new instructions, and (4) building high level language run-time interpreters.

1.2.1 Custom Algorithms

A custom algorithm that might be put in microcode should be an easily and completely definable set of operations to translate or reduce data from one form to another. Additionally, this one algorithm or operation should be the major function of the machine so that the improved speed of the execution of this algorithm can be directly translated into improved system performance. Examples of algorithms that might be appropriate include a fast Fourier Transform or any of the standard statistical calculation equations (means, deviations, significance calculations and so forth).

Whether a function can be profitably put into microcode is primarily a question of economics that depends very much on the situation. However, some functions are technically more likely to profit from being microcoded than others. In particular, table reductions involving many additions and subtractions and perhaps multiplications and division, temporary storage, and different paths of operations depending on the particular value of the in-process calculation could be more profitably microcoded than another algorithm that is fundamentally a simple translation of one table to another. The reason for this relative advantage is that, if there are many calculations and decisions and relatively few memory references, a programmable machine with a typical memory referencing instruction of slightly over one and a half microseconds is substituted for a programmable machine with an arithmetic or decision time of 200 nanoseconds.

Unfortunately, the main memory still runs at the same speed it always did, so if the microcode algorithm is primarily high-speed memory bound, relatively smaller improvements in execution time can be expected.

Another factor to consider when deciding if a custom algorithm is worth microcoding is to determine if the algorithm is already microcode limited when it is coded in assembly language. This could be true if the assembly language code consists primarily of multiplies, divides and long shifts where the majority of the execution time is determined by the speed of the microcode processor.

1.2.2 Emulating Machines

In emulating, the intent is to substitute the standard Prime Computer Instruction set for that of some different machine, probably with a different architecture. The primary motive for this activity is normally to take advantage of existing software and some other assembly language. In this case, there are two sides to the feasibility question. It's obvious that Prime itself was able to build an instruction set in microcode so that, of course, the task is in some sense useful. However, it is also true that a moderate amount of special hardware help specific to the Prime instruction set is available in the standard Prime Computer that would not be available when emulating a different machine.

1.2.3 Adding Instructions

Adding instructions to the Prime instruction complement is feasible and useful in a number of ways. Examples of potential candidates for instructions to be added would of course include

both user-specific instructions and, potentially, other general-purpose instructions that are not part of the Prime repertoire. Testing, setting and resetting particular bits in memory is an example of an instruction that could be added to the standard Prime instruction set using microcoding techniques.

1.2.4 High Level Language Run-Time Interpreters

An example of a high level language run-time interpreter is a set of microcode that executes using a table generated by a Basic compiler, at least as far as computational tasks are concerned. In general, a run-time interpreter differs from the emulation of a complete machine since I/O device handling; and perhaps file handling may be done by calls to standard systems software or assembly language I/O file handling routines.

1.3 WHY NOT MICROCODE?

Aside from the restrictions placed on the suitability for using microcode in the previous four paragraphs, there are other factors that must be considered before embarking on a microcoding project. The first of these is the question of development time. Because microcode is much closer to the hardware logic of the machine, it is much further from the aids that can be given to the programmer such as higher level languages and on-line debug. Second, many attributes of the Prime Computer that are normally assumed to be part of the hardware specifications of that computer are, in fact, microcode routines. Such features as DMX latency; in fact, all of the I/O functionality; the operation of the control panel; and the basic instruction fetch can be affected in non-obvious ways by errors in the new or added microcode routine. Of course, the fact that these features are microcoded can be considered as an almost undreamed of flexibility to be exploited in specific application-oriented sets of microcode.

Another factor that must be considered before serious attempts at microcoding can be considered is that of microcode space available for the function. The writable control store capability is limited to 256, 52-bit microcode words. Examples of the amount of functionality that can be put into that space are: the complete Prime Instruction Set including DMA occupies only 256 words and the single precision floating point package occupies 185 words of microcode. Of course, the total microcode address space is much larger than 256 words. However, standard Prime hardware for the processors offered to date does not implement this entire address space.

1.4 IMPLEMENTATION AIDS

1.4.1 Writable Control Store (WCS)

The logic for Writable Control Store is contained on a printed circuit board that connects to the Prime 300 central processor printed circuit board by cables on the back of the processor board and by the I/O bus backplane. This board implements 256, 52-bit words of very high speed RAM. This memory may be written into using PIO instructions and then may be entered by executing any of the enter and execute class of instructions implemented on the Prime 300. For more details, refer to Section 8.5, "Writable Control Store Board".

1.4.2 Microcode Assembler

The microcode assembler is a macro package inserted into a file of microcode source language. This macro package is used by the standard Prime macro assembler (PMA) to assemble the microcode source statements. As a result of this two-step approach to microcode assembly; and also because of the complexity of the microcode word, microcode assembles at the rate of about one line of object code per second. The minimum configuration on which a microcode assembler package can be expected to work is a 32K DOS/VM system. Features of this assembler are described in Section 8.3.

1.4.3 Microcode Debug Package

To be specified.

SECTION 2

MICROCODE CONTROL OF THE CPU

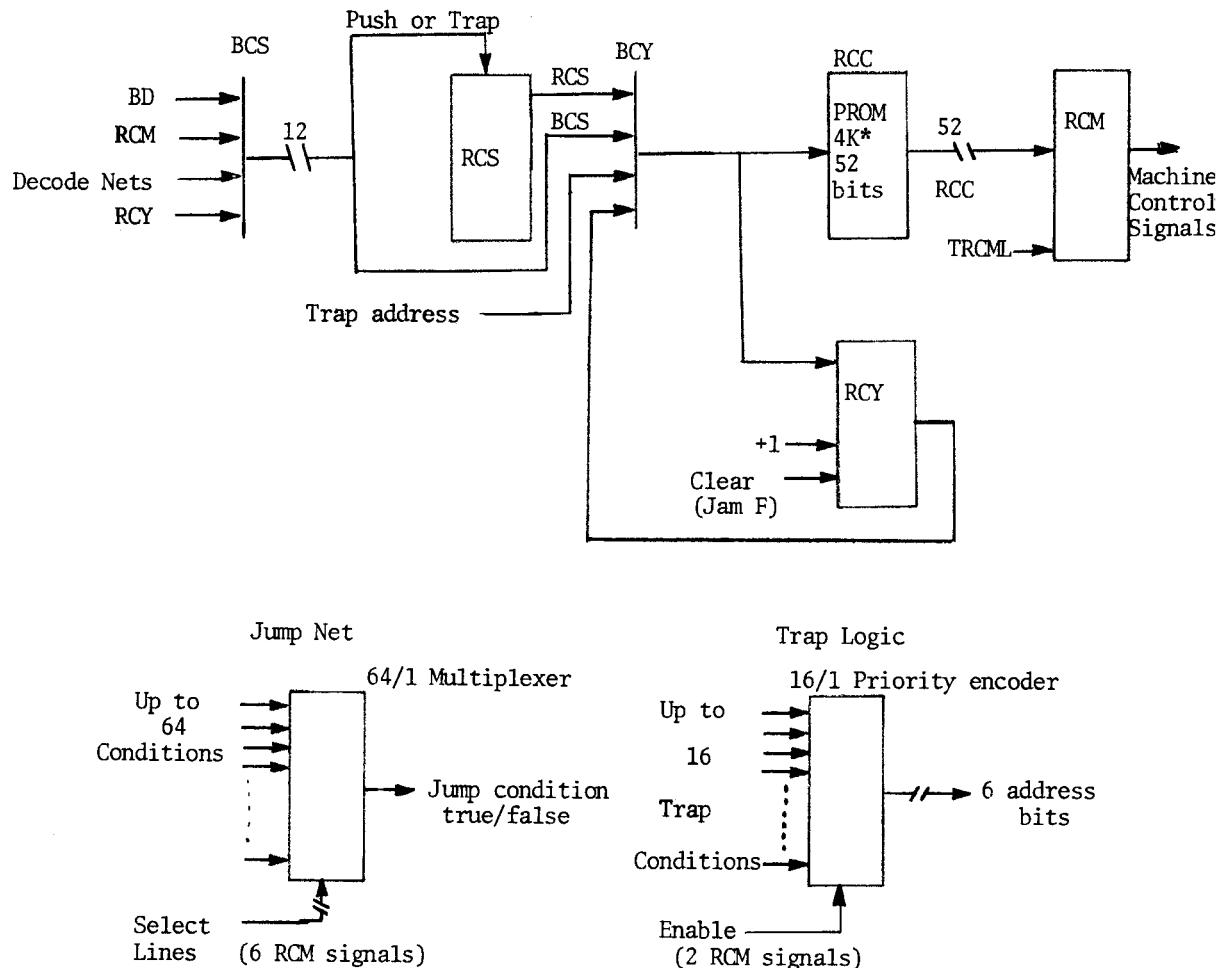
2.1 DESCRIPTION OF THE MACHINE

For the purposes of discussion, the hardware processor board may be divided logically into three major sections. The first section is the control logic, the second section is the controlled logic, and the third section consists of three major subsystems. The subsystems are memory, I/O and parity. Each of the three major sections of a machine is directly controlled by a field or combinations of fields in the microcode. For a diagram of these fields, refer to Appendix A, Figure 2. In addition, each major section has features and capabilities that are only controlled by the microcode and functionalities that are completely and totally implemented in hardware.

2.1.1 Control Logic

The control logic is illustrated in Figure 2-1. The functionality implemented in the control logic includes sequencing of the microcode to the next instruction or returning to the fetch cycle. A microcode trap capability is available that uses a three-deep push-pop stack and can interrupt normal microcode sequence on any one of 16 potential events. Finally, the control unit can be used for subroutine linkage via the same three-deep stack that is used by the microcode trapping capability. The primary purpose of the control logic is to obtain the control word to be executed in the next read-only memory cycle, and have it read into the register control memory (RCM) at the end of the execution of the current cycle. The signal TRCML is used to change the state of the control memory. The microcode control of the control unit is primarily through fields 2, 11 and 12.

Figure 2-1
Control Logic



Glossary:	BCS	Stack source Bus
	BCY	Control Memory Address Bus
	BD	D Bus
	RCM	Control Memory (current instruction)
	RCS	Three deep push/pop stack
	RCY	Control Memory address register
	Decode Net	User instruction Microcode entry point mapping logic
	Trap address	Micro-trap entry point
	TRCML	"Load Control Memory" signal
	RCC	Control Memory Store

2.1.2 Controlled Logic

The controlled logic forms the main body of busses, registers and logic operators to be used in performing the data manipulation desired. Figure 2-2 illustrates the major components of the controlled logic. The basic structure consists of two busses, bus B and bus D with registers and arithmetic and logic unit (ALU) suspended in between. All data paths are 16 bits wide with parity per byte for a total of 18 bits, unless otherwise indicated on Figure 2-2. The microcoder has available in a given micro-instruction three registers for holding in process data: RY, RM and the selected register file register. The register file can be read and be written into the same micro-step. However, only one register within the file can be operated on in the same micro-step. Shifting is accomplished by selecting the appropriate path from the ALU to the D bus. The arithmetic and logic unit is the standard 72-181 TTL device. This means it can add and subtract the full 16-bit numbers in parallel, it can increment the A input or the B input, and it can perform 16 logical functions on the A and B inputs. The microcode fields that control this logic are fields 1, 2, 4, 5, 6, 7 and 8 with a little bit of help from the others.

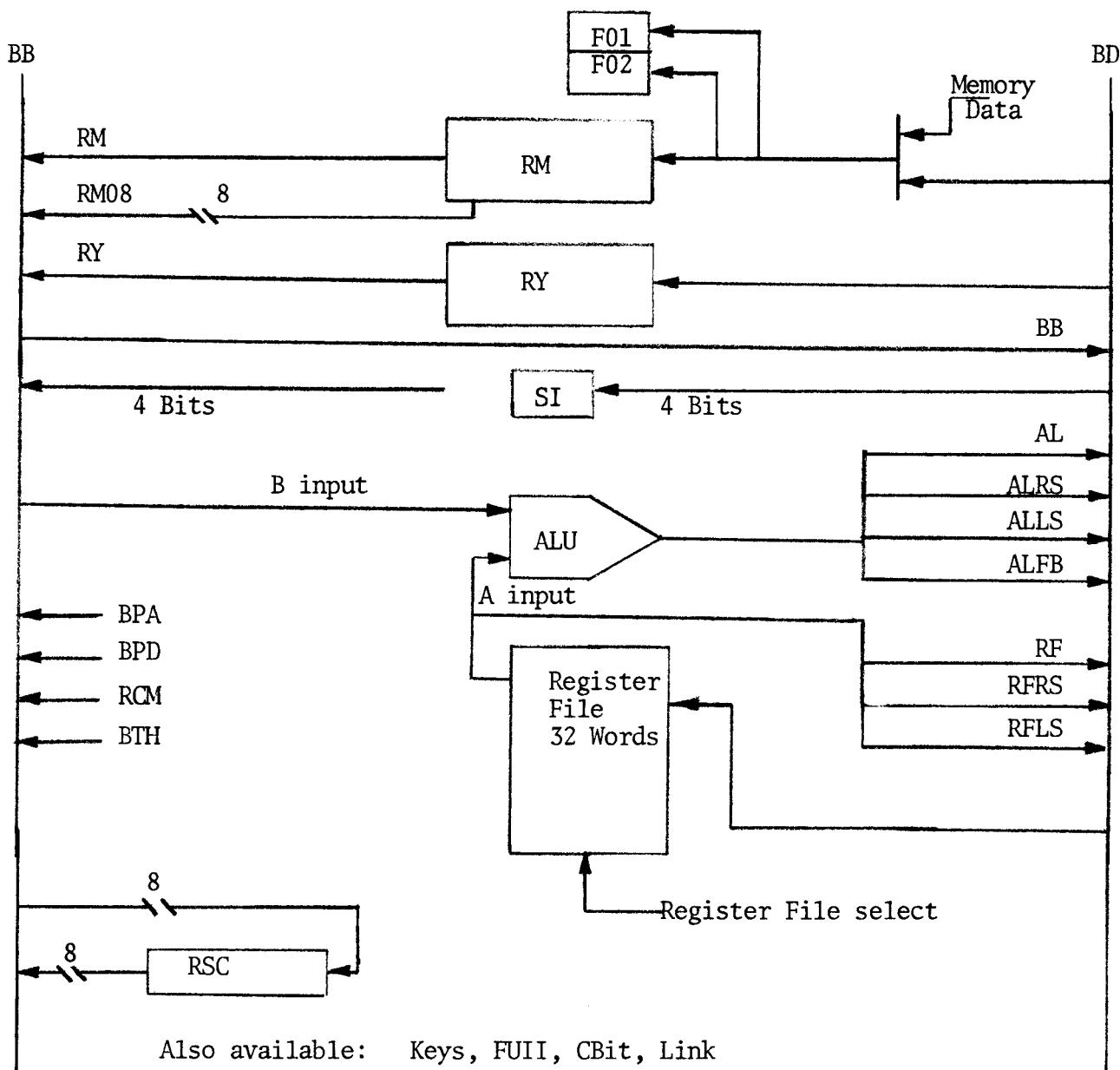
2.1.3 Major Subsystems

The memory subsystem adds two busses to the control logic in Figure 2-2. These are the BMD or Memory Data Bus and BMA or Memory Address Bus. Figure 2-3 illustrates the components of the memory subsystem. Note that the paging hardware shown requires microcode support in order to implement a virtual memory system. Microcode field 9, primarily, controls the memory subsystem. The clock field (#8) controls the time when data is taken from the memories and put into RM. The basic memory control timing signals, and the complete activity of memory refresh, is controlled by hardware in the box labeled Memory Timing in Figure 2-3.

The input/output subsystem illustrated in Figure 2-4 includes the two bidirectional buses, Bus Peripheral Data (BPD), and Bus Peripheral Address (BPA) in addition to a hardware box that generates the various input/output control signals under control of microcode fields 6 and 7.

The parity subsystem is entirely implemented in hardware, except it can be enabled and disabled using RCM bit 7 and/or PARIM. This is evident from Figure 2-5. Logic consists of a number of independent parity error detection circuits with their outputs ORed together to determine if any of them has discovered a parity error.

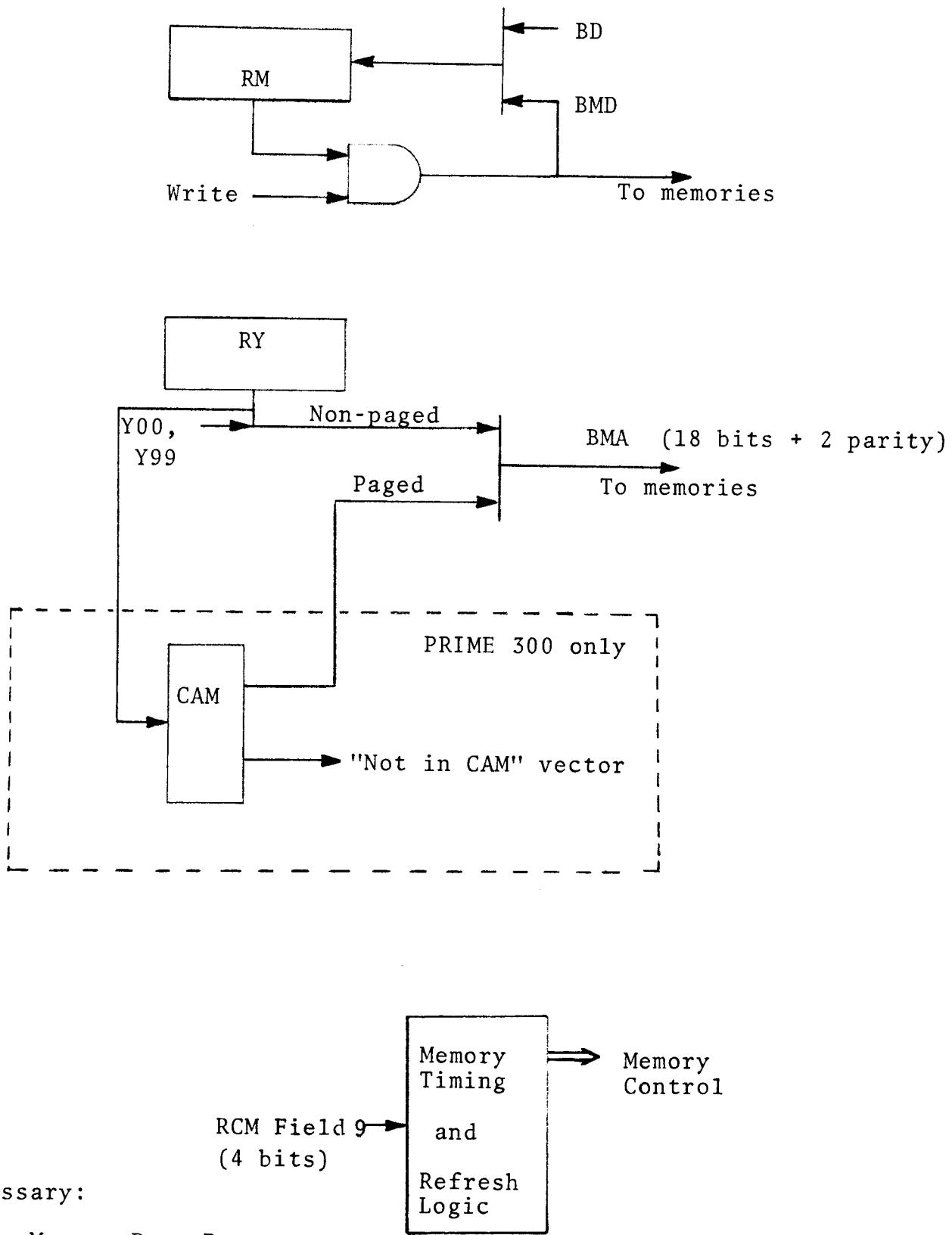
Figure 2-2
Controlled Logic



Glossary: BB B Bus

Glossary:	BB	B Bus
	BPA	Peripheral Address Bus
	BPD	Peripheral Data Bus
	XXLS	XX Left Shift
	XXRS	XX Right Shift
	ALFB	ALU byte interchange
	RSC	Shift counter
	BTH	Top hat bus (not now used)

Figure 2-3.
Memory Subsystem



Glossary:

BMD= Memory Data Bus

BMA= Memory Address Bus

CAM= Content Associative

Memory (for virtual memory)

Logical physical mapping.)

← "Missing Memory Module"

Figure 2-4
I/O Subsystem

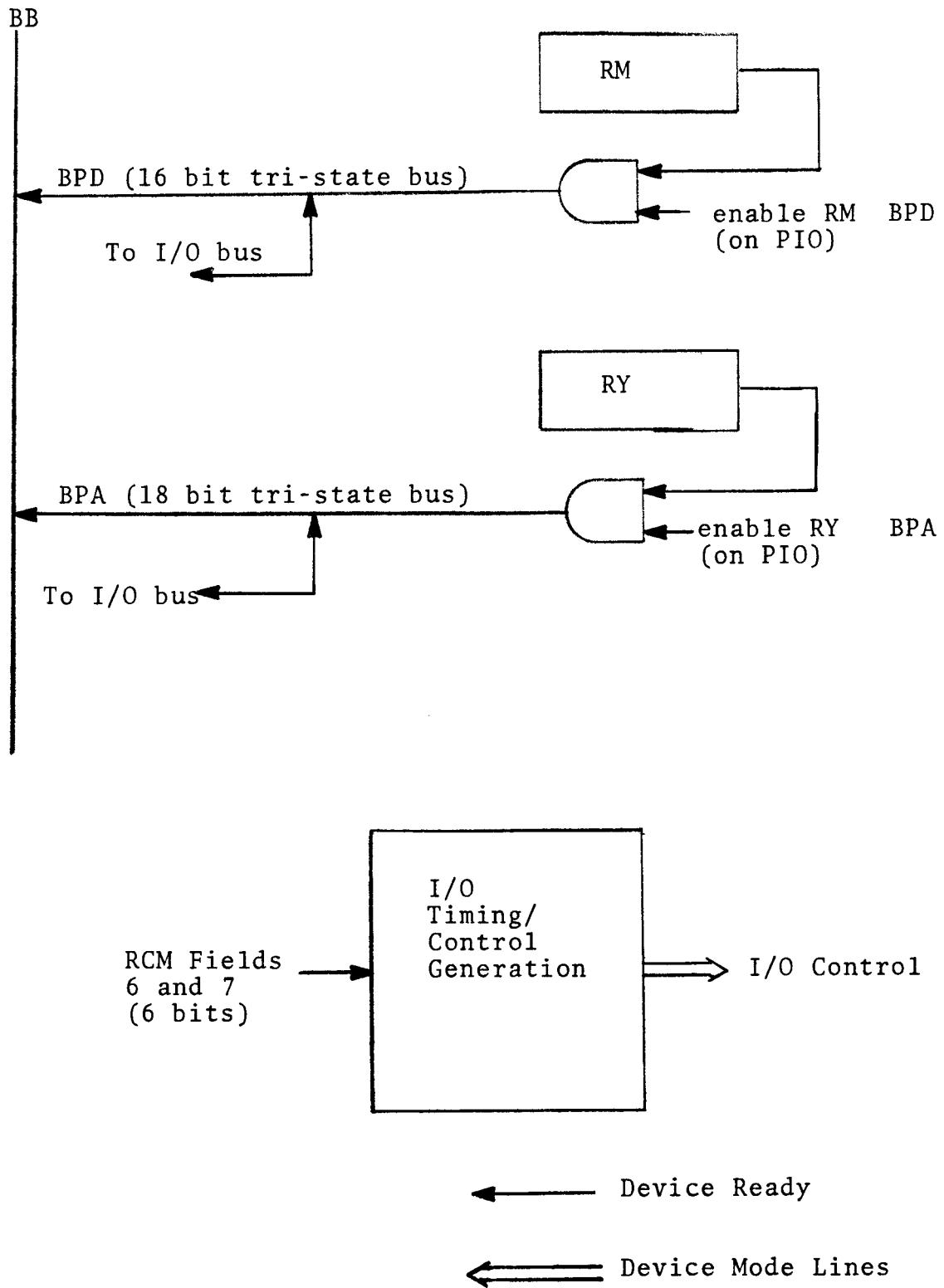


Figure 2-5
Parity Subsystem

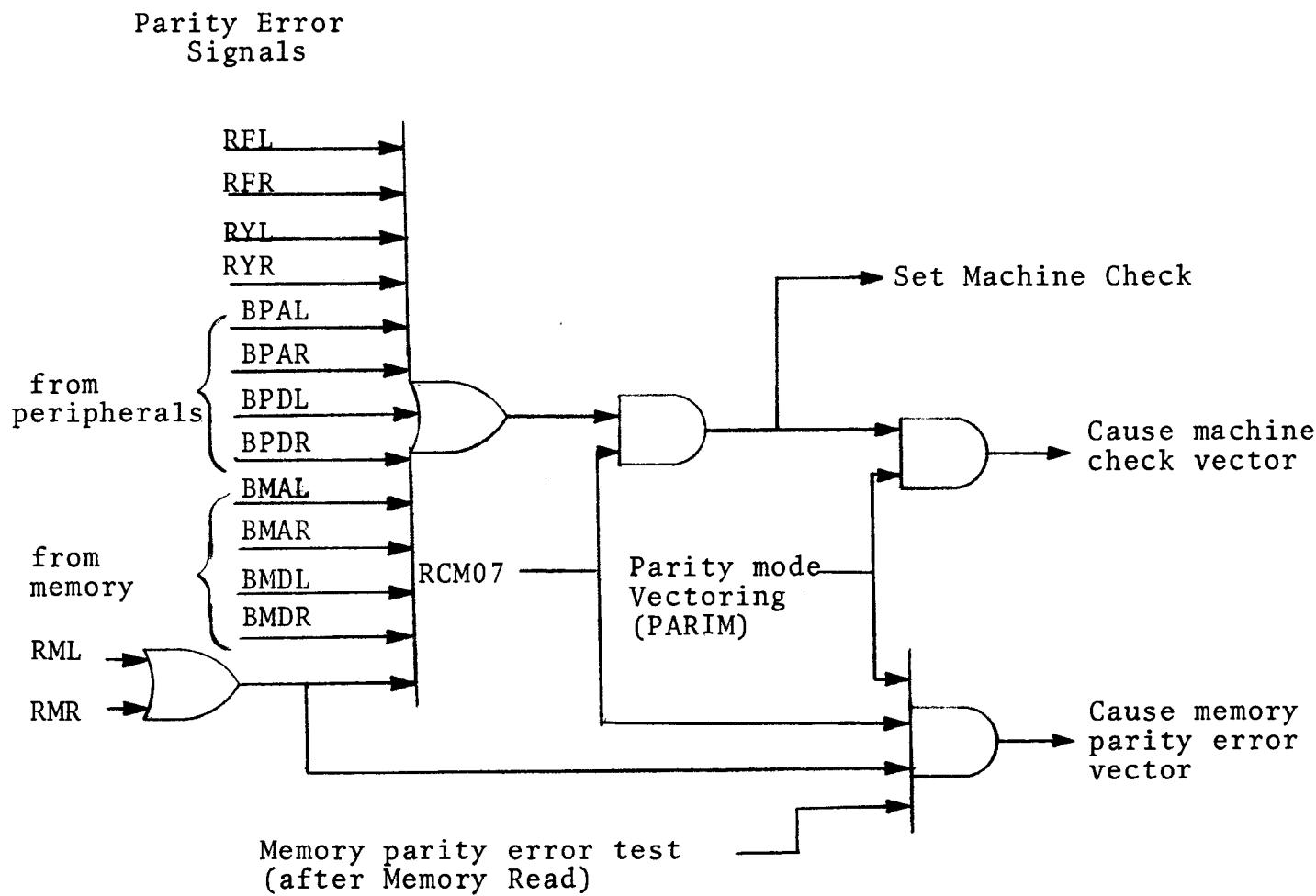
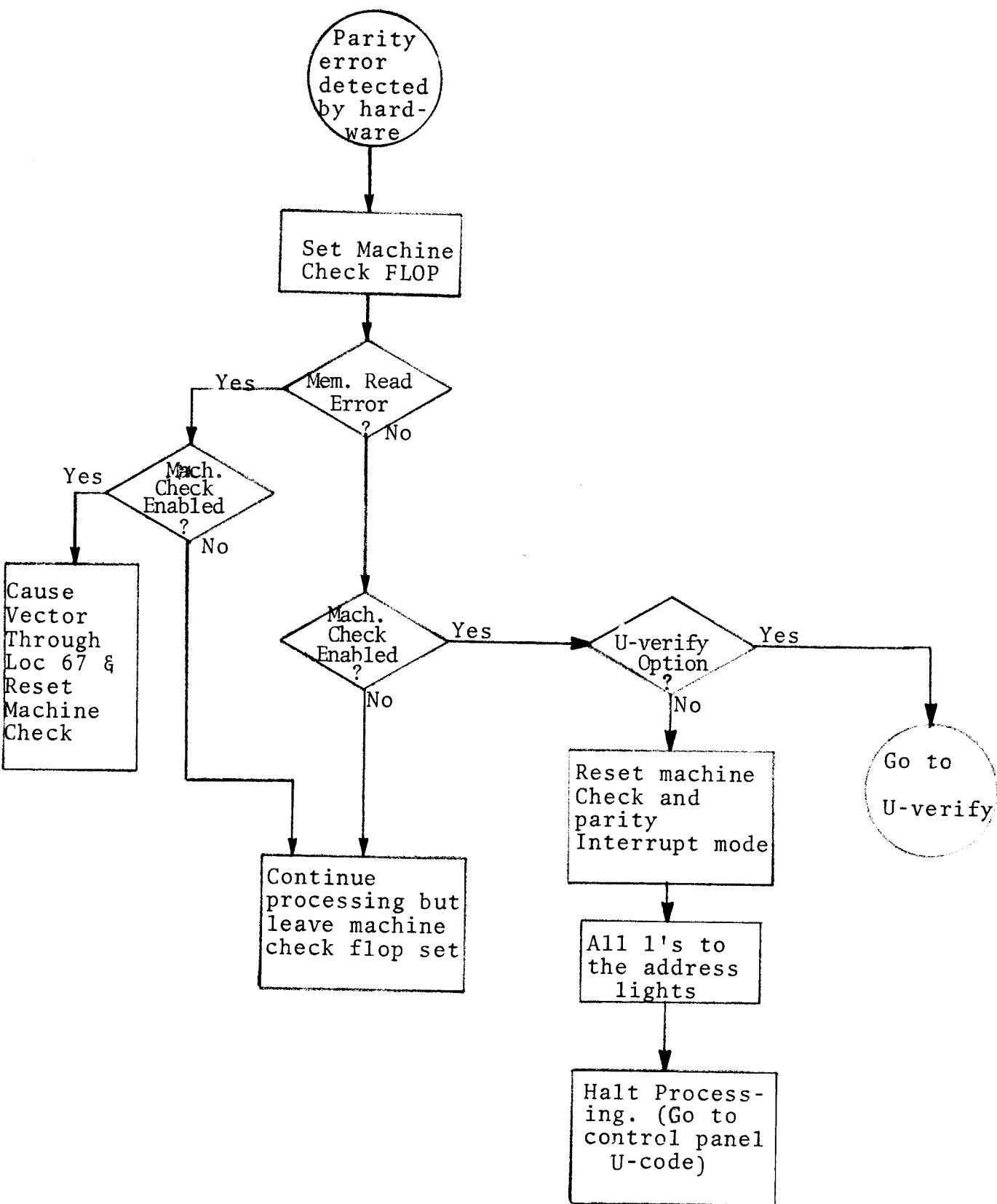


Figure 2-5.1
PARITY DETECTION LOGIC DIAGRAM



2.2 INTRODUCTION TO MICROCODE

2.2.1 Register-to-Register Transfers

The simplest microcode operation is transferring information from one register to another register. The first example is the transfer of a register in the register file to RM. In order to do this, the appropriate register must be selected; the register file must be allowed on the Bus D; and, finally, the results must be put into RM. In this example, it is assumed that RA was the register to be selected. Section 2.2.2, Example 1 shows the microcode fields that must be encoded to perform the desired operation: transfer of register A to register M. The unfilled fields have no effect on this operation. Also, in Example 1, the abbreviated form that indicates the same operation using the μ -code (microcode) assembler is shown below the listing of each field.

Figure 2-6, the short dashed lines show the path that the data takes on this transfer.

For the next example, it is desirable to take information in RM and move it back down to RA in the register file. To do this, RM is selected as the source of bus D; and, finally, the register file must be used as the destination of the information on bus D. As Section 2.2.2 Example 2 shows fields 1, 2, 6, 7 and 8 in the microcode must be used to select this particular data transfer. Again, none of the other fields are used. The short-hand or RR form of expressing this transfer is also illustrated. The RM to register file (RA) transfer is illustrated using dotted lines on Figure 2-6.

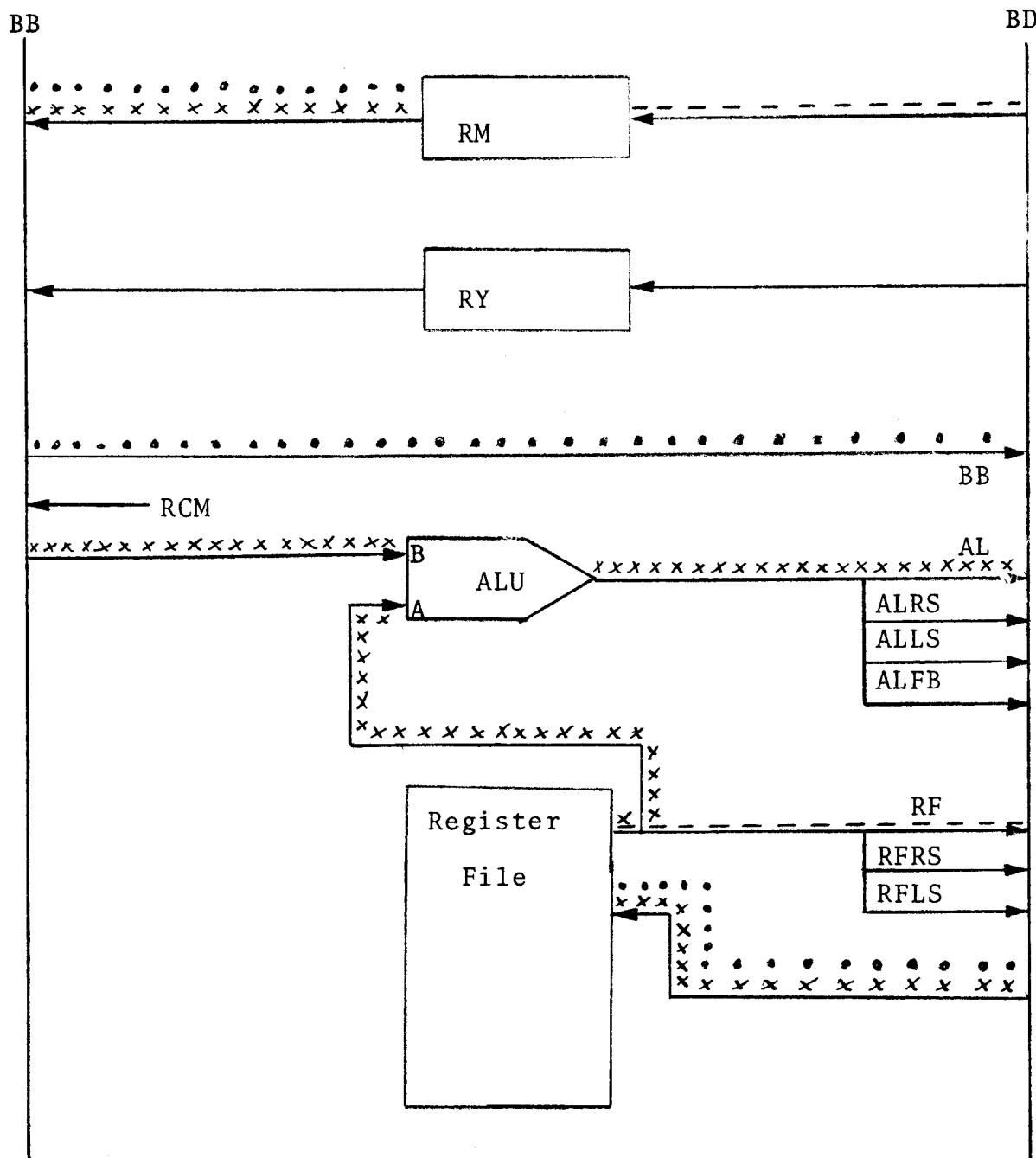
It should be clear from looking at the fields used in these two examples that microcode field 1 selects the source on the D bus, field 2 selects the source on to the B bus, fields 6 and 7 combined select a particular register in the register file, and field 8 determines the destination register from the D bus.

With this much information, it is possible to construct the entire set of register-to-register operations. Section 2.2.2 Example 3 shows the microcode sequence that interchanges the information in register A and register B. These two registers are assumed to be two of the 32 registers in the register file. The execution of code sequence accomplishes the functionality of the Prime instruction IAB.

For a final example of register-to-register transfer, consider putting the value 1 into register A. Numbers, masks and general data that are known by the micro program can be emitted

Figure 2-6

Controlled Logic
Data Paths



on to bus B by using the RCM source on bus B. If the microcode field corresponding to the bus B data is field 12, field 11 must be set to a zero to signal the control unit to interpret field 12 as data. Section 2.2.2 Example 4 shows that microcode fields 1, 2, 6, 7, 8, 11 and 12 are used in order to transmit a 1 from the control memory to register A. This operation is used to execute the Prime instruction LT or Logicize True.

2.2.2 Examples for Section 2.2.1

Example 1:

Field

1	2	3	4	5	6	7	8	9	10	11	12
RF	--	--	--	--	M	RA	RM	--	--	--	--

(Short Form)

RR RA \Rightarrow RM

Example 2:

BB	RM	--	--	--	M	RA	RF	--	--	--	--
----	----	----	----	----	---	----	----	----	----	----	----

(Short Form)

RR RM \Rightarrow RA

Example 3 :

1	2	3	4	5	6	7	8	9	10	11	12
RF	--	--	--	--	M	RB	RM	--	--	--	--
RF	--	--	--	--	M	RA	RY	--	--	--	--
BB	RY	--	--	--	M	RB	RF	--	--	--	--
BB	RM	--	--	--	M	RA	RF	--	--	--	--

(Short Form)

$$\begin{array}{ll} RR & RB \Rightarrow RM \\ RR & RA \Rightarrow RY \\ RR & RY \Rightarrow RB \\ RR & RM \Rightarrow RA \end{array}$$

Example 4 :

1	2	3	4	5	6	7	8	9	10	11	12
BB	RCM	--	--	--	M	RA	RF	--	--	DATA	1

(Short Form)

$$RR \quad RCM = 1 \Rightarrow RA$$

2.2.3 Transfers Using the Arithmetic and Logic Unit (ALU)

Suppose that it is desired to add two numbers together, the first of these numbers is in RM and the second of these numbers is in RA. The results are to be put in RA. The first step is to get the correct data at the inputs of the ALU. This is done by selecting RM as the source for the B bus, and RA as the register file register. Next, the ALU must be conditioned to add, which is done by selecting the add function in the combined fields 4 and 5. Finally, the results have to be put back into the register file (RA) by selecting AL as the source of bus D and the register file as the destination of the operation. Section 2.2.4, Example 1, shows the microcode fields that are used to perform this activity. At this point, half of the capability of one microcode instruction is being used. Note the different format available for shorthand indication to the microcode assembler of this addition operation. In general, operations that use the arithmetic and logic unit (ALU) can be requested using the ALU macro of the microcode assembler. The line of X's on Figure 2-6 shows the active data paths for Example 1.

As is obvious from the Section 2.2.4 Example 1, fields 4 and 5 combine to control the Arithmetic and Logic Unit operation that is performed on the incoming data. The complete set of ALU operations are found in Appendix B.

Associated with the Arithmetic and Logic Unit are three flip-flops. The first to be discussed is the carry bit, also called the C bit, or FCBIT. This is a one bit storage register that can be loaded using field 9 of the microcode. The C bit can be loaded with any one of six different signals upon request: arithmetic overflow (AOVFL), shift overflow (SOVFL), but D bit 1 (BD01), RF01, 16-bit ALU carry (COUT), and the link source, (or divide overflow (DIVER)). The other two flip-flops are called the condition code and always contain the high order bit of the results of the ALU in one flip-flop and an indication if the results were equal to zero in the other. Whenever field 10 of the microcode says SET CC, the condition code can then be used in conjunction with the conditional branching logic to make a decision about the relative size of the number; equal to 0, not equal to 0, greater than 0, less than 0, etc.

The division of functions between fields 4 and 5 of the microcode in controlling the arithmetic and logic Unit may now be inspected more closely. Field 5 is used to specify use of arithmetic or logic mode for the adder. If arithmetic mode is used, field 5 is used for carry-in: 0, 1, or the C bit must be considered. Field 4 directly encodes one of 16 arithmetic or logical functions available in the ALU integrated circuit.

Section 2.2.4, Example 2 is an attempt to put together what has been learned about ALU and RR type microcode operation. This double precision add, assumes that registers A and B are to be treated as a standard double-word number, and the new second double-word number to be added to this register is now stored with the high order half in register 13 and the low order half in the M register (RM). As example 2 shows, it takes four microcode steps to complete a double precision add. In the second step, the high order bit of RB must be masked out. This bit would have been set if there had been overflow on the first add step. In the fourth step, it is possible to use the C bit that was established in the first step; and at the end of the operation, reload the C bit with the new overflow information.

It is also possible to use the ALU to perform single input operations and to generate constants of either minus 1 or 0.

2.2.4 Examples for Section 2.2.3

Example 1:

Field

1	2	3	4	5	6	7	8	9	10	11	12
AL	RM	--	ADD	0	M	RA	RF	--	--	--	--

(Short Form)

ALU RA PLUS RM => RA

Example 2:

1	2	3	4	5	6	7	8	9	10	11	12
AL	RM	--	ADD	0	M	RB	RF	AOVFL	--	--	--
AL	RCM	--	AND	L	M	RB	RF	--	--	DATA	\$7FFF
RF	--	--	--	--	M	13	RM	--	--	--	--
AL	RM	--	ADD	CBIT	M	RA	RF	AOVFL	--	--	--

(Short Form)

ALU	RB	PLUS	RM	\Rightarrow	RB	C=AOVFL
ALU	RB	AND	RCM	=	\$7FFF	\Rightarrow RB
RR	13	\Rightarrow	RM			
ALU	RA	PLUS	RM + CBIT	\Rightarrow	RA	
C = AOVFL						

2.2.5 Shifting

Shifting is accomplished in microcode using the bus D source. RFRS or RFLS are the two inputs most frequently used for shifting. RFRS, for instance, means that each output of the register file is shifted right one place before it is brought to the output of the D bus. The difficulty of shifts is that the information to be shifted in one end can be different coming out, depending on the functionality that is wanted with the shift. In addition, there exists a one bit link that can be loaded with a variety of signals for use in multiple precision shifting operations.

The loading of the link and the various end conditions that are to be used are combined and are called the shift and end conditions. Microcode fields 2, 4 and, to some extent 9, are used to determine the appropriate shift/end conditions. Microcode fields 2 and 4 are available because, in a typical shift, bus B and the ALU are not used.

There is no logical reason for the choice of the bit patterns in fields 2 and 4 and for the end conditions that are generated. As a result, shift and end conditions must be chosen from a table (Appendix A Field 1). There is no choice but to look up the appropriate bits to put into fields 2 and 4 in order to select the particular shift and end conditions for the direction that one wishes to shift. In Example 1, Section 2.2.6, the objective is to do a right rotate of one place on RA and put the results back into RA. From the shift and end condition for bus D select, it is determined that a rotate end condition requires the selection of the 2, in field 2, and a 0 in field 4. Fields 1, 6, 7 and 8 are filled in as required to get the correct bus activity. For shift operations, there is no equivalent to the ALU and RR short cut macros, and the entire microcode word must be written out. These are called CPU macros. Fields not used in the CPU macro must have the default microcode selection put in their place. Fields 3 and 10 are the only ones that have default values other than 0. Default for field 3 is a 2 and the default for field 10 is a 4. Section 2.2.6, Example 2, illustrates a double word long logical left shift (LLL) of one place. In this case, it takes two instructions to accomplish the shift because only 16 bits can be shifted at one time. However, it is important that the bit that is shifted out of the low order half (in this case, RB) be saved for shifting into the high order half on the second half of the shift. To make this easy to accomplish, there is a single bit register called the Link that is loaded from a source selected by the same shift and end condition fields that have already been used (fields 2 and 4). However, the Link is loaded only if field 9 is being used to select one of the sources for the carry bit or if the selection is LINK. (Numerically, codes 1 through 7 enable the Link to be loaded.) In the example, the carry bit is loaded with the high order bit of RA that would otherwise be lost in a single left shift. The proper end condition for the RB shift should put a 0 into bit 16, shift bit 2 into bit 1, and load the Link with bit 1. From the table of shift and end conditions (Appendix A Field 1) the first shift and end condition shown (encoding a 7 in both field 2 and field 4) provides the proper results. For the high order shift, the Link is loaded into bit 16, and RF02 is put into RF01. A shift and end condition that accomplishes this is a 3 and a 7 in fields 2 and 4, respectively. Note that a 3 and 6, or a 3 and 9 shift combination would have worked as well, because it does not matter what value goes into the Link bit.

To count the number of shifts made, a general purpose 8-bit scratch shift counter register (RSC), was created outside of the register file. This counter can be loaded from bus B and can be read in as the low order half of bus B. Field 10 of the microcode (the Independent Action Code field (IAC)) is used to control the loading and counting of the shift counter.

There is an IAC called load shift count (LOADRSC) and another for incrementing the shift count (INCRSC). The shift counter incrementation takes place at the end of the ROM cycle.

Thus, if incrementation and testing are done in the same ROM cycle, the test reflects the count before incrementation. In Section 2.2.11, Example 1 shows how the shift counter can be used in conjunction with counting the number of times to loop on a shift.

2.2.6 Examples for Section 2.2.5

Example 1: Right Rotate

1	2	3	4	5	6	7	8	9	10	11	12
RFRS	2	--	0	--	M	RA	RF	--	--	--	--

(Short Form)

CPU	RFRS	2	2	0	0	M	RA ;
RF	NOP	NOP					

Example 2: Long Left Shift

1	2	3	4	5	6	7	8	9	10	11	12
RFLS	7	--	7	--	M	RB	RF	LINK	--	--	--
RFLS	3	--	7	--	M	RA	RF	RF01	--	--	--

(Short Form)

CPU	RFLS	7	2	7	0	M	RB ;
RF	LINK						
CPU	RFLS	3	2	7	0	M	RA ;
RF	RF01						

2.2.7 Branching and Subroutining

One of the primary advantages of the Prime micro-processor design is the capability to test the results of a previous operation and conditionally jump on those results while at the same time performing a new and different operation using the controlled logic.

There are a total of 64 selectable jump conditions. Of this set, about 50 are implemented. They are listed in the microcode field description under Appendix A, Field 11. Several have already been discussed; they include the two condition codes, the carry bit, and the shift counter.

In Section 2.2.8, Example 1, RA is loaded with a 0 if RA<RM, a "1" if RA = RM, and a "2" if RA>RM, through the use of conditional branches. It is necessary to test for arithmetic overflow on the original subtract, and no destination clocking is selected. The symbol used in the destination clocking field (field 8) for this is clock (CLC).

The calling of subroutines in the microcode is accomplished by using the three-deep push down stack. Two instructions are required to enter a microcode subroutine, and one to return. The two entry instructions are: first, to load the microcode stack; and second, to branch to the subroutine. The return is made using the special operator in field 11. When this special operator is used, indicated by an S, all of the conditional branches are still available, and with the branch condition false, the next sequential instruction is executed. However, if the branch condition is true, one of a number of special actions is taken. Example 2 of Section 2.2.8 shows the standard subroutine linking using the microcode stack. Another IAC is used to force the loading of the microcode stack.

Two other capabilities that exist, using the special operator in field 11, are the 16-way branch and the N-way branch. The 16-way branch is similar to a regular jump except that the low order four bits of the jump address are taken directly from bus D. This means that any of 16 different locations is entered starting from the address specified taken modulo 16. As an example: if the location to be branched to is specified as T3 that is assigned to location hexadecimal 112, then; for hexadecimal number 0 through F on the low order four bits of the bus D, the next microcode instruction to be executed is taken from location 110 through 11F hexadecimal. Section 2.2.8, Example 3, shows an example of the use of a 16-way branch.

The multi-way branch permits any form of decode to be done across an arbitrarily large microcode address space. In this case, the entire D-bus serves as the address for the next microcode instruction to be executed. Depending on the value of bus D, any one of the 4K addressable microcode words can be accessed. It is expected that this capability be used, in general, by building a microcode decode word. This can be done by masking out the low order four or five or six bits and then ORing in the low order decode bits. Section 2.2.8, Example 4, shows how a 64-way branch on the low order bits of RA can be implemented, giving a start of execution after the branch beginning at T4.

2.2.8 Examples for 2.2.7

Example 1:

*Compare RM vs RA If RA > RM, 2 => RA

 If RA = RM, 1 => RA

 If RA < RM, 0 => RA

1	2	3	4	5	6	7	8	9	10	11	12
--	RM	--	SUB	1	M	RA	CLC	AOVFL	SETCC	--	--
--	--	--	--	--	--	--	CLC	--	--	JUMP	FCBIT T1
AL	--	--	ZERO	L	M	RA	RF	--	--	JUMP	LT EXIT
AL	--	--	INC	1	M	RA	RF	--	--	JUMP	EQ EXIT
AL	--	--	INC	1	M	RA	RF	--	--	JUMP	TRUE EXIT
AL	--	--	INC	0	M	RA	CLC	--	SETCC	JUMP	TRUE T2

(Short Form)

	ALU	RA	MINUS	RM	=> NULL	C=	AOVFL ;
		SETCC					
	RR	NOP	=> NOP	NOP	JUMP ON FCBIT TO T1		
T2	ALU	CON	0 => RA	NOP	JUMP ON LT TO EXIT		
	ALU	INC	RA => RA	NOP	JUMP ON EQ TO EXIT		
	ALU	INC	RA => RA	NOP	GO TO EXIT		
T1	ALU	INC	RA + 0 => NULL	SETCC	GO TO T2		

Note: Step T1 is necessary because overflow occurred on the first step. The only way overflow can occur on a subtract is if the signs are unlike. Therefore, the sign of RA alone is sufficient to determine the results of the comparison.

Example 2: Subroutine two's compliments RA and returns

1	2	3	4	5	6	7	8	9	10	11	12
BB	RCM	0	--	--	--	--	CLC	--	PUSHBD	Data	RTNA
--	--	--	--	--	--	--	CLC	--	--	Jump	TO TCA

RTNA is the return address
continue code

TCA											
AL	--	--	NOT	L	M	RA	RF	--	--	--	--
AL	--	--	INC	1	M	RA	RF	--	--	S	TRUE POP

(Short Version)

RR	RCM	=	RTNA => NULL	PUSHBD
RR	NOP	=>	NOP	NOP GO TO TCA

RTNA (Return Address)

TCA	ALU	NOT	RA	=> RA
	ALU	INC	RA	=> RA
			NOP	S ON TRUE, POP

2.2.8 Examples for 2.2.7 (Cont)

Example 3:

1	2	3	4	5	6	7	8	9	10	11	12
RF	--	0	--	--	M	RA	--	--	--	S TRUE	16WAYS T3

Example 4: 64 Way branch starting at T4

AL	RCM	--	AND	L	M	RA	RM	--	--	DATA	\$3F
BB	RM	--	--	--	M	13	RF	--	--	--	--
AL	RCM	--	ADD	0	M	13	RF	--	--	DATA	T4
RF	--	0	--	--	M	13	--	--	--	S	TRUE, BD

(short Version)

ALU	RA	AND	RCM	= \$3F	\Rightarrow RM
RR	RM	\Rightarrow	13		
ALU	13	PLUS	RCM	= T4	\Rightarrow 13
RR	13	\Rightarrow	NOP	S	TRUE, BD

2.2.9 Traps

Field 3 controls the enabling of the trap logic in the Prime microcode. Of the 16 total possible microcode traps available, 15 are placed in one class and the other trap (DMX) is placed in another class. Each of the two bits in microcode field 3 controls the trap associated with it. If the bit is set, the traps are enabled for that ROM cycle; and if the bit is reset, the traps are disabled. The mnemonics for controlling these are shown in Appendix A, Field 3.

The Appendix D describes each of the traps and, in general, the interrupts they generate. However, there are a few rules that the microcoder must keep in mind with regard to the trap.

Rule #1: in general, all traps but DMX are always enabled. This is automatically selected by the RR and ALU macros unless specifically requested otherwise.

Rule #2: DMX traps must be permitted no less frequently than once every 1.5 microseconds or system DMX latency is compromised.

Rule #3: traps must be disabled if bad parity can be generated as a result of a particular operation, and that parity must be corrected by running the offending data through the adder in any of the adder's modes before traps can be re-enabled. Bad parity can be caused by the following:

1. Willful generation of bad parity using the RCM EMIT pseudo-op instead of the DATA pseudo-op in the CPU macro.
2. Inputting data from device address 20.
3. Inputting serial interface.
4. Reading from a non-existent memory location, or a location already containing bad parity.

Rule #4: When the microcode stack is explicitly pushed in a microcode instruction, the trap logic must be disabled, because the control logic can only push one item into the stack in one micro-step. The trap logic must save the microcode return point in the stack so the PUSHBD independent action code and the DECODE step must both have traps disabled. Similarly, if a multi-way or 16-way branch is executed, no returnable trap can be permitted (DMX, Page, or Address).

Trap codes:

- 0 None
- 1 DMX (only)
- 2 NX (all but DMX)
- 3 ALL

for RR and ALU macros, use TR= if traps different from the explicit traps are to be specified.

Rule #5: if a 160 nanosecond clock is selected, traps must be disabled. The reason for this is: the control unit cannot successfully determine if there is going to be a trap in 160 nanoseconds. Section 3, microcode timing in greater detail.

The Restricted Execution trap feature is available using field 10 codes RXM and RXMF. Use of these IAC's forces a trap if the μ -code step is executed while the machine is running in Restricted Execution or virtual mode.

Restricted Execution traps occur after the execution of the instruction following the one that had a field 10 of RXM or RXMF. If traps are disabled in the next instruction executed, the RXM trap is missed. Careful attention must be paid to all possible sequences (Address traps, DMX breaks, etc.) to ensure that the RXM trap unequivocally occurs.

Section 2.2.10 Multiply and Divide

Special hardware in the Prime Computer enables the more rapid execution of multiply and divide than would otherwise be possible. The special multiply logic permits the automatic selection within a microcode step of either the arithmetic unit output or the register file output, depending on whether the link contains a 1 or a 0 at the beginning of the cycle. This special hardware permits two microcode steps executed 15 times to perform a full 16-bit multiply leaving a 32-bit result. The algorithm employed is always shift, adding only if the bit of the multiplicand is a 1. Section 2.2.11, Example 2, shows the set up and operation of the standard multiply loop.

A new feature of the microcode must be introduced in order to be able to activate the special multiply logic. This feature is called the emit-action code (EAC). It is analogous to field 10, except the emit field must be dedicated in order to use the emit-action code. If field 11 is coded as EAC or a 2, then field 12 can contain an emit-action.

Division is not so straightforward. However, there is also some special hardware that permits a non-performing style of divide to be implemented more efficiently. This hardware is similar to the special hardware used by the multiply. It is turned on from the microcode using an emit action code, and it also causes an automatic selection of the arithmetic unit or the register file on the D bus. The difference, however, is that the divide logic monitors the high order output bit of the ALU and compares it to the previous high order ALU bit stored as part of the condition code. If the two bits are the same, then the ALU output is selected. If the bits are different, the register file output is selected. The correct shift and end conditions are selected if either an add or a subtract operation is being requested of the ALU.

Divide is more complicated than multiply because division by unlike signed numbers does not map as nicely as multiplication by signed numbers. A complete divide, including a properly signed remainder, involves a fair amount of clean up or end condition fix up at the completion of the basic divide loop. For details of what is required, see Appendix C "Microcode Listings" for the divide. However, it is possible to demonstrate the basic inner divide loop. Section 2.2.11, Example 2, illustrates this loop for divide.

A non-performing divide was selected because the decision to perform the arithmetic operation or the shift on a bit-by-bit basis is faster than a standard restoring divide and requires much less microcode than a standard non-restoring divide. Non-performing divide means that the sign bit of the attempted arithmetic operation is monitored. If the sign of the remainder being accumulated would be changed by allowing the operation to be completed, the operation is not performed. Instead, the partial remainder is shifted one place to the left. For a more thorough explanation of various ways to divide using two's complement arithmetic, refer to Flores¹.

The divide logic information, whether to perform the subtract, is also significant for more than switching the source of the D-bus. If a quotient bit of one is obtained and the subtract is performed on the first iteration (assuming like signed numbers), then the division has had an overflow. Because the information on whether the first arithmetic operation was performed indicates divide overflow, it is available as one of the conditions selected to be loaded into the C bit. Finally, the perform-or-not information is, in effect, the quotient bit for that cycle of the divide algorithm. This is available to be loaded into the link if the standard divide microcode step is used. The link can be emptied into a separate register (or back into the low order register as in the standard divide).

I. Flores, Ivan: Logic of Digital Arithmetic
Prentiss Hall, Inc., 1963

2.2.11 Examples

Example 1 MPY RB * RA:

RR RA \Rightarrow RM

* Load shift counter = - 15 and zero out RA

```
CPU AL RCM NX ZERO L M RA;  
RF NOP LOADRSC;  
DATA - 15
```

* Now Load link with LSB of RB

```
CPU RFRS 5 NX 6 0 M RB;  
RF LINK
```

* Main MPY Loop - first step uses special MPY aid

* Switching between ALRS and RFRS depending on the
* state of the link

```
CPU ALRS RM NX ADD 0 M RA;  
RF LINK NOP  
EAC MPYLOGIC
```

```
CPU RFRS 0 ALL 6 0 M RB;  
RF LINK INCRSC;  
JUMP ON RSCNEM1 to * -1
```

* Multiply Loop is finished except for final Subtract
* (with no shift). The same special logic can be used
* again.

```
ALU RA Minus RM  $\Rightarrow$  RA c = AOVFL;  
NOP EAC MPYLOGIC
```

Example 2:

Divide RA | RB (positive)/RM (positive)

Quotient => RB
Remainder => RA

* Set condition code = positive, Divide overflow
* is detected if first subtract yields a positive
* result because 16 magnitude bits (or more) are required
* to hold correct results and we only have 15.

CPU - RCM NX ZERO L 0 0;
CLC NOP SETCC;
DATA -15

* Test for error (overflow)

CPU ALLS RM NX SUB 1 M RA;
CLC DIVER NOP;
EAC DIVLOGIC

* Pre-load link - exit on error

CPU RFLS 3 ALL 3 0 M RB;
RF LINK NOP;
JUMP ON FCBIT TO DIVER

* Main loop - 15 iterations, 1 quotient bit/cycle
* first must = 0.

CPU ALLS RM NX SUB 1 M RA:
RF LINK NOP;
EAC DIVLOGIC

CPU RFLL 3 ALL 3 0 M RB;
RF LINK INCRSC;
JUMP ON RSCNEM1 to * - 1

* final iteration must not shift remainder. First ins.
* sets up link.

CPU ALLS RM NX SUB 1 M RA;
200 LINK NOP;
EAC DIVLOGIC

CPU AL RM NX SUB 1 M RA;
RF NOP NOP;
EAC DIVLOGIC

CPU RFLL 3 ALL 6 0 M RB;
RF

SECTION 3

TIMING

3.1 INTRODUCTION TO TIMING

One of the relatively unique features on the Prime microcode is the ability for every microcode step to specify the time needed for that step to execute. The clock control microcode field (field 5) permits any 16 combinations of destination registers and time. Timing is specific to a particular microcode processor and also specific to the microcode address space from which code is being executed. As a result, the timing for a particular instruction is processor dependent. Because the previous sections have been general, no clock or timing information has been included. On both a Prime 200 and Prime 300 Central Processor, the various clocks available range from 160 ns up to 280 ns. If the microcoder uses the CPU Macro, a decision must be made as to which of the clocks is appropriate to the activities commanded by the other fields in that microcode instruction. In addition, if an operation must take longer than 280 ns, it is possible to have two identical microcode instructions differing only because the first has a 200 or 280 ns microcode clock without changing any of the registers. This can permit clocks of 440 or 480 or 400 ns to be a construction of two successive microcode steps.

The clocks also control the destination registers so that a typical clock would be RM200 to specify that register M should be updated 200 ns after the start of the cycle. For the full list of clocks for a Prime 200 and a Prime 300, see Appendix A, Field 8. The Prime 100 clocks control the same destination registers as those for the Prime 200 but the times for all clocks are 360 ns for a single step.

Another functionality within the clock field is automatic coordination with memory. It is possible to select a clock into RM on MRDY. This forces the memory data bus to be loaded into RM after the memory in access is complete. Similarly, it is possible to load RY conditional on Y busy. This delays the changing of state of RY until the memory is finished with that register. However, there are minimum times associated with these clocks. Even if the memory cycle was started several micro steps in the past, there is still a minimum time associated with the particular ROM cycle.

3.2 TIMING CONSTRAINTS

Different models of the Prime family have different basic timing constraints. The basic timing constraints for different functions are as follows:

For the control unit on a Prime 200, if traps are disabled (TR = 0 or None), and there is no conditional branch specified, the minimum time to perform an activity is 160 ns. If traps

are enabled or if a conditional branch is permitted, the minimum time lengthens to 200 ns. Finally, in the control unit, if an N-way or 16-way branch is attempted, the minimum time becomes 280 ns.

For the controlled unit, times are associated with register-to-register, ALU, multiply/divide, and shift operations; each of which could take a different length of time. For the Prime 200, those times are, respectively: 160, 280, 400 and 240 ns.

For the Prime 300, the control unit has the same restrictions as for the Prime 200. However, the controlled unit has been speeded up so that ALU operations and shift operations take 200 ns; multiply, 240; and divide, 280 ns.

RY destinations on a Prime 300 are loaded 40 ns early, permitting memory access times to be improved by 40 ns in many cases. Unfortunately, this loading also means that if RY is both the source and destination of a single micro-step, the results of the adder or BB cannot be guaranteed to be stable at the end of the micro-step. This means that the C-bit, condition code, the shift counter, or the register file could be loaded with bad information.

Examples:

GOOD			BAD		
ALU	INC	RY => RY	ALU	INC	RY => RY SETCC
ALU	RA PLUS	=5 => (RY,RF)	ALU	RA PLUS	RY => (RY,RF)
ALU	RA PLUS	RY => RY	ALU	RA PLUS	RY => RY C = AOVFL
ALU	RA PLUS	RY => RA SETCC			

For extended microcode, whether it is in WCS or fast or slow P-ROM, the control unit remains the same. However, the control unit remains the same with the fast P-ROM, and 80 ns slower in the slow P-ROM and WCS portions of the extended control store. These extensions cause some of the longer controlled clocks to become over 280 ns, the maximum specifiable in one cycle. When the control unit must go to multiple cycles, a first cycle becomes the minimum CLC and the second cycle must be a 280 ns clock. Table 3-1 summarizes these items.

The Prime 100 is very slow and the times shown may not be minimum, but they are the only times available.

Some microcode activities have special timing constraints associated with them, this includes the PUSHBD independent action code which requires a minimum 280 ns clock. JAMF and any sort of POP off the stack require the same clock as is used for the conditional branch. The decode step requires a minimum 280 ns clock, except for the Prime 100 that requires a 360 ns clock. If traps are enabled, a minimum clock of 200 ns must be chosen.

Table 3-1

Required Minimum Micro Instruction Times

WCS Micro Instruction Times

1. The following operations require 240 ns clock times.
 - A. Register to Register Operation
 - B. ALU Operations
 - C. Multiply Operations
 - D. Shift Operations
2. These operations require 280 ns clock times.
 - A. Microcode Branch Operations
 - B. JAMF Operation
 - C. Divide Operation
3. The 16-way branch and NOTRF16 branch require 480 nsec.

Processor/ Extension	<u>CONTROLLED UNIT</u>					<u>CONTROL UNIT</u>					
	RR	ALU	MPY	DIV	Shift	No Branch	*2 Branch	16-Way Branch	N-Way*2 Branch	JAMF	Not RF16 Branch
100 *1	360	360	360	720	360	360	360	360	360	360	NA
200	160	280	280	400	240	160	200	280	200	200	280
FROM	200	280	280	400	240	200	240	440	240	240	280
300	160 *3	200 *3	240	280	200 *3	160	200	280	200	200	280
FROM	240	240	240	280	240	240	280	480	280	280	480
WCS	240	240	240	280	240	240	280	480	280	280	480

*1 All single instruction clocks are 360 ns despite requests for other clocks.

*2 Some branches off-board can be faster.

*3 RY destinations are 40 ns longer.

When working with the microcode assembler, if the CPU macro is used, the clock chosen must be explicitly specified. However, if the RR or ALU macro is used, the fastest clock possible always is chosen by the particular macro. For example, for a Prime 200, the RR macro chooses a 160 ns clock and disabled traps, if there is a destination clock of 160 ns available. If, however, a conditional branch or a "go to" statement is specified, then the RR macro automatically chooses a 200 ns clock and enables traps (TR = NX). If traps are specified equal to something other than NONE or 0, then a 200 ns clock is selected and the traps are put as they are specified.

The ALU macro operates in a similar fashion. On the Prime 200, a 280 ns clock is selected and traps are set to NX. In the Prime 300, a 200 ns clock is selected for the ALU macro, unless the destination includes RY, in which case a 240 ns clock is chosen.

To aid in the selection of the correct clocks for the ALU and RR and CPU macros, microcode intended to execute in different portions of P-ROM must define the label P300 equal to a value of 0, 1, 2, 3, etc., depending on where the microcode is to be executed. For more details, refer to Section 8.1.3 on the microcode assembler and preparing microcode for assembly.

With the information discussed so far, it is now possible to precisely calculate the time it takes to execute any microcode algorithm (except for the times spent waiting for high speed memory to finish). Memory timing is covered in the next section. There are two other factors that must be considered. The first is trap extension time, and the second is memory refresh time. Again, the memory refresh is covered in the next section. However, the trap extension time is important for any algorithm that might use address or page traps or DMX operations. If the trap logic requests a break in the microcode sequence, the cycle being executed is automatically extended to 360 ns in order to allow the trap address to be propagated to the address lines and the return address to be saved on the stack. This is why it is a good microcode practice to permit DMX break on instructions that do a memory read and, therefore, already take longer than the 360 ns cycle that occurs if a DMX trap is required.

SECTION 4

OPERATING WITH MEMORY

The Prime CPU has been designed to allow easy microcode synchronization with high-speed memory. Memory cycles are requested using microcode field 9 which is also used to control the carry bit and the link bit. It is possible to request a 16-bit (word) read or a write on either of the left or the right byte or on both bytes. These memory operations can be either mapped or absolute. The memory cycle begins at the beginning of the microcode step that requested it. Time for a memory cycle is determined by the processor and memory configuration of a particular system.

Table 4-1
Memory Cycles

Mem. Op.	P100	P200	P300	
			Fast	Slow
Read acc.	680	600	440	600
cyc.	800	720	640	720
Write	920	840	800	840
Refresh	840	840	800	840
Paged Read Acc	-	-	520	680
Cyc.	-	-	720	800
Paged Write	-	-	880	920
Overlapped Write Pos?	No	No	Yes	Yes

Mapping slows down memory when paging is enabled.

With overlapped write, the memory may be started in the same cycle that RM is loaded.

Access time is defined to be the time from the start of a μ -code command of a memory read to the time the data is clocked into RM from memory.

Cycle time is the time memory takes to do a full cycle and be able to be started in another cycle.

Table 4-1 shows the timing relations for the different memories.

Before requesting a memory cycle, it is necessary to load RY with the desired memory address. Loading RY also ensures that the memory is free for use because the μ -code clock delays loading RY until the current cycle is completed.

On a memory write cycle, it is also necessary to load RM. On a Prime 200, this must be done before the memory cycle is requested. Both RM and RY must not be altered until the memory cycle is finished. This can be ensured by loading RY and by the RM280 clock for RM because all such clocks wait for the completion of the memory cycle.

For the Prime 300, a memory write cycle can be started in the same μ -code in which RM is loaded. The RM200 clock must not be used for this because it, like the RM280 clock for the P200, waits for the memory to finish the current cycle. The ability to start a memory cycle before RM is loaded saves, typically, one μ -step per memory write.

Normal memory operation of a read cycle starts a memory read and puts the information into RM during the same μ -code step. This makes that step equal in time to the memory access. RM is loaded from memory on any clock that is conditional on MRDY (memory ready). The single step read operation is the only way that guarantees that address traps the registers from 0 to '37 as memory and guarantees the paging mechanisms will work. If neither of these capabilities is required, it is possible to overlap memory and μ -code more efficiently.

This overlap can be used to start a memory read cycle and then use RM as a scratch register for 1 to 3 μ -code steps before loading RM from memory. The DMA and DMT μ -code illustrates one use of this capability. However, a 200 ns clock is the minimum that can be used to start a memory cycle, if traps are disabled; a 280 ns clock is the minimum if traps are permitted.

Read-modify-write cycles (like IRS or IMA) on a single memory location can be done, but the first memory cycle must be finished before the next can begin. This can be accomplished as follows:

1. Take RY to RM before starting the next cycle.
2. Load RM using a clock that waits for memory (RM200 for P300, RM280 for P200).

3. Wait long enough (200 ns after the access time for fast memories, 160 ns for slow).

Note, this sequence fails:

(P300)

```
CPU 00 NX 0 0 0 0 RMMRDY MREAD
CPU AL RM NX INC 1 XM DISABLE RM280 MWRITE
```

This sequence works:

```
CPU 00 NX 0 0 0 0 RMMRDY MREAD
ALU INC RM => RM
CPU 00 NX 0 0 0 0 200 MWRITE
```

Refresh of memory normally takes care of itself. However, refresh is of importance in timing analysis. In particular, after requesting a write cycle, before RM or RY can be used again, worst case timing is a full memory write cycle plus a full refresh cycle. Of course, synchronization can always be established by using a clock that waits until memory is available for RM and RY.

SECTION 5

I/O OPERATION

The Prime μ -code is the basic timing generator for the signal sequences on the I/O bus. The interrelationship between the signal generation and worst case times for the I/O bus is complex at best. This section of the Microcoders Handbook is an attempt at outlining the constraints and techniques. Detailed timing analysis is beyond the scope of this document. The only way to guarantee results with the I/O bus μ -code interface is to allow at least as much time as is allowed in the appropriate I/O algorithm.

5.1 SIGNAL GENERATION

The various I/O signals are generated from μ -code fields 6 and 7. If field 6 = 2 or 3, RY and RSC, respectively, are used as the source for the register file address. This leaves field 7 available for uses other than register file specification. The I/O signals are generated from field 7. Individual bits control each I/O signal. If more than one bit is set, both signals are produced.

Signals can be pulses or levels, and can start and end at different nominal times. Pulses begin and end within one μ -code step. Levels are started in one cycle and can continue until turned-off.

Table 5-1 summarizes the nominal times and nature for each signal.

5.2 PROGRAMMED INPUT/OUTPUT (PIO)

The sequence of signals for PIO is:

1. Load RY with the instruction.
2. Start PIO (280 ns clock minimum).
3. Wait for a valid Ready response (200 ns minimum).
4. Test Ready (280 ns minimum).

If Output transfer:

5. Enable RM to BPD (RM is assumed to be loaded).

6. Generate Strobe (maintain RM => BPD).
7. Stop Strobe (maintain RM => BPD).
8. Done (stop RM => BPD).
9. Stop PIO.

If Input transfer:

5. Read BPD
6. Generate Strobe
7. Stop Strobe
8. Stop PIO

5.3 DMX TRANSFERS

DMX sequences are more complicated. In general, the address phase is independent from the data phase. The address phase for a given DMX transfer is the time from the start of DMX Enable to the start of the next Enable.

During the address phase, the algorithm must determine the type of transfer, use the discipline associated with the algorithm to obtain the memory address, generate a Clear Priority Net (CPN) signal and also send out 'End of Range' information if it is called for by the algorithm.

The link between the address and data phase is that Strobe must begin before the address phase ends. The data phase is when the memory is read or written into and the transfer of information is made.

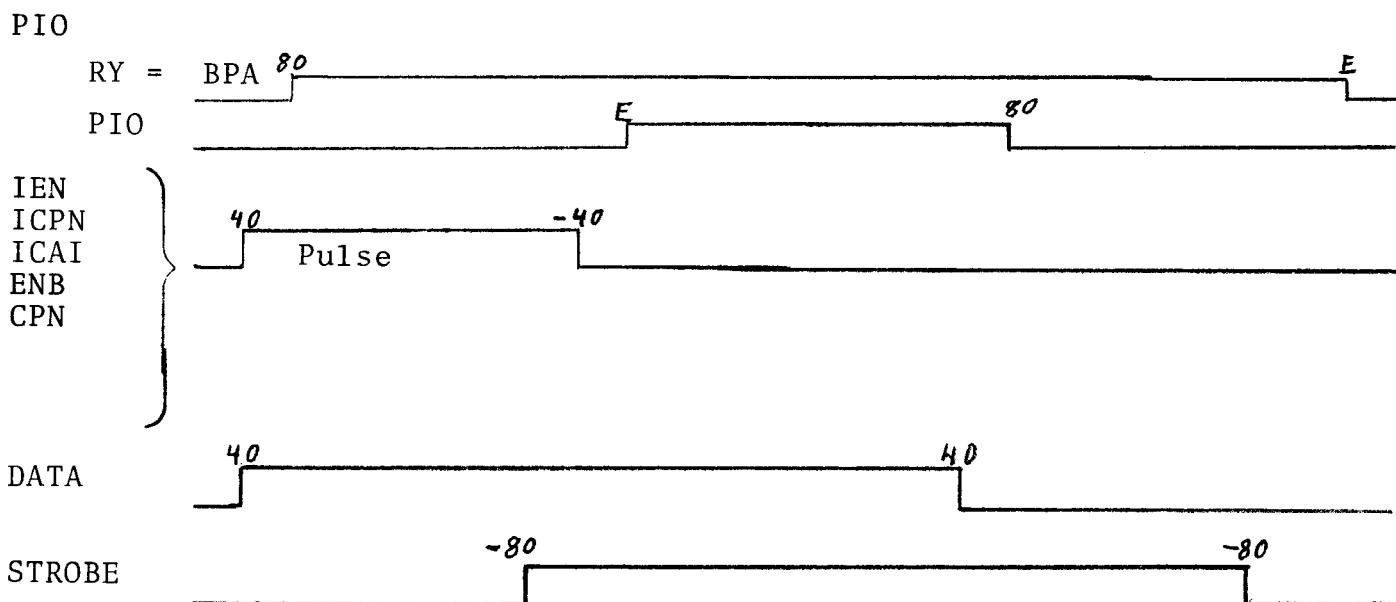
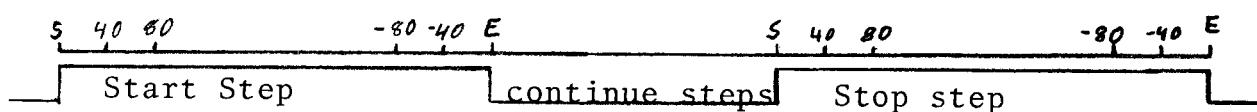
Overlapped transfers are possible in the sense that the data phase of cycle N can be running concurrently with the address phase of cycle N+1.

For a detailed description of the relationships required for I/O bus operation, see the GPIB manual.

(continued on page 5-4)

Table 5-1
Timing and Signals

<u>Signal</u>	<u>Description</u>	<u>Generate/Turn Off</u>	
PIO	Enables RY = BPA Generates PIO	Start: Continue: Stop:	RY, PIO any RY or RSC in field 6 any M or XM in field 6
IEN	Interrupt Enable	Start: Continue: Stop:	RY, IEN RY, IEN any other
ICPN	Interrupt Clear Priority Net	Pulse	RY, ICPN
ICAI	Interrupt Clear Active Interrupt	Pulse	RY, ICAI
ENB	DMX Enable	Pulse	RSC, ENB
DATA	Enables RM = BPD	Start: Continue: Stop:	RSC, DATA RSC, DATA any other
CPN	Clear DMX Priority Net	Pulse	RSC, CPN
STROBE	I/O Bus Strobe	Start: Continue: Stop:	RSC, STROBE RSC, STROBE any other



Times are in nano-seconds and are nominal only.

The relationships are:

- a. Enable must be generated in a 280 ns cycle.
- b. At least a 160 ns cycle must pass after an enable before the mode lines are tested.
- c. CPN must be generated at least 200 ns before the next enable.
- d. END of Block information can only be valid on the trail edge of a CPN in a 240 or 280 ns cycle.
- e. Strobe must be generated in the step prior to the next Enable.
- f. Data must be read in before Strobe is ended (and at least 280 ns after Strobe is started).
- g. Data on output is only valid at the trailing edge of Strobe. If read from memory, and if the contents of RM are already enabled to BPD when RM is loaded from BMD, a 240 ns cycle in which Strobe ends is the minimum that allows the data to get to the controller.

5.4 INTERRUPT TRANSFERS

External interrupts operate similar to DMX with an Interrupt Enable starting the process. At the end of the Enable signal, the highest priority active device enables its address and mode lines onto the Bus. BPCOMD2 has the meaning of Memory Increment if true, and a memory increment operation is done.

For normal vectored interrupts, the address lines are read to obtain the interrupt vector location and an ICPN is issued to clear the priority net down to the active device. The rest of the net is cleared with an ICPCAI which is generated by the instruction CAI.

For non-vectored interrupts, the address lines are ignored, and the ICPCAI is issued implicitly before the ICPN.

Memory increment uses the address lines for the location to be incremented. An End of Range signal is sent back down the bus whenever the location is incremented to zero. The signal is valid only at the trailing edge of ICPN.

Timing constraints:

- a. IENB must be 480 ns long (minimum).
- b. Address lines are valid 280 ns after enable until ICPN.
- c. Mode lines are valid for test 400 ns (minimum) after IENB.
- d. ICPN and ICAI must occur in a 200 ns or longer cycle.
If End of Range information is given a 280 ns minimum, ICPN is required.

The two signals cannot be generated in the same μ -step.

SECTION 6

INTERFACING TO STANDARD MICROCODE

There are only very minor differences between the basic microcode on the Prime 300 and Prime 200/100. These differences are in the Clock Field (field 8) and are primarily the addition of an RY240 clock and the loss of the RMRF280 clock.

Other differences have been explained in the previous sections.

Register assignments are common to both Prime 200 and Prime 300. These are:

<u>Loc.</u>	<u>Name/Use</u>	<u>Mnemonic</u>
0	X Register	RX
1	A Register	RA
2	B Register	RB
3	Stack/	RS
4	Floating PT Accumulator	FLTH
5	(double word)	FLTL
6	Visible Shift Counter	VSC
7	Program Counter	RP
10	Page Map Address Register	PMAR
11	Flex, UII	{ Floating } 11
12	Effective Address Save	{ Point } 12, EAS
13	M-scratch	{ Scratch } 13
14	RY saved	DMX scratch
15	RM saved	YSAVE
16	RSC saved	MSAVE
17	DMC scratch	RSCSAVE
20	Reserved for user (normally DMA channels)	17

37

The rest of this section describes using some of the features built into the existing Prime μ -code.

6.1 USING EXISTING ALGORITHMS

There are various Prime Instructions that require many μ -steps for completion. Examples include PIO, MPY, DVD, and all the floating point instructions.

The control unit and current algorithms are not set up to permit easy use of existing instructions as subroutines because all of them return to the fetch cycle on completion. To use these instructions as subroutines, the following procedure must be used:

1. Save (RP) somewhere (probably in memory as all the scratch registers are used by floating point).
2. Load a three-memory location with an "Enter and Execute" instruction point to the desired place to enter in μ -code.
3. Load RP with a pointer to the "Enter and Execute".
4. Load RY with the memory location of the memory argument.
5. Jump to the μ -code for the instruction.

The above process is quite painful, but step 2 can be done ahead of time and the rest can easily be a μ -code subroutine.

There are several subroutines that exist inside of the floating point package as pure subroutines. These include single and double precision load, adjust (align) and normalize routines. The linkage to the first two routines is by pushing a return address onto the three deep μ -code stack (the routines themselves use another level of the stack) and then branching to the routine.

Unfortunately, the adjust routine does not always return. If the two numbers are too far apart to be aligned, an exit directly to the normalize routine can occur.

The normalize routine itself is not really a subroutine, as it always exits to the fetch cycle.

6.2 μ -CODE FOR VIRTUAL MODE EXECUTION

To produce μ -code that works on a system to be run in full virtual mode, it is necessary to:

- a. Taking DMX latency into account.
- b. Allow the external interrupts to work.
- c. Let the mapping hardware, μ -code and software work.

DMX latency is easily provided for by enabling DMX traps at least every 1.4 micro-seconds in the code.

Making code interruptible is more difficult. It is possible to use the F1 branch condition to determine if an interrupt is pending. If the condition is true, either the control panel wants a halt or a power failure has been detected or an interrupt or memory increment is requested.

These various functions may be sorted out in one of two ways.

First, a branch to location zero or FHALT can be made. This permits the processing of the external request. However, the program counter will be used on returning, so the same procedure used for calling μ -code already written as a subroutine must be used. The second method is to perform the interrupt logic in the new μ -code. This method requires additional space but permits complete control of the machine to be maintained.

Writing μ -code that operates in a virtual memory environment is even more complicated. There are two basic ways to view the problem. In the first, the new μ -code looks like a new instruction executable by the virtual user. To do this, the μ -code sequence must either be interruptible or short enough so interrupts can be locked out. Memory references must be mapped and traps must be enabled for the step that starts memory. If the cycle is a read from memory, the cycle must be finished in the same step in which it is begun. A CAM update can occur automatically. Page fault vectors can also occur. Because the program counter is automatically backed up and the instruction is re-executed after the paging software has found the missing page, the P-counter must be pre-loaded with the address +1 (FUII cleared) or address +2 (FUII set) before the memory reference is attempted, if there is a chance that the page will not be in memory.

In the second method of writing virtualizable μ -code, the user "sees" an entirely different machine wholly created in new μ -code. In this case, a new fetch cycle is written and the μ -code must be made interruptible. The paging problem can be handled by changing the entry point into the μ -code and allowing the P-counter (register 7) to be decremented, and the EVMX found there to be re-executed. If this is done, the user visible machine must use some other register as a virtual program counter.

SECTION 7

MICROCODE TACTICS

This section briefly describes some techniques that have been found useful in inventing and encoding μ -code algorithms. Standard good programming practices are all that are generally required, but some specific tactics have been found useful.

The primary difference between coding for a normal assembly level language and coding for Prime μ -code, is the additional paralleled capability available in μ -code. Conventional flowcharting techniques have frequently been found to be inadequate guides in revealing where the inherent parallelism can be exploited.

One technique that has proved useful is to break the original algorithm into:

a. Decisions:

These generally require one use of a conditional branch per decision. This requires the condition code or C-Bit to be ready at least one step before and will use fields 11 and 12. A minimum μ -code algorithm requires at least as many steps as there are decisions.

b. Constants:

Except for 0, 1, and -1, these will have to come from the μ -code. (0, 1, and -1 can be generated in the ALU.) Often it is possible to store a constant somewhere more convenient for further use so that only each distinct constant need be counted.

Because constants, like conditional branches, must use fields 11 and 12, the total of decisions and conditional branches is equal to the minimum number of steps.

c. BD use:

It is generally possible to count the number of times some result must be put somewhere. This requires a trip through BD.

Using the information on BD use, decisions, and constants, the next step is to try to generate μ -code sequence that uses the maximum number of fields per instruction. For example, in one operation, it is possible to test and conditionally branch on the condition code, perform a memory read, transfer RM to register '12, and to set the condition code to show a zero:

```
CPU BB RM ALL ZERO L M 12;
RMRFMRDY MREAD SETCC;
JUMP ON NE TO S12
```

The free use of parallelism must be tempered however by remembering that it is not possible to use one field to specify two things:

```
ALU RA PLUS RCM = 1 =>RM;
NOP GO TO S12
```

will not work because fields 11 and 12 are twice specified; once by the RCM = 1, and once by the GO TO.

The following, however, is legal:

```
ALU INC RA =>RM NOP;
GO TO S12
```

It accomplishes the same thing as the previous example, but only uses fields 11 and 12 once, for the GO TO.

Some other examples of exploiting parallelism include:

1. Increment RP RP and RY load the shift counter with a -15.

```
CPU AL RCM NX INC 1 M RP;
RYRF240 NOP LOADRSC;
DATA -15
```

2. Shift RA the number of places in the shift counter, return to the fetch cycle when finished:
Load the C-bit with the bit shifted out of RF01.

```
CPU RFLS 7 ALL 7 0 M RA;
RF240 RF01 INCRSCF;
JUMP ON RSCNEM1 TO *
```

3. Perform a subtract of RM and RA; to RA, Jump on a not equal condition.

```
ALU RA MINUS RM RA SETCC;
JUMP ON NE TO S12
```

Use of scratch registers is another area where considerable speed increase can often be realized by carefully assigning the use of the available registers. Within the register file, registers 11, 12, and 13 are always available. Registers 0 - 6 are also open if their function in normal μ -code can be ignored. For example, 4, 5, and 6 are available if the floating point accumulator can be destroyed.

The registers RM and RY are also open. These have some extra power. They are always available, and transfers from one to the other, or to any register in the file takes only one step. Transfer from one register in the file to another takes two steps (using RM or RY for intermediate storage). A number in RM or RY may be TWO's complemented in one step. However, if RY is both the source and destination for an operation, neither the C-bit nor the condition code is valid.

Finally, if a register is required for a very brief period, then registers YSAVE, MSAVE, RSCSAVE and 17 are available, if no DMX traps or page traps are permitted during the time the register is in use.

The use of high-speed registers, instead of memory, gains an immediate improvement of at least seven times in access time. In addition, a single micro-step can select a register, then read and modify it.

SECTION 8

MICROCODE WRITING AND IMPLEMENTING

8.1 GENERATION PATH

1. Generate μ -code algorithm.
2. Select Program Organization.

This activity includes selection of program segments and subroutines, register assignment and other general tasks. Flow charting could be part of this step.

3. Generate Code.

It is at this time that parallelism is exploited and the logic reduction effort is most intense.

4. Create Source.

During this step, detailed knowledge of the system editor (ED) and μ -code assembler formats is required. Section 8.2 and 8.3 covers this information in detail.

5. Assemble Source.

If step 4 has been properly done, inputting the DOS command: PMA Filename (Filename) is all that is required.

6. Print Listing.

7. Examine and correct assembler flagged errors.

Section 8.3.5 covers some of the more frequently encountered errors.

8. Repeat 5, 6, and 7 until no errors are detected by the assembler.
9. Prepare a load module for WCS. See Section 8.4.
10. Load the WCS board and begin debug. Section 8.5 contains some examples and details of this process.
11. Correct errors found in debug on the source and repeat steps 5-10 until program is judged to be working.
12. Finished.

8.2 SOURCE CREATION

Source code must be generated in a form compatible with the PMA assembler and also with the macro package called MA which acts as a microcode assembler. In the remainder of this section, it is assumed that the user has a detailed knowledge of ED and how to use it. However, a few notes should prove helpful.

8.2.1 Ed Notes

- a. The tabset normally used is 8, 16, 21, 24, 32, 39, 45, 51
- b. Semi-colons are frequently required to indicate a μ-code line is continued on the next source line. The editor will not accept them. One strategm for inserting semi-colons is to substitute another character (& or #, etc.) for the semi-colon and then changing all of these characters to the semi-colon using a global Change command to the Editor.

8.2.2 Normal Source

In addition to the μ-code steps themselves, additional instructions are necessary or customary. The following shows a typical example of μ-code source:

* SAMPLE MICRO-CODE	/Line for printout header.
P300 XSET 3	/Required - sets assembler for WCS.
\$INSERT MA	/Load in μ-code macro masters.
IDNT (SAMPLE MICRO-CODE)	/Required - see 8.3.1
ORG \$C00	/WCS starting address
(body of μ-code)	
END	

8.3 MICROCODE ASSEMBLER

The microcode assembler consists of several macro calls. The detail of the mnemonics and format is summarized in Appendices A and B. There are also several utilities associated with the assembler.

The microcode assembler uses the idea of fields. Fields are given argument numbers by position starting with argument one (1) as the first value after the macro. By definition, argument 0 is the label. Each argument must be separated by a comma or by one or more spaces. Null arguments are assumed to take a default value. (Zero for all fields except 3 and 10 which have 2 and 4 as default.) Several examples are given to show how the assembler interprets spaces and commas.

#1	CPU	RF,,,RA...	/5 blank Fields
#2	CPU	RFΔ,,,RA...	/5 blank Fields
#3	CPU	RFΔ,Δ,,,RA...	/5 blank Fields
#4	CPU	RF,ΔΔ,,,M,RA	/4 blank Fields

Normally, the position of an argument determines its interpretation. For example, the CPU macro typically contains 12 fields and, hence, 12 arguments. The RR Macro can contain as few as two and as many as six arguments and be meaningful.

Exceptionally, items that resemble arguments (i.e., they are separated by commas or spaces) can be interpreted as simply adding to the readability of the macro without being further interpreted by the macro. Examples of this type of word for the CPU ALU and RR macros are "ON" and "TO" and "=>". They are formally termed "noise words".

Also to be contended with, are words that serve to define the argument following it as an argument with a specific number regardless of position. Examples of these "positional noise words" are "C=", "TR=", "=", and "+". These words can be anywhere in the argument string and serve to identify the following argument as having a specific "place". Note that "+1" is interpreted far differently than " $\Delta+\Delta 1$ ". In the former case, a 1 is added to the value of the previous symbol. In the latter, field 5 is set to 1.

Another feature of microcode fields 6 and 12 is that arguments can be 'or'ed together within parenthesis. There is a limit of 32 characters that may be in the area enclosed by parenthesis.

8.3.1 Auxiliary Macros

```
(label) IDNT ARG1, ARG2 . . . ARG10
```

There can be up to 10 arguments of up to 30 characters each. (This serves as header for the tape listing.) This macro is required before other µ-code to initialize the microcode assembler.

Example: IDNT (PRIME 211 REV E MICRO-CODE),
 (PRE-RELEASE VERSION),
 (APRIL 9, 1973)

```
(label) ORG ARG1
```

ORG is part of the full symbolic statement label capability in this assembler. Labels are maintained and usable in exactly the same way as for standard assembler code. * can also be used as can *-1 and *+1, etc. ORG is useful for absolutely positioning a given statement (like a trap location).

8.3.2 CPU Macro

This macro simply encodes on a field by field basis the symbols defined for each microcode field as defined in Appendix A. It is normally used when the activities desired cannot be conveniently specified using the RR or ALU Macros. The limitation is that no self-checking is done so illegal clock speeds and nonsense transfers are as happily assembled as legitimate instructions. Let the user beware!

8.3.3 RR Macro

The Register to Register transfer Macro is intended to be used for non-arithmetic transfer operations of a normal sort. The chores of allowing proper clocks and traps is taken care of implicitly. Additionally, Register file selection is checked to find if the same register is used for both source and destination. If not, an error is logged.

Appendix B defines the format and symbols of the RR Macro. The RR Macro automatically selects the proper values for fields 1 to 12. However, argument <3> can be used to override the normally selected NOP and TR=, C=, and = override fields 3, 9, and 11 and 12, respectively. (Note that C=, TR= and = must have at least one space on either side.)

The fastest clock possible for the options selected is chosen.

For clocking RY or No destination traps are set = NX unless otherwise specified.

Note that IAC's do not change the chosen clock.

8.3.4 ALU Macro

The ALU Macro is intended to be used for arithmetic operations of a normal type. Like the RR macro, the fields are implicitly filled where possible. Appendix B shows the format and special symbols used in the ALU macro.

8.3.5 Microcode Error Messages

The Micro-code assembler has various cryptic methods of informing the user of his transgressions. Frequently, a major disaster is flagged with a little comment. On the other hand, a missing space or comma can generate a string of up to 14 errors.

Figure 8-1 shows a simple micro-code program with problems.

Example 1 shows the ordinary result of mistyping a field symbol. In this case, field 2 (BB select) was typed in as BB instead of RCM. The macro package appended a B\$ to the label and found the results undefined. This problem is shown by the error message that includes the comments "BB evaluate".

Example 2 demonstrates the type of error statement which can be expected from the attempt to transfer information from one register in the file to another in one instruction. (In this case, both RA and RB are used.)

Example 3 shows the typical result of forgetting the comma required to define the missing field. The line should be:

ALU INC RS => RS , JUMP ON EQ TO START

Example 4 shows the consequence of the omission of a single field (BB select) in a CPU macro. Each following field is misdefined, producing error statements for all of them. Note that after each XSET there is a "letter" \$ followed by one of the source fields. The comments areas show the field that the assembler thought it was working on.

```

<0051> IDNT      <PRIME MICRO-CODE -- ERRORS>
<0052> + ERRORS SAMPLE MICRO-CODE
<0053> +
<0054> START    CPU     BB   BB   NX   ZERO   L   M   RA
<0055>             RF260   NOP   SETCC DATA 1234
1. U 000000 (ML01) BBV$ XSET   B$BB   BB EVALUATE
   000. E23C 1007 0000 0002
2. F <0056> ALU     RA PLUS RM => RB , JUMP ON NE TO START
   (ML01) FAIL
   001. 8260 2004 0004 4000
3. U <0057> ALU     INC RS => RS JUMP ON EQ TO START
   000000 (ML01) IAV$ XSET   J$JUMP
   U 000000 (ML02) EMV$ XSET   K$EQ   EM EVALUATE
   V 000000 (ML02) ERB$ XSET
   002. 8264 3B06 0000 0000
4. <0058> CPU     RCM  ALL  0   0   M   RA ;
   <0059>             RF260  COUT  SETCC DATA 1234
   U 000000 (ML01) B0V$ XSET   R$RCM
   U 000000 (ML01) BBV$ XSET   B$ALL
   U 000000 (ML01) AMV$ XSET   E$M
   U 000000 (ML01) BRV$ XSET   F$RA
   U 000000 (ML02) AVF4$ XSET G$RF260
   U 000000 (ML01) CLV$ XSET   H$COUT
   U 000000 (ML01) CSV$ XSET   I$SETCC
   U 000000 (ML01) IAV$ XSET   J$DATA
   U 000000 (ML02) EMV$ XSET   K$1234
   V 000000 (ML02) ELB$ XSET
   V 000000 (ML02) ERB$ XSET
   003. 0000 0000 0000 0000

```

Figure 8-1. Errors Sample Microcode

8.4 PREPARATION OF A LOAD MODULE

After a microcode assembly has been successfully completed, a procedure must be performed to generate a block of code suitable for loading WCS.

The assembly produces an object file of microcode that must be loaded using the loader.

A sequence to do this is:

```
FILMEM  
LOAD  
LO B < (filename)  
MA  
QU
```

This sequence generates a memory image of the microcode starting at '10,000+ 4*(starting microcode address). For the WCS starting address, this is '10000+ \$C00*4 = '40000. A 256 word module uses 256 * 4 = 1024 = '2000 words of HSM. This module may be directly loaded into the WCS board, or it may be saved on the disk.

8.5 WRITABLE CONTROL STORE BOARD (WCS) OR EXTEND CONTROL BOARD (XCS)

The XCS option provides extended microprogramming capability to Prime central processors and microprogrammed options. XCS features include:

1. 512 words of PROM for extending the central processor microcode (FPROM).
2. 512 words of PROM for further extension of central processor microcode with reduced control unit speeds (SPROM).
3. 256 words of writable RAM (random access memory) designated as Writable Control Store (WCS) used for further extension of central processor or microprogrammed controller microcode. WCS can also be used for dynamic microprogram testing and execution from either central processor or microprogrammed controllers when used in the simulator mode. When operating in simulator mode, the simulated module is disabled and WCS data is provided whenever the simulated module is addressed.
4. Provisions are included for connecting an external PROM copier to allow PROM programming utilizing data from WCS.

5. A Field Engineering Panel Interface is included as an aid for troubleshooting the central processor and the XCS. Switches and indicators are contained on the standard FEP hand control.

8.5.1 PROM COPY Interface

The PROM COPY Interface consists of a cable between XCS and a PROM copier. Addresses to this site are provided from the PROM copier and are sent to WCS. Data to this site is provided by bits 61 through 64 of WCS and is sent to the PROM copier. The procedure for copying PROM is as follows:

1. With power OFF, connect PROM copier to XCS.
2. Turn power ON.
3. Insert new PROM in copier.
4. Execute a CRA and an OTA '324.
5. LDA with data to be programmed into location 0 of PROM in bits 13 through 16 of A register.
6. Execute four OTA '124 (data is written into proper cell during 4th OTA).
7. LDA with data to be programmed into location of PROM into bits 13 through 16 of A register and continue as in E and F above until all 256 locations are loaded.
8. LDA = '040000
9. OTA '324
10. HLT
11. HLT (or JMP to suitable terminal I/O response routine).
12. Depress PROM copier button.
13. Verify copy.
14. Remove PROM and insert new PROM.
15. Start CP and jump to routine to load WCS with next data to be copied.
16. Go to 4 above.

8.5.1.1 Instructions for Use of PROM, μ -Code Program

For example programs, see Appendix E.

8.5.2 FPROM Interface

The FPROM Interface consists of a central processor BCY (control memory address bus) buffer and address decoder plus 13 or 26 PROMs.

8.5.3 SPROM Interface

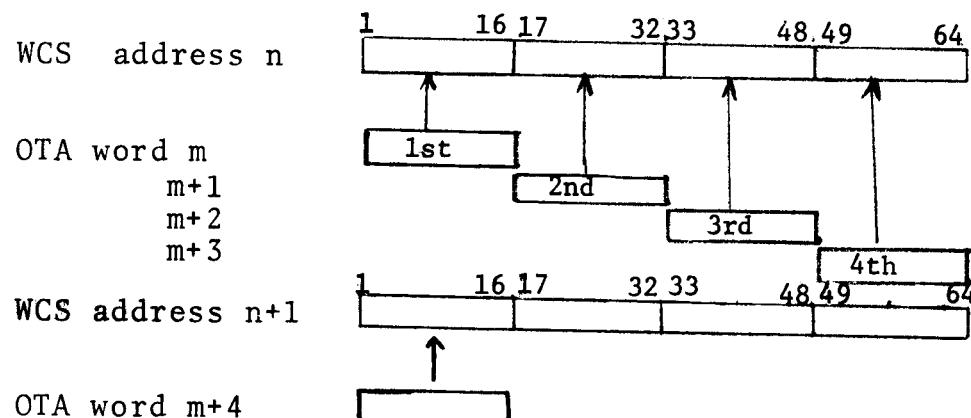
The SPROM Interface consists of the following:

1. A multiplexer for selecting central processor BCY.
2. Either 13 or 26 PROMs.
3. A data buffer for interfacing with the central processor.
4. Dip sockets wired to address and data for interfacing to external microprogrammed controllers.

8.5.4 WCS Interface

The WCS Interface consists of the following:

1. An incrementing register used for loading/fetching data into/from WCS. The WCS will pack four central processor words into one microprogrammed word, then increment the WCS address register (see below).



2. Module decoders for disabling the simulated module of the central processor, XCS, or external microprogrammed controller. These signals are sent to the controller as DSMODn where n equals the module to be disabled.

3. A WCS address multiplexer for selecting one of the following:
 1. PROM copier
 2. Central processor BCY
 3. WCS address (used when writing into or fetching data from WCS)
4. An address comparator used to enable WCS when addressing a simulated module.
5. 52 RAMs

8.5.4.1 WCS LOAD PROGRAM

SAMPLE SIMPLE WCS LOAD PROGRAM

PAGE 6001

```

(0001) * SAMPLE SIMPLE WCS LOAD PROGRAM
(0002) *
(0003) * PROGRAM ASSUMES U-CODE STARTS AT '10000 (AS STANDARD
(0004) * WCS CODE DOES) AND LOADS ALL 256 WORDS OF WCS.
(0005) *
(0006) * A NON-ZERO A REGISTER SETTING ON ENTRY WILL BE USED TO
(0007) * OVERRIDE THE DEFAULT '10,000 SETTING.
(0008) *
(0009) * A NON-ZERO B REGISTER SETTING ON ENTRY WILL BE USED TO
(0010) * OVERRIDE THE STANDARD WCS MODE TO ENTER SIMULATE MODE
(0011) * WITH SIMULATION OF THE ADDRESS SPACE SPECIFIED IN B.
(0012) *
(0013) *
(0014) * THE ROUTINE CAN ALSO BE USED AS A SUBROUTINE BY INSERTING
(0015) * AN ENTRY POINT BEFORE START, AND EXITING WITH A JMP*
(0016) *
(0017) *
(0018)     REL
(0019) *
000000:          START    ELM
000001: 031724 00021) OCP    '1724           INITIALIZE WCS
000002: 25. 0000026 (00022) LDW    --100000           DEFAULT START
000003: 1000010 (00023) SZE
000004: 25. 000001A (00024) LDW    1           SPECIFIED START
000005: 22. 0000027 (00025) LDA    --(256+1)           # OF WORDS
000006: 04. 0000025 (00026) STA    COUNT
000007: 22. 000000A (00027) LOOP   LDA    0, 1           LOAD 1/1 WCS WORD -- WCS BUMPS OWN POINTER.
000008: 170124 (00028) OTR    '124
000009: 01. 0000010 (00029) JMP    +-1
000010: 1101114 (00030) IRX
000011: 12. 0000025 (00031) IRS    COUNT
000012: 01. 0000007 (00032) JMP    LOOP
000013: 031724 (00033) OCP    '1724           RESET WCS BOARD
000014: 140204 (00034) MCS
000015: 101010 (00035) SNZ
000016: 0000000 (00036) HLT
000017: 170224 (00037) OTR    '224           RETURN OR JMP TO PROGRAM.
000018: 01. 0000021 (00038) JMP    +-1           OUTPUT SIMULATE STARTING ADDRESS
000019: 0300224 (00039) OCP    '224           ENTER SIMULATE MODE.
000020: 0000000 (00040) HLT
000021:          (00041) *
000022: 00. 040000A (00042) COUNT  DAC    ++
000023:          (00043) *
000024:          (00044) END
000025: 00. 040000A
000026: 00. 170000A

```

8.5.5 Firmware Description

Table 8-1 describes the allocation of CP/XCS microprocessor address space.

Table 8-1

All addresses in hexadecimal.

MODULE		
000 - OFF	CPU	0
100 - OFF		1
800 - 8FF	SPROM	4
900 - 9FF		5
400 - 4FF	F PROM	2
500 - 5FF		3
C00 - CFF	RAM	6

Portions of XCS that are used with the central processor should follow the standard formats.

A. Field 8, Destination and Time of cycle. Times are specified (see Section 3 - Timing).

CP Simulator Mode - When RAM is utilized in the simulator mode, the microcode must be written with field 8 times equal to that required for the address space that is being simulated. WCS hardware delays are introduced when entering this mode to compensate for any restrictions that might otherwise be imposed by field 8.

8.5.6 Software Description

In addition to standard I/O instructions, the XCS utilizes four instructions that are restricted.

	<u>OP CODE</u>
EPMX - Enter Paging Mode and jump to XCS	'237
EVMX - Enter Virtual Mode and jump to XCS	'723
ERMX - Enter Restricted Mode and jump to XCS	'721
LPMX - Leave Paging Mode and jump to XCS	'235

Each of these instructions have the following format and require three HSM locations:

CP word n	(instruction word)
n+1	(pointer to address m)
m	(address in XCS to jump to)

8.5.7 I/O Instructions

The XCS is always ready and always skips on its INAs and OTAs.

OCP '1724 - INITIALIZE

Places WCS in same status as following a MASTER CLEAR with the exception of the clock slow down, which is not disabled until initiation of the next instruction. WCS address register and comparator are set to a default address of \$C00, (\$ indicates hexadecimal notation.) Simulator mode is disabled. Copy address is disabled.

OCP '324 - SIMULATE MODE

1. No external microprogrammed option attached.
 - a. Lengthens all micro instructions by 80 nanoseconds.
 - b. Disables the simulated module associated with the central processor.
 - c. Provides WCS data to the central processor whenever the disabled module is addressed.
2. External microprogrammed option attached.
 - a. Disables the simulated module associated with the microprogrammed option.
 - b. Provides WCS data to microprogrammed option whenever the disabled module is addressed.

NOTE: IF SIMULATING CENTRAL PROCESSOR MODULE 0 or 1 - CARE SHOULD BE TAKEN TO ENSURE COMPATIBILITY OF MICRO-STEPS FOR A SMOOTH TRANSITION FROM THE ACTIVE MODULE TO THE SIMULATED MODULE. OCP SIMULATE MODE TAKES EFFECT DURING THE OCP OR THE FOLLOWING INSTRUCTION. PROVISIONS HAVE ALSO BEEN INCLUDED TO ENTER SIMULATE MODE BY MEANS OF A SWITCH (SS3 ON FPEII).

OTA '324 - OTA ADDRESS

1. Output the starting address of the WCS microcode addresses to be loaded, fetched, or simulated. If loading for normal WCS mode into location \$C00, no OTA '324 is necessary if no prior OTA '324 has been issued. If loading any other address or consecutive addresses, the starting address must be OTA'd. Only one module at a time can be simulated, therefore, care should be taken to avoid outputting words across the module boundary. Only entire 256 word modules can be simulated. Any individual word or consecutive words being simulated can be changed by disabling simulator mode (OCP initialize), OTA the individual address to be changed, OTA the data to be changed, OCP Simulate Mode.
2. Select PROM copier for address to and data from WCS if bit 2 of the A register is set.
3. Deselect PROM copier if bit 2 of A register is not set.

OTA '124 - OTA DATA

1. Loads data into WCS from the A register.
When used with the central processor, use the following format:

Word 1	1	RCC	16
Word 2	17	RCC	32
Word 3	unused	45 RCC 48	
Word 4	49	RCC	64

The above format is generated from a LOAD.

2. Increment WCS address register after four OTAs.

INA '1124 - ID NUMBER

The format of the data is as follows:

1	3	4	8	9	10	11	16
0	0	0	SLOT #	0	0	'24	

PROGRAMMING NOTES

1. When using WCS in its normal mode, no OCPs or OTA address are necessary. Powering on of the central processor sets the XCS into the normal (addresses equal \$C00 - \$CFF) WCS mode. Simply OTA the data to load WCS. The data is now available for execution. Halting the processor and master clearing does not affect the data. WCS data is available(just as the standard central processor PROM data is available) simply by addressing it.
2. When using XCS in simulator mode, first OTA a starting address then OTA the data and finally, OCP Simulate Mode. To leave Simulate Mode, issue an OCP initialize or Master Clear.

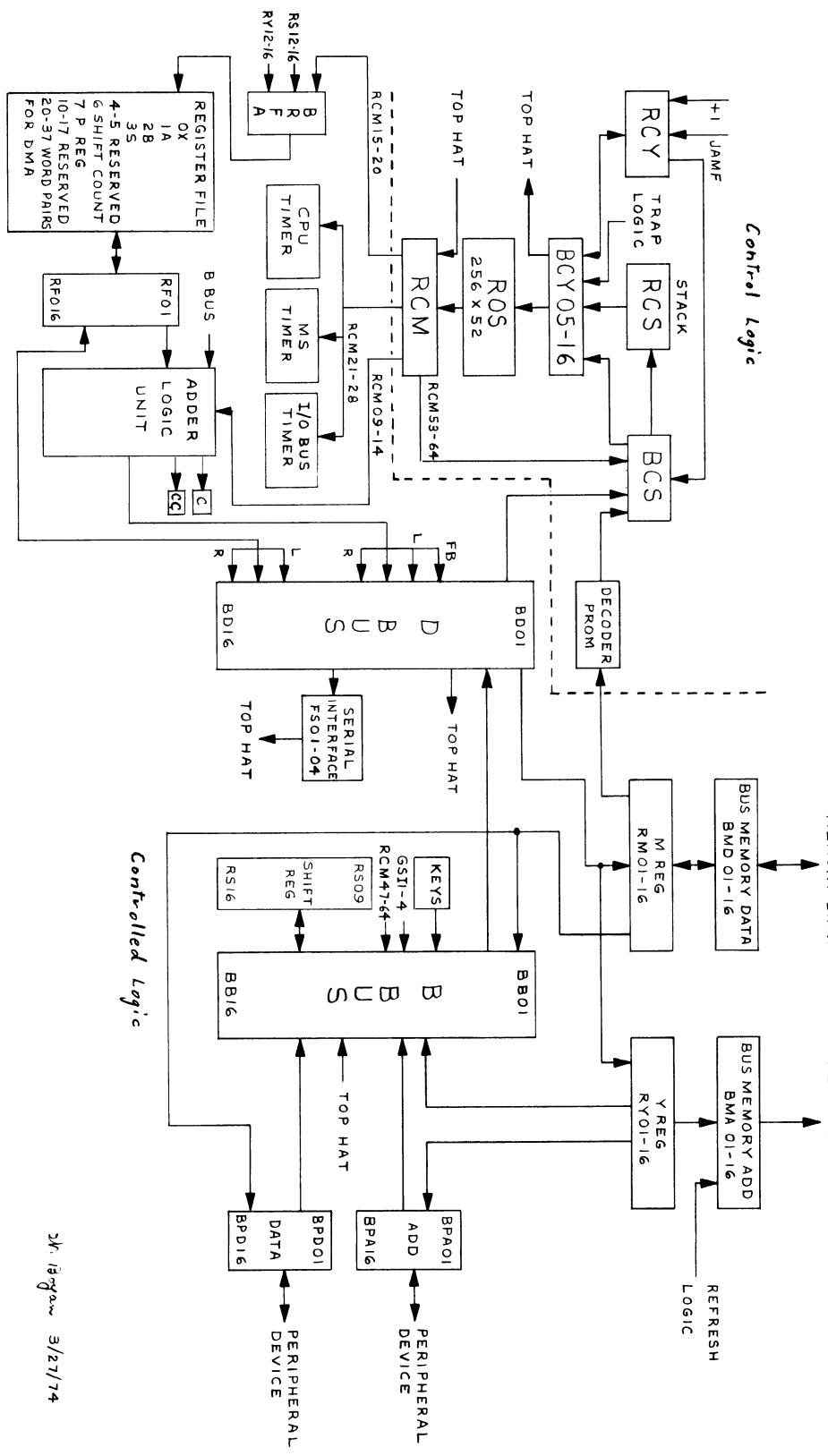
3. To add 80 nanoseconds to all microcode steps, issue an OCP simulate after an OCP initialize or master clear or use SS3 on REPII (maintenance troubleshooting feature).

Note: Do not address SPROM after OTAing a SPROM address without first initializing (OCP '1724) or entering simulate mode (OCP '324).

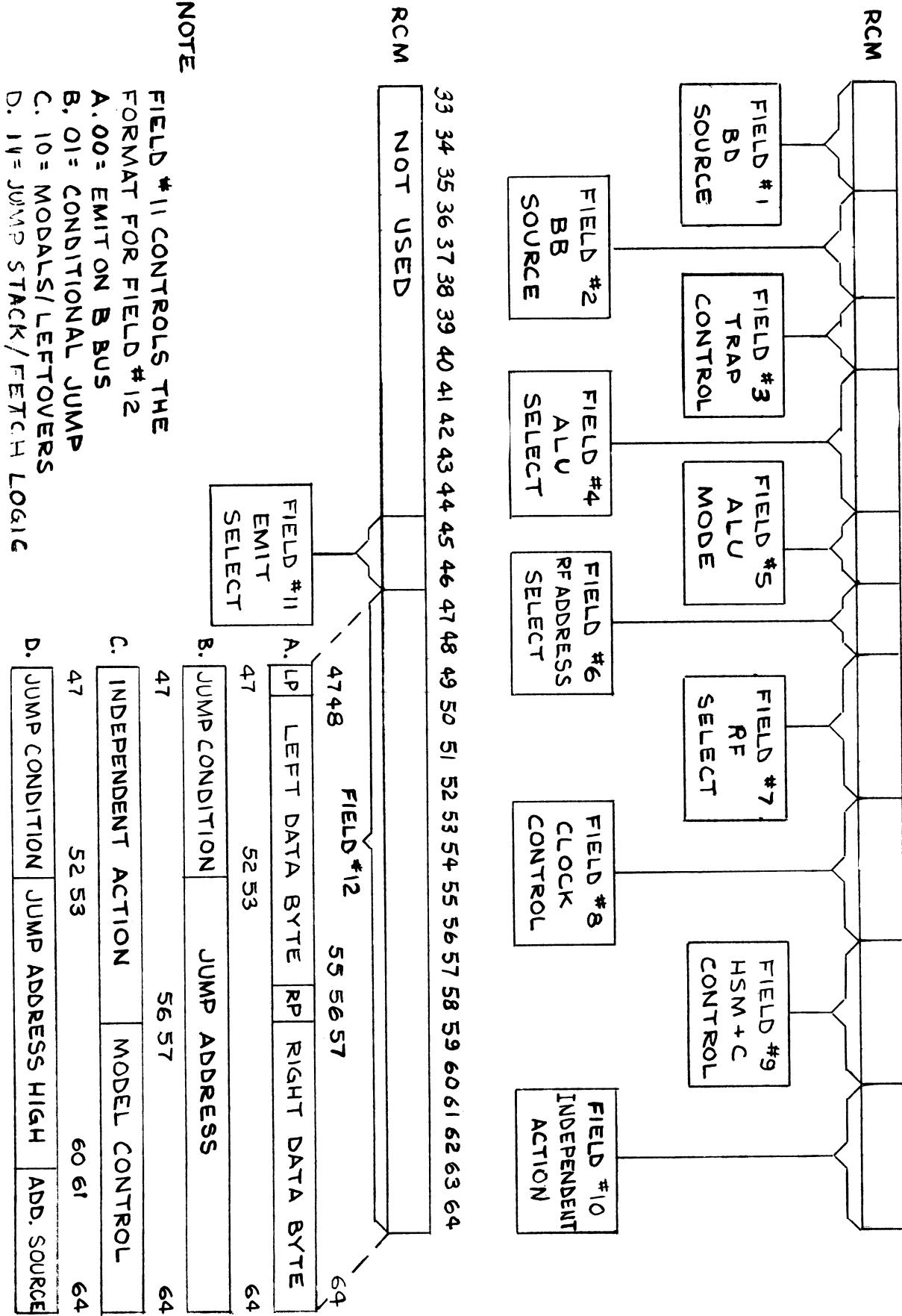
APPENDIX A
BLOCK DIAGRAM, MICROCODE FORMAT
AND FIELD DESCRIPTIONS

CPU BLOCK DIAGRAM

CPU BLOCK DIAGRAM



1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32



APPENDIX A (cont)
Basic M-code Field Description

Figure 1

FIELD DESCRIPTIONS		ROM BITS
Field #1	BD Source Select	3 RCM 01-03
Field #2	BB Source Select	3 RCM 04-06
Field #3	Trap Control	2 RCM 07-08
Field #4	ALU Select	4 RCM 09-12
Field #5	Arithmetic Carry/Mode Control	2 RCM 13-14
Field #6	RF Source Select (BRFA)	2 RCM 15-16
Field #7	Register File Source Select	5 RCM 17-20
Field #8	BD Destination and Clock Control	4 RCM 21-24
Field #9	Carry Source, Main Memory Operation	4 RCM 25-28
Field #10	Independent Actions	4 RCM 29-32
Field #11	Emit Select	2 RCM 45-46
Field #12	Emit Field	16 RCM 47-64
Reserved for Future Use		12 RCM 33-44

Field #1: D-BUS SOURCE SELECT		Shift End Conditions*				Modifying Fields			
Field #1	Source	Destination = D-Bus (BDxx)				Link**	Field #2	Field #4	
0, RF, (blank)	RFxx	01 02 03 04 05 06 07 08 09 10 11 12 13 14 15 16	BD16	BD02	BD01	RF02 RF01 Link 0 Link Link Link	RF01 RF02 RF01 RF02 RF02 RF01 RF02	7, BTH 1,KEYS,RSC 3,RM 7,BTH 3,RM 3,RM 3,RM	7 8 7 3,ZERO,2A 9,SUB 6,XOR,ADD 3,ZERO,2A
1, RFLS	RFxx	03 04 05 06 07 08 09 10 11 12 13 14 15 16				RF01 RF01 Link 0 Link Link Link	RF16 RF16 RF16 RF16 RF16 RF16 RF16	3,RM 5,BPA 2,RY O,RM08,SI, 1,KEYS,RSC 3,RM	6,ADD 6,XOR,ADD 6,ADD 6,XOR,ADD 6,XOR,ADD 6,XOR,ADD
2, RFRS	RFxx	02 03 04 05 06 07 08 09 10 11 12 13 14 15				RF01 RF01 RF01 Link RF01 RF01	RF16 RF16 RF16 RF16 RF16 RF16	3,RM 5,BPA 2,RY O,RM08,SI, 1,KEYS,RSC 3,RM	6,ADD 6,XOR,ADD 6,ADD 6,XOR,ADD 6,XOR,ADD 6,XOR,ADD
3, ALFB	ALxx	09 10 11 12 13 14 15 16 01 02 03 04 05 06 07 08							
4, AL	ALxx	01 02 03 04 05 06 07 08 09 10 11 12 13 14 15 16							
5, ALLS	ALxx	02 03 04 05 06 07 08 09 10 11 12 13 14 15 16					DIVGQ1	3,RM	
6, ALRS	ALxx	01 01 02 03 04 05 06 07 08 09 10 11 12 13 14 15					AL16	6 or 9	
7, BB	BBxx	01 02 03 04 05 06 07 08 09 10 11 12 13 14 15 16						6,XOR,ADD	
RF(xx)	Register File (bit xx)		ALLS	ALU left shifted one bit			* It is possible to create other shift end conditions, but these cover all the useful cases.		
RFLS	Register File left shifted one bit		ALRS	ALU right shifted one bit					
RFRS	Register File right shifted one bit		BB(xx)	B Bus (bit xx)					
AL(xx)	Arithmetic & Logic Unit (ALU) (bit xx)		BD(xx)	D Bus (bit xx)			**if enabled by Field #9 = 1 to 7		
ALFB	ALU with bytes swapped		DIVGQ1	Incremental divide quotient bit					

Figure 2

Figure 3

Field #2 : B-BUS SOURCE SELECTION		Destination = B-Bus (BB xx)															
Field #2	Source	LP 01 02 03 04 05 06 07 08	RP 09 10 11 12 13 14 15 16														
0, RM08, SI, (blank)	RMxx GSIx FDPM FCBIT	- 08 08 08 08 08 08 08 *	-- - - - - 1 2 3 4														
1, KEYS, RSC	FAMI FAM2 RSxx	0 0 * 09 10 11 12 13 14 15 16															
2, RY	RYxx	LP 01 02 03 04 05 06 07 08	RP 09 10 11 12 13 14 15 16														
3, RM	RMxx	LP 01 02 03 04 05 06 07 08	RP 09 10 11 12 13 14 15 16														
4, RCM	RCMxx	47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64															
5, BPA	BPAxx	LP 01 02 03 04 05 06 07 08	RP 09 10 11 12 13 14 15 16														
6, BPD	BPDxx	LP 01 02 03 04 05 06 07 08	RP 09 10 11 12 13 14 15 16														
7, BTH	BTHxx	LP 01 02 03 04 05 06 07 08	RP 09 10 11 12 13 14 15 16														

"—"=generated byte parity bit
 "--"=undefined
 "LP"=left byte parity bit
 "RP"=right byte parity bit

*No Parity on BBRP for GSIX or RSXX. If these inputs are used, new parity must be generated (by going through the adder).

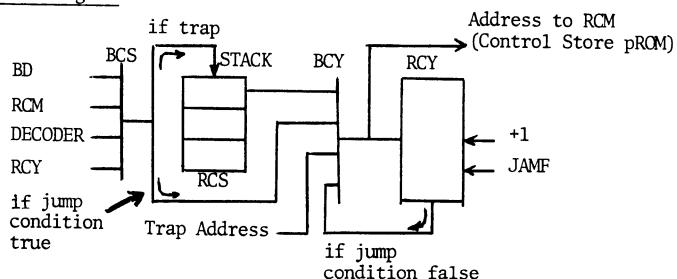
RM (xx)	M Register (bit xx)	RS (xx)	Shift Register (bit xx)
SI	Serial Interface	RY (xx)	Y Register (bit xx)
GSI (x)	Serial Interface (bit x)	BB (xx)	B-Bus (bit xx)
RSC (xx)	Shift Counter Register (bit xx)	BPA (xx)	Bus Peripheral Address (bit xx)
FDPM	Double Precision Mode Flag	BPD (xx)	Bus Peripheral Data (bit xx)
FCBIT	Carry Bit	BTH (xx)	Bus Top Hat (bit xx)
FAM 1	Address Mode Flag, bit 1		
FAM 2	Address Mode Flag, bit 2		

Figure 4

Field #3: TRAP CONTROL

Field #3 =	Control
0, NONE	No Traps
1, TDMX	DMX Only
2, NX, (blank)	All but DMX
3, ALL	All Traps

Control Store Address Diagram



EXPLANATION OF MICROCODE TRAPS:

Priority	Hardwired	Description
Highest	Trap	
to	Address	
Lowest	(Hexidec.)	
1	6E	Missing Memory Module (generates interrupt)
2	6C	Memory Parity (generates interrupt)
3	6A	Central processor parity (generates machine check interrupt)
4	68	Restricted execution mode (generates interrupt)
5	66	Fetch read address trap (put RF into RM as appropriate instead of main memory to RM, load F01 and F02)
6	64	Read address trap (put RF into RM as appropriate instead of main memory to RM)
7	62	Write address trap (put RM into appropriate RF instead of main memory).
8	60	Page fetch read address trap (the CAM must be filled with the new page pointer if available; if not, generate a page fault interrupt; load F01 and F02)
9	7C	Page trap (same as 60 without loading of F01, F02)
11	72	Page writer violation (generates interrupt)
12	70	DMX (performs a DMX transfer without changing user execution flow)

Field #4: ALU FUNCTION SELECT ; Field #5: ARITHMETIC/CARRY MODE CONTROL				
Field #4	The ALU output (AL) as a function of its inputs (RF, BB and FCBIT)			
	Field #5 = 0, (blank)	Field #5 = 1, PLUS1	Field #5 = 2, CBIT	Field #5 = 3, L
0, RF, INC.	RF	RF + 1	RF + FCBIT	RF
1, AND	(RF& BB--) + RF	(RF& BB--) + RF + 1	(RF& BB--) + RF + FCBIT	RF& BB
2, BB	RF & BB + RF	RF & BB + RF + 1	RF & BB + FCBIT	RF & BB --
3, ZERO, 2A	RF + RF	RF + RF + 1	RF + RF + FCBIT	0
4, OR	RF ∨ BB	RF ∨ BB + 1	RF ∨ BB + FCBIT	RF ∨ BB
5, B, BB	(RF∨BB--) + (RF∨BB)	(RF∨BB--) + (RF∨BB) + 1	(RF∨BB--) + (RF∨BB) + FCBIT	BB
6, XOR, ADD	RF + BB	RF + BB + 1	RF + BB + FCBIT	RF+BB
7	RF + (RF∨BB)	RF + (RF∨BB) + 1	RF + (RF∨BB) + FCBIT	RF --& BB
8	RF∨BB --	RF∨BB -- + 1	RF∨BB -- + FCBIT	RF ∨ BB --
9, SUB	RF - BB - 1	RF - BB - 1 + FCBIT	RF - BB - 1 + FCBIT	(RF ∨ BB) --
10, BBN	(RF&BB) + (RF∨BB --)	(RF&BB) + (RF∨BB --) + 1	(RF&BB) + (RF∨BB --) + FCBIT	BB --
11, NOR	RF + (RF∨BB --)	RF + (RF∨BB --) + 1	RF + (RF∨BB --) + FCBIT	(RF∨BB) --
12, MINUS1	-1	0	-1 + FCBIT	1 (Logical)
13	(RF&BB --) - 1	RF&BB --	(RF&BB --) - 1 + FCBIT	RF --> BB
14	RF&BB-1	RF&BB	RF&BB-1 + FCBIT	(RF&BB) --
15, RFNOT, ANOT, DEC	RF-1	RF	RF-1 + FCBIT	RF --

ALU	Arithmetic and logic Unit	+ Add (Arithmetic ADD)
AL	ALU output	- Subtract (arithmetic Minus)
RF	Register File	AND
BB	B Bus	∨ Inclusive OR
FCBIT	Carry bit	∧ exclusive OR
		-- NOT

Figure 5

Fields #6, #7: REGISTER FILE SELECTION

Figure 6 Expansion of Field #7 for Field #6 = 1-3

Field #6=	BFRA=	Register Selected	Description/Comment (Std. Macro-Instruction Use)	Field #6=1, XM	Field #6=2, RY	Field #6=3,RSC
Field #6=	Field #7=			Field #7=	Field #7=	Field #7=
0,M,(blank)	0,RX,(blank)	0, RX	X Register: Index Register	0,(Blank)	0, (Blank)	0, (Blank)
	1, RA	1, RA	A Register: Arith,Shift,I/O	1, Disable	1, PIO	1, ENB
	2, RB	2, RB	B Register: Ext Arith, Shift		2, IEN	2, DATA
	3, RS	3, RS	Stack Pointer	All even numbers operate same as 0: odd	3=1A2	3=1A2
	4, FLTH	4, FLTH	Floating Point High		4, ICPN	4, CPN
	5, FLTL	5, FLTL	Floating Point Low		5=1A4	5=1A4 *
	6, VSC	6, VSC	Visible shift counter Accumulate		6=2A4	6=2A4
	7, RP	7, RP	P Register: Program Counter	Prime processors may use 2-17 for additional capabilities	7=1A2A4	7=1A2A4
	10, PMAR	10, PMAR	Page Map Address Register		10, ICAI	10, STROBE
	11,	11,	Scratch:μ-code Scratch Location		11=1A10	11=1A10
	12,EAS	12,EAS	Effective Address Save for ILL, UII,		12=2A10	12=2A10
	13,	13	Scratch:μ-code Scratch Location		13=1A2A10	13=1A2A10
	14, YSAVE	14, YSAVE	Scratch:RY Save for Control Panel & DMA		14=4A10	14=4A10
	15, MSAVE	15, MSAVE	Scratch:RM Save for Control Panel & DMA		15=1A4A10	15=1A4A10 *
	16, RSC	16, RSC	Scratch:RSC Save Location		16=2A4A10	16=2A4A10
0,M,(blank)	17	17	Scratch:μ-code Scratch Location		17=1A2A4A10	17=1A2A4 A10
				*resulting action is questionable		
1,XM	0,(blank)	0,RX	Select Index Register	CYCLE 1	CYCLE N	CYCLE N+1
1,XM	1,DISABLE	-	Disable Register File		Field #6=2,3	ROM CYCLES(Field #8)
2,RY	0,(blank)	RY	RY12-16=BFRA	ERYBPA	BPCPIO	
3,RSC	0,(blank)	RSC	RSC12-16=BFRA	BPCIEN	BPCIEN	
		Function Generated		BACIEN	BACCHI	
2,RY	1, PIO	ERYBPA	Enable RY on to BPA			
		BPCPIO	BPA stable for PIO transfers			
2,RY	2, IEN	BPCIEN	Staticize Priority Interrupts			
2,RY	4, ICPN	BPCICPN	Reset Interrupt Priority Net			
2,RY	10, ICAI	BPCCHI	Clear Highest Active Priority Interrupt			
3,RSC	1, ENB	BPCDEN	Staticize DMX Requests			
3,RSC	2, DATA	ERMBPD	Enable RM on to BPD			
3,RSC	4, CPN	BPCDCPN	Reset DMX Priority Net			
3,RSC	10, STROBE	BPCSTRB	Strobe DMX Transfer			
				BIT 19=0		
					BIT 19=0 or field #6 ≠ RSC	ERYBPD
						BPCDCPN
						BIT 19=0 or field #6 ≠ RSC

Field #8: CLOCK CONTROL PRIME 200

Clock Control Field # 8 =	BUS to Register Transfer at end of cycle		Nominal Cycle Time (ns)	Cycle Extended Until
	Source	Destination		
0, 200, (blank)	-	-	200	-
1, RM160	BD	RM	160	-
2, RM200	BD	RM	200	-
3, RMMRDY	BMD	RM	240	MRDY
4, RM280	BD	RM	280	YBSY--
5, RMRFMRDY	BMD	RM	280	MRDY
6, 280	BD	RF	280	-
7, RY280	BD	RY	280	YBSY--
8, RY200	BD	RY	200	YBSY--
9, RF160	BD	RF	160	-
10, RF200	BD	RF	200	-
11, RF240	BD	RF	240	-
12, RF280	BD	RF	280	-
13, RYRF280	BD	RY	280	YBSY--
	BD	RF	280	
14, CLMCLFCLI	BMD	RM	280	MRDY
	BD	RF		
	BRM	F01		
	BRM	F02		
15, RMRF280	BD	RM	280	-
	BD	RF		

RM = Memory Data Register

MRDY = Memory Access Completed

BRM = RM Bus

YBSY-- = Memory Cycle Completed

Note: BRM = BD if RCM25 = 0
= BMD if RCM25 = 1

-- = "NOT"

BMD = Memory Data Bus

BD = D=Bus

Figure 7

F01 = Indirect Address Mode

F02 = Indexed Address Mode

Field #8: CLOCK CONTROL PRIME 300

Clock Control Field # 8 =	Bus to Register Transfer at end of cycle		Nominal Cycle Time (ns)	Cycle Extended Until
	Source	Destination		
0, 200	-	-	200	-
1, RM160	BD	RM	160	-
2, RM200	BD	RM	200	YBSY-
3, RY240	BD	RY	240	YBSY-
4, RM280	BD	RM	280	-
5, RMRFMRDY	BMD	RM	240	MRDY
6, 280	BD	RF	280	
7, RMMRDY	BMD	RM	200	MRDY
8, RY200	BD	RY	200	YBSY-
9, RF160	BD	RF	160	
10, RF200	BD	RF	200	
11, RF240	BD	RF	240	
12, RF280	BD	RF	280	
13, RYRF240	BD	RY	240	YBSY-
	BD	RF		
14, RY280	BD	RY	280	YBSY-
	BD	RF		
15, CLMCLFCLI	BMD	RM	200	MRDY
	BD	RF		
	BRM	F01		
	BRM	F02		

RM = Memory Data Register

MRDY = Memory Access Completed

BRM = RM Bus

YBSY-- = Memory Cycle Completed

Note: BRM = BD if RCM25 = 0
= BMD if RCM25 = 1

-- = "NOT"

BMD = Memory Data Bus

BD = D=Bus

F01 = Indirect Address Mode

F02 = Indexed Address Mode

Figure 7A

Figure 8

Field #9: CARRY SOURCE, HSM OPERATION

Field #9 =	Signal Enabled on to Carry	Field #9 =	Memory Action Initialized	
0, NOP, CNOP, (blank)	None (Link disabled)	Mapped Reference, if in Page Mode; if not, Absolute Refer.		
1, DIVER,LINKS	Divide overflow, or Link source	8, MREAD	Read Memory (HSM01-16 → BMD 01-16)	
2, COUT	True 16 Bit carry	9, MRBW	Write Right Byte (RM01-16 → BMD 09-16 → HSM09-16; HSM 01-08 unchanged)	
3, BD01	D-Bus bit 01 (BD01)	10, MLBW	Write Left Byte (RM01-16 → BMD 01-08 → HSM 01-08; HSM 09-16 unchanged)	
		11, MWRITE	Write Memory (RM01-16 → BMD 01-16 → HSM 01-16)	
Absolute Reference, independent of Page Mode				
4, LINK	None (No change but LINK enabled)	12, AREAD	Read Memory (HSM01-16 → BMD 01-16)	
5, RF01	Register File bit 01 (RF01)	13, ARBW	Write Right Byte (HSM 01-08 unchanged; RM01-16 → BMD09-16 → HSM09-16)	
6, SOVFL	Shift Overflow (ALFHFT)	14, ALBW	Write Left Byte (HSM09-16 unchanged RM01-16 → BMD 01-08 → HSM01-08)	
7, AOVFL	Arithmetic Overflow (ALOVFL)	15, AWRITE	Write Memory (RM01-16 → BMD01-16 → HSM01-16)	

HSM xx = Main Memory Word bit xx
BMD xx = Memory Data Bus bit xx

Figure 9

Field #10: INDEPENDENT ACTION
Independent Action

Field #10 =	
0, JAMF	0 → RCY05-16 (Go to Fetch)
1, INCRSCF	RSC + 1 → RSC; 0 → RCY 05-16 (Increment Shift Register (RSC); Go to Fetch)
2, RESTJAMF	Cause a Restricted Execution Trap if Restricted Execution Mode is set; Go to Fetch
3	0 → RCY05-16 (Go to Fetch) Future processor models may expand definition
4, NOP, (blank)	No Operation
5, INCRSC	RSC + 1 → RSC (Increment Shift Register (RSC))
6, REST	Cause a Restricted Execution Trap if Restricted Execution Mode is set
7, SETCC	Set Condition Codes: Staticize "AL01--", "AL01-16 = 0" at end of cycle until next SETCC
8, LOAD256K	RY15,16 → RY99,00 if RCM02=0, BPA99,00 → RY99,00 if RCM02=1 (set high order Memory Address bits for DMA, DMT)
9, FORCERD	Force absolute memory reads without changing memory request status flops (MWLB, MRWB). Used to read memory map after a page fault. Will override a concurrent memory write request.
10, HSMRESUME	Resume interrupted memory operation; ie. start another memory cycle using previously set but interrupted, memory request status flops.
11, DISABLERHBB	0 → BB09-16, (Force right hand Byte of B Bus to zero)
12, PUSHBD	BD → BCS → RCS and Push stack: Field #3 must be = 0: (D Bus to μ-code stack)
13, EAF	In 16K Address mode: 0 → BD01, 02; In 32K Mode: 0 → BD01 (truncate D Bus per address mode for effective address formation)
14, LOADRSC	BB09-16 → RSC09-16 (Load Shift Counter from B-Bus)
15, CLEARFUII	Clear FUII status flop (FUII can be set (Field #11= 2, #12 = 10), reset (Field #10 = 15) and tested (field #11 = 1, #12 = 21); normally used to staticize unimplemented instruction traps)
RCY (xx)	Control store address register (bit xx)
AL (xx)	Arithmetic and logic unit output (bit xx)
RY (xx)	Y Register - memory / peripheral address register (bit xx)
BB (xx)	B Bus (bit xx)
BD (xx)	D Bus (bit xx)
BCS	Control store bus

Summary of Field #11 and Field #12

Field #11	Field #12
0, EMIT, (blank),	RCM47 → BBLP RCM48 - 55 → BB01-08 RCM56 → BB RP RCM57 - 64 → BB09-16 if field #2 selects RCM
DATA	RCM 48-55 → BB01-08 RCM 57-64 → BB09-16 BBLP and BBRP generated if field #2 selects RCM
1, J, JUMP	Jump condition: If the conditions decoded from bits RCM47-52 and listed below are true, then RCM53-64 → BCS05-16 → BCY05-16 → RCY05-16.
2, M, EAC, MODAL	Emit Action is selected by RCM47-50; RCM54 Triggers nonvisible keys; RCM56 Triggers visible keys; RCM 57-64 contain the keys
3,S	Jump Stack Condition & Fetch Logic Control; if the condition decoded from bits RCM 47-52 are true, create jump address (RCY05-16) as specified by RCM61-64 and check indexing conditions as enabled by RCM56-60; if false go to RCY + 1, but still check indexing conditions.

Figure 10

Field #12: JUMP FIELD (for field 11 = 1)

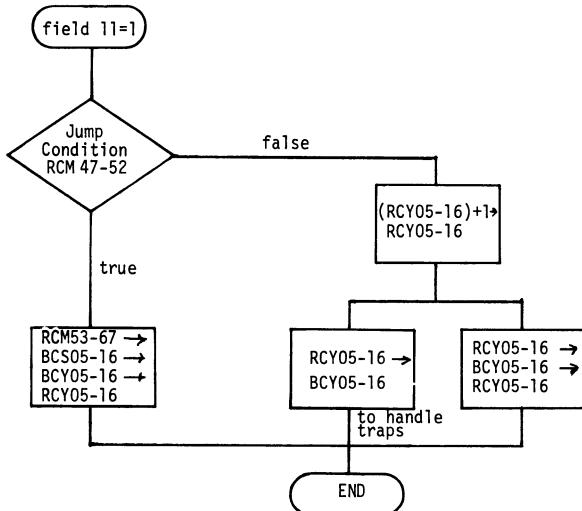


Figure 11A

Figure 11B

Field #12: JUMP FIELD (for field #11 = 1)		
Field #12 =	Signal Tested	Description
0, T, True, (blank)	-	Unconditional branch
1, RM01	RM01 +	Sign or Indirect bit
2, RMGEM240	GDL240-	RM08-16 \gg - 240; Relative mode addressing
3, BPSP1	BPCM0D2+	I/O Mode line; Interrupt: increment memory or external interrupt; INA: clear or OR
4, NE	FALZERO-	Test condition codes for not equal to zero
5, INPUT	BPCINMD+	DMX in input mode (set by external controller)
6, GE	FALMINUS-	Test condition codes for not minus; i.e., greater than or equal to zero
7, LE	GJCLE+	Test condition codes for less than or equal to zero (FALZERO \vee FALMINUS)
8, SKIP	FSKIP+	Staticized version of skip net
9, RSCNEM1	GRSC6Z-	(RSC) not equal to -1; used for looping as in shift instructions
10, FETCH1	GJCFSPI+	Any condition that require the fetch cycle be stopped: master clear, control panel, external interrupt, power failure.
11, SYSCLRNOT	FYSYSLCR-	Not master clear
12, CP	FRUN-	Control panel request
13, REL, AM1	FAM1 +	Relative mode, address mode #1
14, INDIRECTEND	GJCNMI+	End of indirect addressing chain
15, FCBIT	FCBIT+	Carry bit
16, STACKOP, RS15	GJCSOP +	Stack operation; (F01--V F02--) \wedge RS15
17, RELDONE	GJCRELD +	Effective address completed for relative mode; (F01-- \wedge F02--)
18, PUSH, RS16	RS16+	Push on to stack register (ie: RS16=1); (pop= (RS16=0))
19, FETCHDONE,	GJCNMAF+	Fetch completed (used as F01-- in PI/O instructions)
FO1NOT		
20, OTANOT	F01.F02	
21, FUII	FUII+	FUII Register/Flop; (used to indicate implemented instructions; set by field #11=2 and field #12=SETFUII; reset by field #10=15
22, DANOT20	GJCPA20-	DeviceAddress not equal to 20
23, READYNOTANDNE20	GJCRDY20-	Device not ready (external signal) and device address not equal to 20.
24, READYANDF02	FPCREDY \wedge F02	Device ready and OTA (F02)
25, FDRQ	FDRQ+	DMX request pending
26, RSC11	RSC11+	RSC11
27, RSC12	RSC12+	RSC12
28, DP	FDPM+	Double precision mode
29, DMX, STATREQ	FREQSEN-	Last DMX enable did not catch a DMX request
30, DMANOTVALID	DMA-VALID	Not a DMA request
31, DMTNOTVALID	DMT-VALID	Not a DMT request
32, FALSE	-	Do not jump
33, RM01NOT	RM01-	Not minus or not indirect
34, RMLTM240	GDL240+	RM01-16 \ll 240
35, BPSP1NOT	BPCM0D2-	I/O Mode line
36, EQ	FALZERO +	Test condition codes for equal to zero
37, OUTPUT	BPCINMD-	DM in output mode (set by external controller)
38, LT	FALMINUS+	Test condition codes for "less than" or minus
39, GT	GJCLE-	Test condition codes for greater than (FALMINUS-- \wedge FALZERO-).
40, DMCVALID	DMCVALID-	DMC mode of transfer selected by external device
48, EVIM	FVIM+	Vectored interrupt mode (set by field #11=2, field #12 bit 54=1, bit 61=1 and RM15=1; reset by field #11=2 and either field #12=8 or bit 54=1 and bit 61=0 and RM15=0)
49, MC	FMCHK+	Machine check error detected
50, MCNOT	FMCHK-	Machine check error not detected
51, VERIFY	MCV + (PLUPN)	A Micro verification check requested
52, RXM	FRXM +	Restricted execution mode
53, DMTOUTNVAL		DMT output is not valid
54, DMTINNVAL		DMT input is not valid
55, NOTRF16		RF16 is not set this cycle requires a 280 ns clock
56, SPECIALVALID	DMCSPLVD	Special DMX mode (=00) selected by external device
41-47,	-	Reserved
57-63	-	Reserved

Figure 12A

Field #12: EMIT ACTION (for field #11 = 2)

Field #12*	EMIT Action
RCM 47-50 =	
0, NOP, (blank)	None
1, LOADSERIALINT	Load the Serial Interface: BD13-16 → FS0 1-4
2, JST	Replace BD01,02 with BB01, 02 in 16S mode; BD01 with BB01 in 32S or 32R mode; and make no replacements in 64R mode; In normal use as a JST, field #1=RF, Field #2=RM field #6=M, field #7=RP
3, MPYLOGIC	If Link=1, AL01-16 → BD01-16; if link=0, RF01-16 → BD01-16.
4, DIVLOGIC	If AL01 or FALMINUS =1, RF01-16 → BD01-16; if=0, AL01-16 → BD01-16
5,	Reserved
6, LOADCAM	RM01-16 → entry part of CAM; RY8-16 → Associative part of CAM
7, CLEARCAM	CAM forced to "no match" condition
8, CLRNVKEYS	Clear the non-visible keys (RXM, FSYSCLR, PAM and EINTM) if triggered by RCM54=1
9, PLOADVKEYS	BD01-08 → Visible keys if triggered by RCM56=1
10, SETFUII	1 → FUII (double word fetch cycle flag)
11, LOADFO1F02	BB01 → FO1 (indirect addressing); BB02 → FO2 (indexed addressing)
13	Reserved
14	Reserved
15	Reserved
RCM51-64	
51	Reserved
52	Reserved
53	Reserved
54, TRIGNVKEYS	Trigger non-visible keys (required for CLRNVKEYS & defines RCM57-64 as non-visible keys)
55	Reserved
56, TRIGVKEYS	Trigger visible keys (required for PLOADVKEYS & defines RCM52-64 as visible keys)

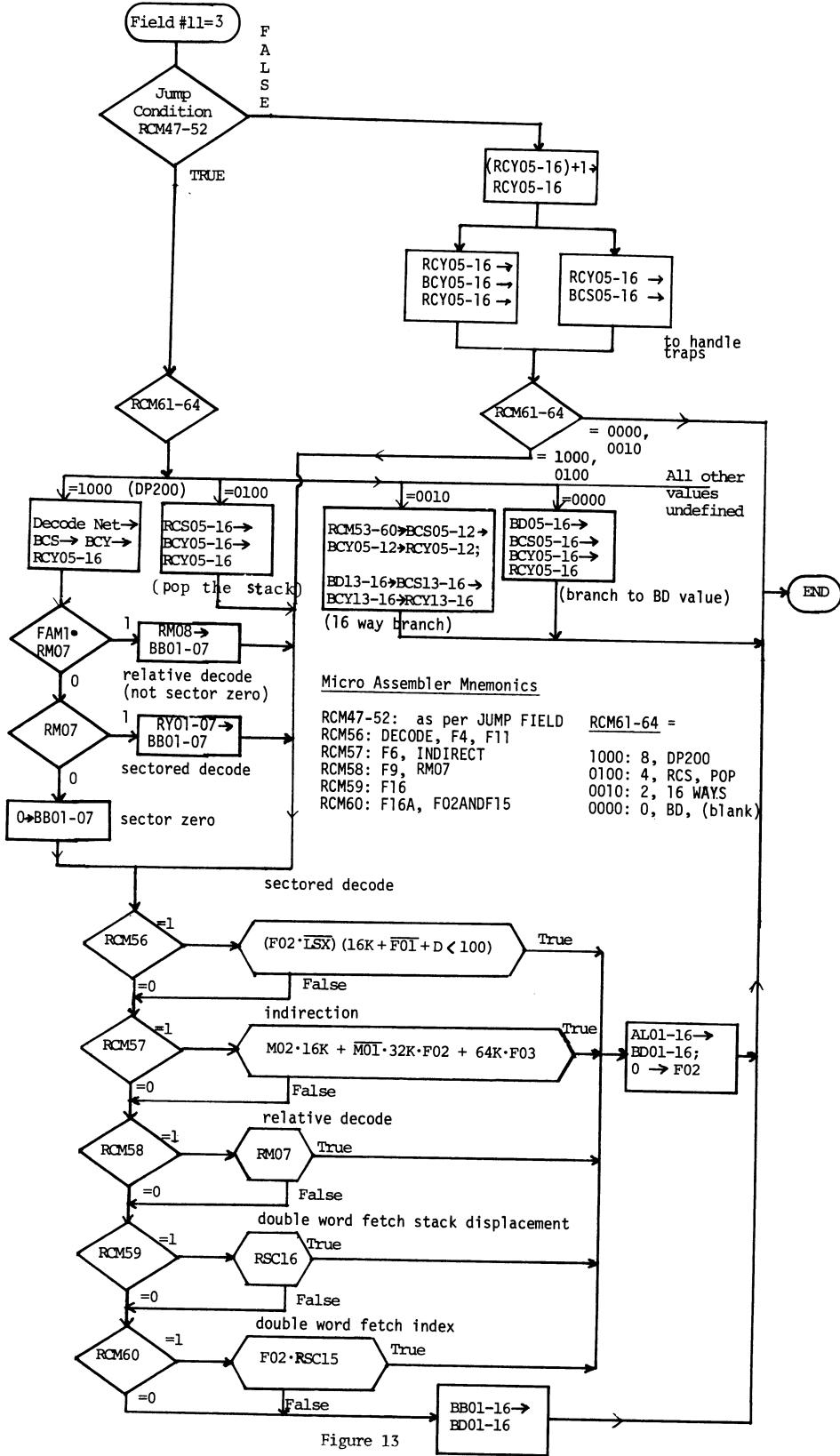
*Enclose multiple parameter of field #12 in parentheses

Figure 12B

EMIT ACTION (continued)

Field #12 RCM 57-64 (Visible Keys)	Enable conditions to update visible keys (if RCM56=1, TRIGVKEYS)			
	Condition	Condition set by	Condition reset by	
57	Spare			
58, DP	Double precision mode	RM15=1	RM15 = 0	
59	Spare			
60	Spare			
61, AM1	Address mode bit #1	RM07=1	RM07= 0	
62, AM2	Address mode bit #2	RM15=1	RM15=0	
	<u>AM1</u> <u>AM2</u> <u>Mode</u> 0 0 16S 0 1 32S 1 0 64R 1 1 32R			
63	Spare			
64	Spare			
Non Visible Keys	Enable conditions to update non-visible keys (if RCM 54=1, TRIGNVKEYS)			
57	Spare			
58	Spare			
59, PAM	Paged address mode	RM15=1	RM15=0	
60, EINTM	External interrupts	RM08=1	RM08=0	
61, VIM	Vector interrupt mode	RM15=1	RM15=0	
62, MCHK	Machine check mode	parity error	RM15=0	
63, PARIM	Parity error vector enabled	RM15=1	RM15=0	
64, RXM	Restricted execution mode	RCM64	CLRNVKEYS	

Field #12: JUMP STACK/FETCH LOGIC (for field #11 = 3)



APPENDIX B
MICROCODING MACROS

RR Macros

Format:

(Label) RR <1> = <2> <3> <4> etc.

Symbols:

Argument #	Definition	Symbols	Restriction
<1>	Source	Any BB source	
		Any Register in the Register File	No "indirect" Addressing
		(Blank), NULL	
<2>	Destination	RM, RY or	
		Any Register in the Register File	
		(Blank), NULL	
<3>	Independent Action	Same as field 10 of CPU	
<4>	Emit	Same as fields 11, 12 of CPU	
		Argument <2> may be ORed, i.e., (RM,RA) is legal.	

Special Symbols: (Optional)

= may be used to define RCM data fields, i.e., RCM = '17120 will put an OTA 1720 with proper parity on the D Bus.

C = may be used to define anything in CPU macro argument 9 (HSM + Carry)

APPENDIX B (cont)

TR = may be used to define anything in CPU macro argument 3 (trap control). Overrides normal RR selection of traps.

Examples:

```
RR      RCM    =  3412  =>  RA
RR      RM     => RB  NOP JUMP ON NE TO S12
RR      RA     => RY
```

ALU Macro

Format 1:

```
(Label) ALU <1> <2> <3> => <4> <5> <6> etc.
```

Symbols:

Argument #	Definition	Symbols	Restrictions
<1>	Argument 1	Any Register in the Register File	No "indirect" addressing
		Zero	Register File can't be destination
<2>	Operator	AND OR XOR NOR ADD PLUS SUB MINUS SUB1 MINUS1	Logical AND Logical OR Logical XOR Logical NOR 1 + 3 1 + 3 1 - 3 1 - 3 1 - 3 1 - 3 - 1
<3>	Argument 2	Any BB Source	

APPENDIX B (Cont)

ALU Macro

<4>	Destination	Same as RM, RY
		Any Register in the Register File
<5>	IAC	Same as field 10 of CPU
<6>	Emit	Same as CPU 11, 12

Special Symbols: (Optional)

= Same as RR

C = Same as RR

TR = Same as RR

+ Followed by CPU Field 5 symbol to force carry
in or logic select (normal ALU select for
field 5 is appropriate for command). "INC
RA + 0" is a way to get RA to the condition
code.

FLIP BYTES This selects the Byte swapped output of
the ALU.

Format 2:

(Label) ALU <1> <3> = <4> <5> <6> etc.

Symbols:

Argument #	Definition	Symbols	Restrictions
1	Operator	INC NOT DEC	Only for Registers
		CON	Argument 2 must be ZERO (or 0) or MINUS1 (or -1). Generates the constant

APPENDIX B (cont)

ALU Macro

Argument #	Definition	Symbols	Restrictions
<3>	Argument	Any BB source or Any Register in the Register File	
<4> to <6>		Same as Format 1 ALU 4 6	

Special Symbols: (Optional)

(All used for Format 1 apply)

Examples:

ALU RA PLUS RCM = 3412 = RA

ALU INC RM => RM SETCC JUMP ON NE TO S12

ALU RM MINUS ZERO =>RM

ALU RS PLUS RM =>(RS, RY)

ALU INC RA + 0=>NULL SETCC

APPENDIX C

PRIME 300 MICROCODE

(0001) * 5000,U-CODE,MHJ,FEBRUARY 1974
 (0002) * PRIME 300 MICRO-CODE
 (0003) * PRIME COMPUTER INC.,SRC0768.001
 (0004) * COPYRIGHT 1974,PRIME COMPUTER INC.,NATICK MASS.
 (0005) *
 000001 (0006) P300 xSET 1
 (0007) * MA,SRCLIB,MHJ,FEBRUARY 1974
 (0008) * PRIME MICRO-CODE ASSEMBLER
 (0009) * PRIME COMPUTER INC.,0702.002
 (0010) * COPYRIGHT 1974,PRIME COMPUTER INC.,NATICK MASS.
 (0011) *
 (0012) *
 (0013) * *****
 (0014) * *
 (0015) * *
 (0016) * *
 (0017) * *
 (0018) * *
 (0019) * *
 (0020) * *
 (0021) * *
 (0022) * *****
 (0023) *
 (0855) IDNT (PRIME 3000 MICRO-CODE),(JANUARY 2,1974);
 (0856) (FLOATING POINT),(IS INCLUDED)
 (0857) *
 (0858) *
 (0859) *
 (0860) * BEGIN FETCH CYCLE, TEST FOR NEED TO INTERRUPT PROCESSING
 (0861) *
 (0862) F1 RR RP => RY CLEARFUII;
 (0863) JUMP ON FETCH1 TO HALT
 000: 0200 780F 0004 A030
 (0864) *
 (0865) * INCREMENT P COUNTER, READ INSTRUCTION
 (0866) *
 (0867) F3 CPU AL 0 ALL INC 1 M RP;
 (0868) CLMCLFCLI MREAD , ;
 (0869) JUMP ON REL TO F9
 001: 8304 7F84 0004 0004
 (0870) *
 (0871) * SECTORED DECODE, BUILD EA WITH PRE-INDEXING IF NEEDED
 (0872) *
 (0873) F4 CPU BB RM NONE ADD 0 XM 0 ;
 (0874) RY280 NOP EAF;
 (0875) S FETCHDONE TO DP200 DECODE
 002: EC61 0E0D 0000 3108
 (0876) *
 (0877) * INDIRECTION REQUIRED
 (0878) *
 (0879) F5 CPU 0 0 ALL 0 0 0 0 ;
 (0880) RMMRDY MREAD NOP;
 (0881) GO TO F6
 003: 0300 0784 0004 0010
 (0882) *
 (0883) * RELATIVE DECODE, BUILD RELATIVE EA
 (0884) *
 (0885) F9 CPU BB RM NONE ADD 0 M RP ;
 (0886) RY280 NOP EAF;
 (0887) S FETCHDONE TO DP200 RM07
 004: EC60 7E0D 0000 3048
 (0888) *
 (0889) * TEST FOR DOUBLE WORD OR STACK OPERATION
 (0890) *
 (0891) F10 RR , NOP ;
 (0892) JUMP ON RMLTM240 TO F13
 005: 0200 0004 0006 2008
 (0893) *
 (0894) * PRE-INDEX FOR RELATIVE MODE
 (0895) *
 (0896) F11 CPU BB RY ALL ADD 0 XM 0 ;
 (0897) RY240 NOP EAF;
 (0898) S FETCHDONE TO POP F11
 006: EB61 0300 0000 3104
 (0899) *
 (0900) * INDIRECTION REQUIRED
 (0901) *
 (0902) F12 CPU 0 0 ALL 0 0 0 0 ;
 (0903) RMMRDY MREAD NOP;
 (0904) GO TO F6
 007: 0300 0784 0004 0010
 (0905) *
 (0906) F13 RR RP => RY NOP TR= ALL ;
 (0907) JUMP ON STACKOP TO F17
 008: 0300 7804 0005 0000
 (0908) *
 (0909) * SECOND OPERAND FETCH
 (0910) *
 (0911) F14 CPU AL 0 ALL INC 1 M RP ;
 (0912) RMPFMRDY MREAD EAF;
 (0913) EAC SETFUII
 009: 8304 758D 000A 8000
 (0914) *
 (0915) * DOUBLE STACK INDEX, IF REQUIRED
 (0916) *
 (0917) F16 CPU BB RM ALL ADD 0 M RS ;
 (0918) RY240 NOP EAF;
 (0919) S RELDONE TO POP F16
 00A: EF60 3300 000D 1024
 (0920) *

(0921) * DOUBLE INDEX ON RX, IF REQUIRED
 (0922) *
 (0923) F16A CPU BB RY ALL ADD 0 XM 0 ;
 (0924) RY240 NOP EAF ;
 (0925) S FETCHOONE TO POP F16A
 008: E861 030D 000D 3014
 (0926) *
 (0927) * DOUBLE INDIRECT
 (0928) *
 (0929) F16B CPU 0 0 ALL 0 0 0 0 ;
 (0930) RMMRDY MREAD NOP ;
 (0931) GO TO F6
 00C: 0300 0784 0004 0010
 (0932) *
 (0933) * STACK OPERATION PROCESSING
 (0934) *
 (0935) F17 RR RS => RY NOP ;
 (0936) JUMP ON PUSH TO F19
 00D: 0200 3804 0005 2014
 (0937) *
 (0938) * PRE-DECREMENT OR POP PROCESSING
 (0939) *
 (0940) F18 CPU AL 0 ALL INC 1 M RS ;
 (0941) RF200 NOP EAF ;
 (0942) S ON RELDONE, POP
 00E: 8304 3A0D 000D 1004
 (0943) F18A CPU ,,,ALL,,,RMMRDY MREAD
 00F: 0300 0784 0000 0000
 (0944) *
 (0945) * INDIRECTION AND POST INDEXING
 (0946) *
 (0947) F6 CPU RF RCM NONE 0 0 M RA ;
 (0948) RF160 ,LOADRSC DATA -8
 010: 1000 190E 0003 FEF8
 (0949) F6A CPU BB RM NX ADD 0 XM 0 ;
 (0950) RY240 NOP EAF ;
 (0951) S INDIRECTEND TO POP INDIRECT
 011: EE61 0300 000C E084
 (0952) * MULTIPLE LEVELS OF INDIRECTION
 (0953) *
 (0954) *
 (0955) F7 CPU 0 0 ALL 0 0 0 0 ;
 (0956) RMMRDY MREAD INCRSC ;
 (0957) JUMP ON RSCNEM1 TO F6A
 012: 0300 0785 0004 9011
 (0958) F7A RR ,,REST GO TO F6A
 013: 0200 0006 0004 0011
 (0959) *
 (0960) * POST-INCREMENT STACK OP---PUSH
 (0961) *
 (0962) F19 CPU AL 0 ALL DEC 0 M RS ;
 (0963) RYRF240 NOP EAF ;
 (0964) S ON RELDONE TO POP
 014: 83F0 3DU0 000D 1004
 (0965) *
 (0966) * INDIRECT PUSH
 (0967) *
 (0968) F20 CPU 0 0 ALL 0 0 0 0 ;
 (0969) RMMRDY MREAD NOP ;
 (0970) GO TO F6
 015: 0300 0784 0004 0010
 (0971) EJCT

(0972) *
 (0973) * EXTERNAL INTERRUPT
 (0974) *
 (0975) INT3 RP ,CLEARFUII JUMP ON FUII TO INT3
 016: 0200 000F 0005 5016
 (0976) CPU BB BPA NX 0 0 0 0 ;
 (0977) RY280 NOP NOP ;
 (0978) JUMP ON BPSP1 TO MI1
 017: F600 0E04 0004 305F
 (0979) ALU CON ZERO => RM TR= NONE ,JUMP ON FVIM TO NVECT
 018: 803C 0204 0007 001A
 (0980) CPU BB RCM NONE 0 0 RY ICAI ;
 (0981) RY200 ,, DATA '63
 019: F002 8804 0002 0153
 (0982) NVECT CPU ,ALL,,,RY,ICPN,RMMRDY AREAD,,;
 (0983) MUDAL CLRNVKEYS (TRIGNVKEYS,EINTM)
 01A: 0302 47C4 000A 0410
 (0984) CPU AL RM NONE BB L 0 0 ;
 (0985) RY240 , SETCC GO TO AVECT+2
 01B: 8C5C 0307 0004 0079
 (0986) *
 (0987) * MEMORY INCREMENT. THE LOCATION SPECIFIED BY THE BPA IS
 (0988) * READ AND THEN INCREMENTED. AFTER THIS, IT IS WRITTEN
 (0989) * BACK. IF IT INCREMENTED TO 0, END OF BLOCK IS GENERATED
 (0990) * ALONG WITH ICPN. IF NOT, END OF BLOCK (BPCEOB) IS
 (0991) * GENERATED AS ZERO. BPCEOB = CARRY OUT OF BIT 1 OF THE ALU.
 (0992) *
 (0993) M12 ALU INC RM => RM SETCC
 01C: 8E65 1207 0000 0000
 (0994) RR ,C= AWRITE , JUMP ON NE TO **2
 01D: 0200 00F4 0004 401F
 (0995) CPU 0 RM 1 MINUS1 1 RY ICPN ;
 (0996) 280 , , GO TO CP8
 01E: 0DC6 4604 0004 0020
 (0997) CPU 0 RM 1 MINUS1 0 RY ICPN ;
 (0998) 280 , , GO TO CP8
 01F: 0DC2 4604 0004 0020
 (0999) EJCT
 (1000) * BEGIN PROCESSING THE FUNCTIONS
 (1001) *
 (1002) *
 (1003) ORG \$20
 (1004) * 1 STOP/STEP (OTHERS FOLLOW IN SEQUENCE)
 (1005) *
 (1006) CP8 RR RP => RY NOP TR= ALL ;
 (1007) GO TO F3
 020: 0300 7804 0004 0001
 (1008) CP9 RR YSAVE => RY NOP ;
 (1009) GO TO CP1
 021: 0200 C804 0004 0035
 (1010) CP10 ALU INC YSAVE => YSAVE , ;
 (1011) JUMP ON LT TO CP9
 022: 8204 CA04 0005 6021
 (1012) CP11 RR YSAVE => RY , GO TO CP19
 023: 0200 C804 0004 002C
 (1013) CP12 RR RA => RM , GO TO BOOT
 024: 0200 1204 0004 0091
 (1014) *
 (1015) * CLEAR THE ACTIVE REGISTER. BIT 1 CLEARS THE DATA.
 (1016) *
 (1017) CP13 CPU AL 0 NX ZERO L RSC 0 ;
 (1018) 280 NOP SETCC ;
 (1019) JUMP ON LT TO CP15
 025: 823F 0607 0005 6027
 (1020) *
 (1021) * ADDRESS CHANGES THE RSC ADDRESSED REGISTER FROM
 (1022) * MSAVE TO YSAVE.
 (1023) *
 (1024) CP14 CPU BB RCM NX 0 0 RSC 0 ;
 (1025) 200 NOP LOADRSC ;
 (1026) DATA \$C
 026: F203 000E 0002 010C
 (1027) *
 (1028) * THE SAVED REGISTER SELECTED IS OUTPUT TO THE LIGHTS,
 (1029) * THEN THE DATA SWITCHES ARE ORDERED INTO IT.
 (1030) *
 (1031) CP15 CPU RF 0 NX , RSC DATA RM200
 027: 0203 2204 0000 0000
 (1032) CP16 CPU 0 0 NX 0 0 RSC (DATA,STROBE) ;
 (1033) 280
 028: 0203 4604 0000 0000
 (1034) CPU BB RCM NX 0 0 RSC 0 ;
 (1035) RY200 ,,DATA '131720
 029: F203 0804 0001 6600
 (1036) CP17 CPU AL BPD NX OR L RSC 0 RF280 , ;
 (1037) ,JUMP ON NE TO CP3
 02A: 9A4F 0C04 0004 4037
 (1038) CP18 CPU AL 0 NX ZERO L RSC 0 ;

```

(1039)          RF280    ,, GO TO CP3
02B: 823F 0C04 0004 0037
(1040) CP19   CPU    RF  0    NX  0    0    M    MSAVE ;
(1041)          RM280   AWRITE ,GO TO CP3
02C: 0200 D4F4 0004 0037
(1042)          EJCT
(1043) *
(1044) *      TEST FOR CONTROL PANEL REQUEST, IF NOT, DO EXTERNAL INT.
(1045) *
(1046) FHALT3 RR    ,, TR= ALL ,JUMP ON CP TO CP1
02D: 0300 0004 0004 C035
(1047) *
(1048) *      EXTERNAL INTERRUPT PROCESSING.
(1049) * IENB IS VALID FOR THE THIRD STEP.
(1050) * IENB BEGINS 480 NS EARLIER AT THE START
(1051) * OF THE SECOND CYCLE. BPSPI IS TESTED, IF TRUE
(1052) * A MEMORY INCREMENT OPERATION IS PERFORMED. IF FALSE, AN
(1053) * EXTERNAL INTERRUPT IS TAKEN. THE VECTOR ADDRESS IS TAKEN
(1054) * FROM BPA IN VECTORED MODE, AND GENERATED AS '63
(1055) * IF IN COMPATIBLE MODE.
(1056) *
(1057) INTEX  CPU    0    0    NX  0    0    RY    IEN ;
(1058)          200 NOP NOP ;
(1059)          EAC SETFUII
02E: 0202 2004 0004 8000
(1060)          CPU    0    0    NX  0    0    RY    IEN ;
(1061)          280 NOP NOP GO TO INT3
02F: 0202 2604 0004 0016
(1062)          EJCT
(1063) *
(1064) *
(1065) *      HALTED FETCH CYCLE, FIND WHAT NEEDS PROCESSING
(1066) *
(1067) *
(1068) *      MASTER CLEAR INVERSE TEST
(1069) *
(1070) FHALT  RR    ,, TR= ALL JUMP ON SYSCLRNOT TO FHALT2
030: 0300 0004 0004 8074
(1071) *
(1072) *      MASTER CLEAR ROUTINE CLEARS CARRY, MODALS, AND REGISTERS
(1073) *      0 TO '37. '1000 IS PUT INTO THE P COUNTER, AND THE CONTROL
(1074) *      PANEL ROUTINE WHICH FOLLOWS READS '1000 INTO THE LIGHTS.
(1075) *
(1076) *
(1077) MC1   RR    RCM = '1000 => RY    C= BD01    LOADRSC
031: F200 083E 0000 0500
(1078) MC2   CPU    AL  0    NX  ZERO L    RSC  0 ;
(1079)          RF280   NOP INCRSC ;
(1080)          JUMP ON RSCNEM1 TO *
032: 823F 0C05 0004 9032
(1081) MC3   CPU    AL  0    NX  ZERO L    0    0 ;
(1082)          RM200   NOP CLEARFUII ;
(1083)          JUMP ON VERIFY TO VIRY1
033: 823C 020F 0007 30C4
(1084) MC4   CPU    BB  RY  NX  0    0    M    RP ;
(1085)          RF280   NOP NOP ;
(1086)          EAC CLRNVKEYS (54,56,58,59,60,61,62,63)
034: EA00 7C04 000A 057E
(1087)          EJCT

```

```

(1088) *
(1089) *
(1090) * CONTROL PANEL ROUTINE. THIS PROGRAM FIRST READS THE
(1091) * FUNCTION SWITCHES (INA 1520). THE INFORMATION IS
(1092) * ENCODED IN THE LOW ORDER FOUR BITS OF THE WORD AND THE
(1093) * SIGN BIT. A SIXTEEN WAY BRANCH IS THEN DONE WITH THE
(1094) * FIRST 8 BRANCHES DEFINED AS FOLLOWS
(1095) *      1 RUN OR STOP STEP
(1096) *      2 FETCH THIS
(1097) *      3 FETCH OR STORE NEXT (BIT 1 IS SET FOR FETCH NEXT)
(1098) *      4 STORE THIS
(1099) *      5 AUTO LOAD
(1100) *      6 CLEAR ADDRESS OR DATA (BIT 1 IS SET FOR DATA)
(1101) *      7 ADDRESS (NO SPECIAL FUNCTION--LIGHTS = ADDRESS)
(1102) *      8 DATA (NO SPECIAL FUNCTION--LIGHTS = ADDRESS)
(1103) *
(1104) *
(1105) * REGISTERS YSAVE AND MSAVE HOLD THE WORKING
(1106) * COPIES OF THE ADDRESS AND DATA LIGHTS, RESPECTIVELY. THESE
(1107) * ARE UPDATED EACH TIME THROUGH THE LOOP AND DISPLAYED ON THE
(1108) * NEXT PASS. INA 1720 IS USED TO READ THE DATA SWITCHES AND
(1109) * OR THEM INTO THE SAVED REGISTERS. OTA 1720 IS THEN USED TO
(1110) * DUMP OUT THE OLD IMAGE.
(1111) *
(1112) *
(1113) *
(1114) CP1 CPU BB RY NX 0 0 M YSAVE ;
(1115) 035: EA00 C5C4 0000 0000
(1116) CP2 RR RM => MSAVE TR= NX
036: EE00 DA04 0000 0000
(1117) CP3 RR RCM = '131520 => RY INA FUNCTION
037: F200 0804 0001 6750
(1118) CP4 CPU BB RCM NX 0 0 RY PIO ;
(1119) 280 NOP LOADRSC ;
(1120) DATA $D
038: F202 160E 0002 0000
(1121) CP5 CPU BB BPD NX 0 0 RSC STROBE ;
(1122) RM280 FUNCTION SWITCH TO RM
039: FA03 8404 0000 0000
(1123) CP6 CPU BB RCM NONE 0 0 RSC 0 ;
(1124) RY200 ,,DATA '171720
03A: F003 0804 0003 E600
(1125) CP7 CPU AL RM NONE BR L RSC 0 ;
(1126) RM280 NOP SETCC ;
(1127) S ON TRUE 16WAYS TO CP8
03B: 8C5F 0407 000C 0022
(1128) *
(1129) * REGISTER SAVE FOR DMX ROUTINE.
(1130) *
(1131) DMX2 RR RY => YSAVE
03C: E800 C904 0000 0000
(1132) CPU AL RSC NX BB L M RSCSAVE ;
(1133) RF200 ,,JUMP ON DMXNOTVALID TO DMA
03D: 865C EA04 0005 F048
(1134) EJCT

```

(1135) *
 (1136) * DMT. HIGHEST SPEED OF ALL TRANSFERS, THE PERIPHERAL
 (1137) * ADDRESS LINES ARE READ INTO RY AND DIRECTLY SELECT THE
 (1138) * MEMORY LOCATION TO BE USED. INPUT OR OUTPUT TRANSFER
 (1139) * IS DETERMINED BY TESTING THE INPUT/OUTPUT LINE AS IS
 (1140) * TRUE OF ALL DMX. THE SIGNALS GENERATED ARE THE SAME
 (1141) * AS FOR DMA EXCEPT THAT THE END OF RANGE SIGNAL IS UN=
 (1142) * DEFINED FOR THIS TRANSFER TYPE. THIS MEANS THE CONTROL-
 (1143) * ER DETERMINES IF THE TRANSFER ENDS THE BLOCK.
 (1144) *
 (1145) *
 (1146) DMT CPU BB BPA NX 0 0 RSC (CPN,STROBE) ;
 (1147) RY200 0 LOAD256K ;
 (1148) JUMP ON OUTPUT TO TOUT1
 03E: F603 C808 0006 5046
 (1149) CPU ,,,,RSC STROBE ,,,GO TO TIN1
 03F: 0203 8004 0004 0042
 (1150) *
 (1151) * CYCLE TO CYCLE FULLY OVERLAPPED DMT INPUT LOOP.
 (1152) * NOTE THAT THE STROBE HAS ALREADY BEGUN BEFORE
 (1153) * THE CYCLE CAN EXIT. THIS FORCES ALL OF THE OTHER
 (1154) * ALGORITHMS TO BE WRITTEN WITH STROBE ALWAYS EN-
 (1155) * ABLED.
 (1156) *
 (1157) TIN CPU ,,,,RSC CPN
 040: 0203 4004 0000 0000
 (1158) CPU BB BPA NX 0 0 RSC STROBE ;
 (1159) RY200 NOP LOAD256K ;
 (1160) JUMP ON DMTINNVAL TO TEXIT
 041: F603 8808 0007 604A
 (1161) TIN1 CPU BB BPD NX 0 0 RSC (ENB,STROBE) ;
 (1162) RM280 AWRITE NOP ;
 (1163) GO TO TIN
 042: FA03 94F4 0004 0040
 (1164) *
 (1165) * DMT OUTPUT LOOP.
 (1166) *
 (1167) TOUT CPU 0 0 NX 0 0 RSC (STROBE,DATA) ;
 (1168) RMMRDY
 043: 0203 A704 0000 0000
 (1169) CPU BB BPA NX 0 0 RSC (CPN,DATA) ;
 (1170) RY240 NOP LOAD256K ;
 (1171) JUMP ON DMTOUYNVAL TO TEXIT
 044: F603 6308 0007 504A
 (1172) CPU RF 0 NONE 0 0 RSC STROBE ;
 (1173) RF160
 045: 0003 8904 0000 0000
 (1174) TOUT1 CPU 0 0 NX 0 0 RSC (ENB,STROBE) ;
 (1175) 280 AREAD NOP ;
 046: 0203 96C4 0004 0043
 (1177) EJCT
 (1178) * THIS CODE TRANSFERS CONTROL FROM ONE MODE OF DMX
 (1179) * TRANSFER TO ANOTHER OR RESUMES NORMAL USER LEVEL CODE
 (1180) * EXECUTION.
 (1181) *
 (1182) DMA1 CPU RF 0 NX 0 0 RSC (DATA,CPN) ;
 (1183) RF240 NOP NOP ;
 (1184) JUMP ON DMXSTATREQ TO REST
 047: 0203 6804 0005 0059
 (1185) *
 (1186) * START OF DMC LOOP
 (1187) *
 (1188) DMC CPU BB BPA NX 0 0 RSC STROBE ;
 (1189) RY200 NOP NOP ;
 (1190) JUMP ON DMCVALID TO DMC1
 048: F603 8804 0006 805C
 (1191) CPU ,,,,RSC STROBE ,,,JUMP ON DMANOTVALID TO DMT
 049: 0203 8004 0005 E03E
 (1192) TEXIT CPU ,,,,RSC STROBE ,,,JUMP ON DMXSTATREQ TO REST
 04A: 0203 8004 0005 D059
 (1193) *
 (1194) *
 (1195) * DMA. THE ADDRESS LINES ARE READ INTO THE SHIFT COUNTER.
 (1196) * THIS DIRECTLY SELECTS THE FIRST DMA REGISTER. IT IS INCRE-
 (1197) * MENTED BY \$10 AND TESTED TO SEE IF ZERO IS CROSSED BY THE
 (1198) * END OF BLOCK SIGNAL. THE SECOND REGISTER IS ACCESSED AND AN
 (1199) * INPUT OR OUTPUT TRANSFER IS BEGUN TO THE LOCATION READ. A
 (1200) * BPCENB IS GENERATED BEFORE THE COMPLETION OF THE TRANSFER TO
 (1201) * DETECT CONSECUTIVE TRANSFERS. IF CONSECUTIVE, LOOP BACK,
 (1202) * IF NOT, EXIT.
 (1203) *
 (1204) *
 (1205) DMA CPU 0 BPA NX 0 0 RSC STROBE ;
 (1206) 200 NOP LOADRSC ;
 (1207) JUMP ON DMANOTVALID TO DMC
 04B: 1603 800E 0005 E048
 (1208) CPU AL RCM NX ADD 0 RSC (STROBE,CPN) ;
 (1209) RYRF240 NOP INCRSC ;
 (1210) DATA \$10
 04C: 9263 C005 0002 0010
 (1211) CPU RF 0 NX 0 0 RSC STROBE ;
 (1212) RY200 NOP LOAD256K ;
 (1213) JUMP ON OUTPUT TO DOUT1
 04D: 0203 8808 0006 5058
 (1214) CPU BB BPD NONE 0 0 RSC (ENB,STROBE) ;
 (1215) RM280 AWRITE NOP ;
 (1216) GO TO DIN
 04E: F803 94F4 0004 004F
 (1217) * CYCLE TO CYCLE, FULLY OVERLAPPED DMA INPUT ROUTINE.
 (1218) *
 (1219) *

	(1220) DIN	CPU	AL 0 NX INC 1 RSC 0 ;
	(1221) RF200		
04F: 8207 0A04 0000 0000	(1222) RR	BPA => ,LOADRSC, JUMP ON DMANOTVALID TO DMA1	
	(1223) CPU	AL RCM NX ADD 0 RSC (CPN,STROBE) ;	
	(1224) RYRF240 NOP INCRSC ;		
	(1225) DATA \$10		
050: F600 000E 0005 E047	(1226) CPU	RF 0 NX 0 0 RSC STROBE ;	
	(1227) RY200 NOP LOAD256K ;		
	(1228) JUMP ON OUTPUT TO DOUT1		
051: 9263 C005 0002 0010	(1229) DIN1 CPU	BB BPD NONE 0 0 RSC (ENB,STROBE) ;	
	(1230) RM280 AWRITE NOP ;		
	(1231) GO TO DIN		
052: 0203 8808 0006 5058	(1232) *	DMA CYCLE-CYCLE OUTPUT ROUTINE.	
	(1233) *		
	(1234) *		
053: F803 94F4 0004 004F	(1235) DOUT CPU	RF ,NONE,,RSC STROBE RF160	
	(1236) CPU	0 BPA NX 0 0 RSC (STROBE,DATA) ;	
	(1237) RMMRDY NOP LOADRSC ;		
	(1238) JUMP ON DMANOTVALID TO DMA1		
054: 0003 8904 0000 0000	(1239) CPU	AL RCM NX ADD 0 RSC (CPN,DATA) ;	
	(1240) RYRF240 NOP INCRSC ;		
	(1241) DATA \$10		
055: 1603 A70E 0005 E047	(1242) CPU	RF 0 NX 0 0 RSC STROBE ;	
	(1243) RY200 NOP LOAD256K ;		
	(1244) JUMP ON INPUT TO DIN1		
056: 9263 6D05 0002 0010	(1245) DOUT1 CPU	AL 0 NONE INC 1 RSC (STROBE,ENB) ;	
	(1246) RF280 AREAD NOP ;		
	(1247) GO TO DOUT		
057: 0203 8808 0004 5053	(1248) EJCT		
	(1249) *	RESTORE ROUTINE. RETURN TO NORMAL PROCESSING.	
	(1250) *		
	(1251) *		
058: 8007 9CC4 0004 0054	(1252) REST RR	YSAVE => RY	
	(1253) RR	RSCSAVE => RM	
059: 0200 C804 0000 0000	(1254) CPU	RF RM ALL 0 0 M MSAVE ;	
	(1255) RM280 NOP LOADRSC ;		
	(1256) S ON TRUE, POP		
05A: 0000 E104 0000 0000	(1257) *	DMC. SLOWEST OF ALL THE TRANSFERS, DMC HAS AS ITS VIRTUE	
	(1258) *	THE CAPABILITY OF USING ANY OF THE FIRST 64K MAIN	
	(1259) * MEMORY LOCATIONS AS A CHANNEL. IDENTICAL IN FUNCTION		
	(1260) * TO DMA, THE TWO LOCATIONS MAKING UP A CHANNEL CONTAIN		
	(1261) * THE CURRENT AND ENDING MEMORY ADDRESSES, AND MUST BE ACCESSED		
	(1262) * TESTED AND UPDATED EACH CYCLE.		
	(1263) *		
	(1264) *		
	(1265) *		
	(1266) DMC1 CPU	0 RCM NX 0 0 RSC STROBE ;	
	(1267) RMMRDY AREAD LOADRSC ;		
	(1268) DATA '17		
05C: 1203 87CE 0002 010F	(1269) CPU	BB RCM NX 0 0 RSC STROBE ;	
	(1270) RF200 NOP NOP ;		
	(1271) DATA 1		
05D: F203 8A04 0002 0001	(1272) CPU	AL RM NX ADD 0 RSC STROBE ;	
	(1273) RM280 AWRITE		
05E: 8E63 84F4 0000 0000	(1274) CPU	AL RY NX ADD 0 RSC STROBE ;	
	(1275) RY240 ,GO TO DMC3		
05F: 8A63 8304 0004 0086	(1276) EJCT		

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(1277)      ORG      $60
(1278) *
(1279) *
(1280) *      TRAP ENTRY POINTS. EVERY OTHER LOCATION FROM HERE TO
(1281) * $7E IS A POTENTIAL TRAP ENTRY POINT. THOSE LOCATIONS
(1282) * WHERE TRAPS ARE NOT IMPLEMENTED ARE AVAILABLE FOR OTHER
(1283) * CODING. PRIORITY IS FROM 6F TO 60, THEN FROM
(1284) * 7F TO 70. THEREFORE MISSING MEMORY MODULE IS HIGHEST
(1285) * PRIORITY, AND DMA IS LOWEST.
(1286) *
(1287) *
(1288) *
(1289) *      FETCH PAGE TRAP.
(1290) *
(1291) FPAGE   CPU      BB RCM NONE ,,,280      ,PUSHBD ;
(1292)          DATA FPAGE3
060: F000 060C 0002 008A
(1293)      RR      RY => YSAVE TR= NONE , GO TO PAGE+1
061: E800 CA04 0004 007D
(1294) *
(1295) *      WRITE ADDRESS TRAP
(1296) *
(1297) WRITE   CPU      BB RM 1      ,,RY 0      RF240 ;
(1298)          ,,S ON TRUE, POP
062: EDU2 0804 000C 0004
(1299) PAGE3  CPU      AL RM NONE BB L      M      17 ;
(1300)          RMRFRMDY AREAD FORCED ;
(1301)          GU TO PAGE4
063: 8C5C F5C9 0004 0080
(1302) *
(1303) *      READ ADDRESS TRAP
(1304) *
(1305) READ    CPU      RF 0      1      ,,RY 0      RM280 ;
(1306)          ,,S ON TRUE, POP
064: 0102 0404 000C 0004
(1307)      ORG      $60
(1308) *
(1309) *      FETCH READ ADDRESS TRAP
(1310) *
(1311) FREAD   CPU      RF 0      1      ,,RY 0      RM200 ;
(1312)          ,,EAC LOADFO1F02
066: 0102 0204 000A C000
(1313)      CPU      RF,,1,,,M,0,RF240,,S ON TRUE, POP
067: 0100 0804 000C 0004
(1314) *
(1315) *      RESTRICT EXECUTION MODE TRAP. THOSE INSTRUCTIONS WHICH
(1316) *
(1317) *      ARE RESTRICTED FORCE THIS TRAP IF THE MODE IS ENABLED.
(1318) *
(1319) RXM     RR      RCM = '62 => RY TR= NONE
068: F000 0804 0002 0032
(1320)      CPU      ,,NONE,,,RMMRDY,AREAD,,GO TO AVECT1
069: 0000 07C4 0004 0077
(1321) *
(1322) *      CENTRAL PROCESSOR PARITY .
(1323) *
(1324) CPPAR   ALU      CON 0 => RM  CLEARFUII TR= NONE JUMP ON VERIFY TO VIRY1
06A: 803C 020F 0007 30C4
(1325)      RR      RP => RY TR= NONE , GO TO MC4
06B: 0000 7804 0004 0034
(1326)      ORG      $6C
(1327) *
(1328) *      MEMORY PARITY ERROR
(1329) *
(1330) MEMPAR  RR      RCM = '67 => RY TR= NONE
06C: F000 0804 0002 0037
(1331)      ALU      CON 0 => RM TR= 1 , GO TO MEMP3
06D: 813C 0204 0004 008C
(1332) *
(1333) *      MISSING MEMORY MODULE
(1334) *
(1335) MMOD    RR      RCM = '71 => RY TR= NONE
06E: F000 0804 0002 0159
(1336)      RR      ,,TR= NONE ,GO TO MEMPAR+1
06F: 0000 0004 0004 0060
(1337) *
(1338) *      DMX INSTRUCTION INTERRUPT ENTRY POINT
(1339) *
(1340) DMX1    RR      RM => MSAVE TR= NX
070: EE00 DA04 0000 0000
(1341)      CPU      ,,NONE,,,RSC ENB 280 ,,GO TO DMX2
071: 0003 1604 0004 003C
(1342) *
(1343) *      PAGE WRITE PROTECT VIOLATION
(1344) *
(1345) WRITEP  RR      RCM = '73 => RY TR= 1
072: F100 0804 0002 0038
(1346)      CPU      ,,NONE,,,RMMRDY,AREAD,,GO TO AVECT1
073: 0000 07C4 0004 0077
(1347) *
(1348) *      POWER FAILURE INTERRUPT
(1349) *
(1350) FHALT2 ALU      CON ZERO => RM ,JUMP ON PFLNOT TO FHALT3
074: 823C 0204 0005 9020
(1351) PFL    RR      RCM = '60 => RY TR= NONE
075: F000 0804 0002 0130
(1352)      CPU      AL 0      NONE INC 1      M      RP ;
(1353)          RMRFRMDY AREAD NOP ;
(1354)          EAC CLRPFWFL (TRIGNVKEYS,EINTM)
076: 8004 75C4 0008 0410

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(1355) *
 (1356) * ABSOLUTE VECTOR --- THE FIRST ENTRY ALSO BACKS THE
 (1357) * PROGRAM COUNTER UP BEFORE VECTORTING. THE LOCATION IS
 (1358) * READ. IF ZERO, THE PROCESSER HALTS, IF NOT, A JST TO THE
 (1359) * LOCATION READ IS DONE. NOTE THAT THE ADDRESS IS
 (1360) * INTERPRETED AS AN ABSOLUTE 64K POINTER, NO INDEXING OR
 (1361) * INDIRECTION.
 (1362) *
 000167 (1363) AVECT EQU *
 (1364) AVECT1 ALU DEC RP => RP TR= 1 CLEARFUII ;
 (1365) JUMP ON FUII TO *
 077: 81F0 740F 0005 5077
 (1366) CPU AL RM NONE BB L ,,RY240 ,SETCC ;
 (1367) EAC CLRNVKYES TRIGNVKEYS
 078: 8C5C 0307 0004 0400
 (1368) RR RP => RM TR= ALL , ;
 (1369) JUMP ON EQ TO CPI
 079: 0300 7204 0006 4035
 (1370) RR RY => RP C= AWRITE TR= ALL ,GO TO CASS
 07A: EB00 7AF4 0004 01E5
 (1371) *
 (1372) * PAGE TRAP . PROCESS TO UPDATE CAM IF POSSIBLE
 (1373) * AND CONTINUE THE INSTRUCTION, IF NO PAGE IN MEMORY
 (1374) * BACK UP THE P-COUNTER , AND PAGE FAULT INTERRUPT.
 (1375) *
 (1376) ORG \$7C
 (1377) PAGE RK RY => YSAVE
 07C: EB00 C904 0000 0000
 (1378) ALU PMAR OR RY => RY TR= 0 FLIP BYTES DISABLERHBB ;
 (1379) GO TO PAGE3
 07D: 684C B30B 0004 0063
 (1380) *
 (1381) * POST PROCESSING OF CENTRAL PROCESSOR PARITY ERROR
 (1382) * AFTER MICROVERIFY HAS SUCESSFULLY BEEN EXECUTED.
 (1383) *
 (1384) CPPAR3 RR RCM = '70 => RY TR= NONE
 07E: F000 0804 0002 0038
 (1385) CPU ,,NONE,,,RMMRDY,AREAD,,GO TO AVECT+1
 07F: 0000 07C4 0004 0078
 (1386) PAGE4 RR YSAVE => RY TR= NONE , ;
 (1387) JUMP ON RM01NOT TO PAGE7
 080: 0000 C804 0006 1083
 (1388) CPU RF 0 0 0 0 M 17 ;
 (1389) RM280 ,,EAC LOADCAM
 081: 0000 F404 0009 8000
 (1390) CPU ,,ALL ,,,RMMRDY MWRITE ;
 (1391) HSMRESUME S ON TRUE,POP
 082: 0300 07BA 000C 0004
 (1392) PAGE7 RR RY => EAS TR= 1
 083: E900 AA04 0000 0000
 (1393) RR RCM = '64 => RY TR= 1
 084: F100 0804 0002 0034
 (1394) CPU ,,NONE,,,RMMRDY,AREAD,,GO TO AVECT1
 085: 0000 07C4 0004 0077
 (1395) *
 (1396) * DMC EXECUTION
 (1397) *
 (1398) DMC3 CPU BB RM NX 0 0 RSC STROBE ;
 (1399) RMRFRDY AREAD
 086: EE03 85C4 0000 0000
 (1400) CPU RF RM NX SUB 0 RSC (CPN,STROBE) ;
 (1401) RY240 ,,JUMP ON INPUT TO DMC2
 087: 0E93 C304 0004 5089
 (1402) CPU AL,,NX,DEC,U,RSC (STROBE) RY240 ;
 (1403) ,,GO TO DOUT1
 088: 82F3 8304 0004 0058
 (1404) DMC2 CPU AL 0 NX DEC 0 RSC STROBE ;
 (1405) RY240 ,,GO TO DIN1
 089: 82F3 8304 0004 0053
 (1406) *
 (1407) * FETCH PAGE FINISH OFF. IT IS NECESSARY TO LOAD F01 AND2
 (1408) *
 (1409) FPAGE3 CPU BB RM NONE ,,,RM200 ,,EAC LOADF01F02
 08A: EC00 0204 0004 C000
 (1410) CPU RF,,1,,,M,0,RF240,,,S ON TRUE, POP
 08B: 0100 0804 000C 0004
 (1411) *
 (1412) * FINISH THE MEMORY PARITY ERROR TRAP
 (1413) *
 (1414) MEMP3 CPU AL 0 NONE RF 0 M RX ;
 (1415) RF200 ,,EAC NOP (TRIGNVKEYS,MCHK)
 08C: 8000 0A04 0008 0404
 (1416) CPU AL 0 1 RF 0 M RA ;
 (1417) RMRFRDUX AREAD ,GO TO AVECT+1
 08D: 8100 15C4 0004 0078
 (1418) FOUT1 ALU RX ADD RCM = \$20 => RX TR= NONE SETCC
 08E: 9060 0A07 0002 0020
 (1419) RR ,,,TR= NONE JUMP ON NE TO *-1
 08F: 0000 0004 0004 408E
 (1420) RR ,,,TR= NONE GO TO VIRY1
 090: 0000 0004 0004 00C4
 (1421) EJCT

(1422) * CONTROL PANEL BOOT. THIS PROGRAM READS IN 512 WORDS FROM
 (1423) * THE CONTROL PANEL AND PUTS THEM INTO LOCATIONS 6
 (1424) * THROUGH '56 IN VIRTUAL MEMORY. THE LOCATION POINTED TO
 (1425) * BY THE P COUNTER IS THEN EXECUTED.
 (1426) *
 (1427) * METHOD OF OPERATION. AN OTA '1720 SENDS THE CONTROL
 (1428) * PANEL THE LOCATION TO BE READ FROM ITS MEMORY. AN INA
 (1429) * '1420 IS THEN ISSUED TO GET THE CONTENTS OF THE LOCATION
 (1430) * JUST ACCESSED. THIS IS WRITTEN INTO MEMORY, THE POINTERS
 (1431) * ARE INCREMENTED AND THE PROCESS REPEATED UNTIL ALL 512 WORDS
 (1432) * ARE TRANSFERRED.
 (1433) *
 (1434) *
 (1435) *
 (1436) BOOT RR RCM = 0 => RM
 091: F000 0104 0002 0100 (1437) RK RCM = 0 => RB
 092: F000 2904 0002 0100 (1438) RR RCM = 5 => RS
 093: F000 3904 0002 0105 (1439) BOOT1 CPU BB RCM NX 0 0 RY PIO ;
 (1440) RY200 ,DATA '171720
 094: F202 1804 0003 E600 (1441) CPU BB RCM NX 0 0 RSC (DATA,STROBE) ;
 (1442) RY280 , DATA '131420
 095: F203 AE04 0001 6610 (1443) CPU AL 0 NX ZERO L RSC 0 ;
 (1444) 280 NOP NOP ;
 (1445) EAC PLOADVKEYS TRIGVKEYS
 096: 823F 0604 000A 4100 (1446) CPU AL BPD NX BB L RSC 0 ;
 (1447) RM280
 097: 9A5F 0404 0000 0000 (1448) ALU INC RS => (RY,RS)
 098: 8204 3D04 0000 0000 (1449) ALU RS MINUS RCM = '56 => NULL C= MWRITE SETCC
 099: 9294 3087 0002 012E (1450) ALU INC RB => RM
 09A: 8204 2204 0000 0000 (1451) ALU INC RB => RB ;
 (1452) JMF JUMP ON LT TO BOOT1
 09B: 8204 2A00 0006 6094 (1453) EJCT
 (1454) DIV27 ALU DEC RB => RM TR= ALL ,JUMP ON GT TO IAB
 09C: 83F0 2204 0006 71A2 (1455) RR RY => RB ,GO TO LDA+1
 09D: EA00 2A04 0004 01DF (1456) DIV17 CPU ALLS RM NX ADD 0 M RA ;
 (1457) 200 DIVER , ;
 (1458) EAC DIVLOGIC
 09E: AE60 1014 0009 0000 (1459) CPU RFLS 3 ALL 3 0 M RB ;
 (1460) RF200 LINK , ;
 (1461) JUMP ON FCBIT TO DIVER
 09F: 2F30 2A44 0004 F146 (1462) CPU ALLS RM NX ADD 0 M RA ;
 (1463) RF280 LINK ,EAC DIVLOGIC
 0A0: AE60 1C44 0009 0000 (1464) CPU RFLS 3 ALL 3 0 M RB ;
 (1465) RF200 LINK INCRSC ;
 (1466) JUMP ON RSCNEM1 TO *-1
 0A1: 2F30 2A45 0004 90A0 (1467) * SET RSC = 1 SO IAB CODE AT END WORKS
 (1468) CPU ALLS RM NX ADD 0 M RA ;
 (1469) 200 LINK INCRSC EAC DIVLOGIC
 0A2: AE60 1045 0009 0000 (1470) CPU AL RM NX ADD 0 M RA ;
 (1471) RYRF240 ,EAC DIVLOGIC
 0A3: 8E60 1004 0009 0000 (1472) CPU RFLS 3 ALL 6 0 M RB ;
 (1473) RF200
 0A4: 2F60 2A04 0000 0000 (1474) CPU AL 0 NX ANOT L M RB ;
 (1475) RF200
 0A5: 82FC 2A04 0000 0000 (1476) ALU INC RB => RB TR= ALL ,JUMP ON GE TO XCB
 0A6: 8304 2A04 0004 61A6 (1477) ALU RA ADD RM => RY SETCC GO TO DIV27
 0A7: 8E60 1307 0004 009C (1478) DIV4 CPU ,ALL RF 0 M RA ;
 (1479) 200 ,SETCC JUMP ON LT TO DIV17
 0A8: 0300 1007 0006 609E (1480) CPU ALLS RM NX SUB 1 M RA ;
 (1481) 200 DIVER ,EAC DIVLOGIC
 0A9: AE94 1014 0009 0000 (1482) CPU RFLS 3 ALL 3 0 M RB ;
 (1483) RF200 LINK ,JUMP ON FCBIT TO DIVER
 0AA: 2F30 2A44 0004 F146 (1484) CPU ALLS RM NX SUB 1 M RA ;
 (1485) RF280 LINK ,EAC DIVLOGIC
 0AB: AE94 1C44 0009 0000 (1486) CPU RFLS 3 ALL 3 0 M RB ;
 (1487) RF200 LINK INCRSC ;

(1488) 0AC: 2F30 2A45 0004 40AB (1489) (1490) CPU ALLS RM NX SUB 1 M RA ; 200 LINK INCRSC EAC DIVLOGIC	JUMP ON RSCNEM1 TO *-1
0AD: 4E94 1045 0009 0000 (1491) (1492) CPU AL RM NX SUB 1 M RA ; RYRF240 ,,EAC DIVLOGIC	
0AE: 8E94 1D04 0009 0000 (1493) (1494) CPU RFLS 3 ALL 6 0 M RB ; RF200 ,,JUMP ON GE TO XCB	
0AF: 2F60 2A04 0004 61A8 (1495) ALU RA SUB RM => RY SETCC	
0B0: 8E94 1307 0000 0000 (1496) (1497) (1498) CPU AL KEYS ALL RF 1 M RB ; RM200 AOVFL ,; JUMP ON GT IAB	
0B1: 8704 2274 0006 71A2 (1499) (1500) CPU BB RY NX 0 0 M RB ; RF200 ,,GO TO LDA+1	
0B2: EA00 2A04 0004 010F (1501) * (1502) * UNIMPLEMENTED INSTRUCTION VECTOR (1503) * (1504) UII3 RR RCM = '66 => RY	
0B3: F200 0804 0002 0136 (1505) (1506) (1507) CPU BB RM NX 0 0 M 11 ; RMRFMRDY AREAD NOP ; GO TO AVECT1	
0B4: EE00 95C4 0004 0077 (1508) * (1509) * FINISH ILLEGAL INSTRUCTION VECTOR (1510) * (1511) ILL3 RR RCM = '72 => RY	
0B5: F200 0804 0002 013A (1512) RR ,,TR= ALL ,GO TO UII3+1	
0B6: 0300 0004 0004 0084 (1513) STA3 ALU INC RY => RY EAF	
0B7: 8A65 1300 0000 0000 (1514) CPU RF 0 ALL 0 0 M RB ; RM280 MWRITE JAMF	
0B8: 0300 24B0 0000 0000 (1515) (1516) ALU INC RY => RY EAF	
0B9: 8A65 1300 0000 0000 (1517) (1518) CPU BB RM ALL 0 0 M 13 ; RMRFMRDY MREAD	
0BA: EF00 B584 0000 0000 (1519) ALU RB PLUS RM => RB C= AOVFL	
0BB: 8E60 2A74 0000 0000 (1520) ALU RB AND RCM = \$7FFF => RB TR= ALL	
0BC: 931C 2A04 0000 FFFF (1521) RR 13 => RM	
0BD: 0000 B104 0000 0000 (1522) ALU RA PLUS RM + CRIT => RA JAMF C= AOVFL	
0BE: 8E68 1A70 0000 0000 (1523) MI1 CPU ,,NX,,,RY,0,RMMRDY,AREAD,,GO TO MI2	
0BF: 0202 07C4 0004 001C (1524) EJCT	

(1525) *
 (1526) *
 (1527) *
 (1528) *
 (1529) * MICRO-VERIFICATION ROUTINES. THESE ROUTINES ARE DIVIDED
 (1530) * UP INTO '13 TESTS. THE TEST NUMBER IS LOCATED IN RY AT
 (1531) * LEAT AT THE END OF THE TEST WHEN CHECKS ARE DONE
 (1532) * TO SEE IF THE TEST WAS SUCESSFUL OR NOT. IF A TEST FAILS, THE
 (1533) * TEST NUMBER IS DISPLAYED ON THE CONTROL PANEL LIGHTS VIA THE
 (1534) * THE BMA PATH. THESE ROUTINES ARE EXECUTED FOR THREE DIFFERENT
 (1535) * FUNCTIONS:
 (1536) * MASTER CLEAR:
 (1537) *
 (1538) * THE TESTS ARE RUN UNTIL THEY ARE ALL PASSED. UPON COMPLETION,
 (1539) * THE CONTROL PANEL ROUTINE IS ENTERED. FAILURE OF ANY TEST
 (1540) * CAUSES A DELAY, FOLLOWED BY A RETRY OF ALL THE TESTS.
 (1541) *
 (1542) * MACHINE CHECK:
 (1543) *
 (1544) * ENTERED ON THE DETECTION OF A CPU PARITY ERROR, THE TESTS ARE
 (1545) * RUN EXACTLY AS IN MASTER CLEAR EXCEPT THAT WHEN THE TESTS ARE
 (1546) * SUCESSFULLY COMPLETED, THE MACHINE CHECK VECTOR IS
 (1547) * EXECUTED.
 (1548) *
 (1549) * VERIFY (VIRY):
 (1550) *
 (1551) * THIS IS AN EXPLICIT USER REQUESTED EXECUTION OF THE TEST
 (1552) * ROUTINES. SUCCESS IS REWARDED BY SKIPPING
 (1553) * THE NEXT SEQUENTIAL INSTRUCTION, FAILURE IS SHOWN
 (1554) * BY PUTTING THE FAILED TEST NUMBER INTO RA AND EXECUTING
 (1555) * THE NEXT SEQUENTIAL INSTRUCTION.
 (1556) *
 (1557) *
 (1558) * TEST 0: TESTS ALU =0 ,SUB ,=0 CONDITIONAL BRANCH, RCM =0,
 (1559) * CONTROL UNIT AND SETCC.
 (1560) *
 (1561) *
 (1562) *
 (1563) VIRY1 ORG \$C4
 0C4: 803C 0204 0000 0000 CON 0 => RM TR= NONE
 (1564) CPU AL RM NONE ZERO L M RA RYRF240 LOADRSC ;
 (1565) MODAL NOP (54,56,57,58,59,60,61,63,64)
 0C5: BC3C 100E 0008 05FB CPU 0 RCM NONE SUB 1 M RA ;
 (1566) 200 ,SETCC DATA 0
 (1567)
 0C6: 1094 1007 0002 0100 CPU 0 RY NONE SUB 1 M RA ;
 (1568)
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 0C7: 0894 1007 0004 4000 200 ,SETCC ;
 (1571)
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 0C8: 803C 0A04 000A 0504 CPU CON 0 => RX TR= NONE EAC CLRNVKEYS (54,56,62)
 (1575)
 (1576)
 0C9: 8865 1304 0004 40FC ALU INC RY => RY TR= NONE ;
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 (1581)
 0CA: 8865 1304 0007 10FC ALU INC RY => RY TR= NONE ;
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 0CB: 8004 0A05 0004 90Ch CPU TEST 3: TESTS SHIFT COUNTER INCREMENTING AND
 (1590)
 0CC: 9094 0007 0002 0040 THE RSCNOTEQM1 TEST. ALSO RX+1 => RX, AND COUNTS FOR
 (1591)
 (1592)
 0CD: 8865 1304 0004 40FC PROPER NUMBER OF INCREMENTS. (THIS TEST WILL SHOW AS #2
 (1593)
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 (1599)
 0CE: F000 0804 0002 0003 CPU IF RSCNEM1 IS ALWAYS TRUE.)
 (1600)
 0CF: 823C 0204 0000 0000 ALU INC RX => RX TR= NONE INCRSC ;
 (1601)
 0D0: 803C 0904 0000 0000 ALU JUMP ON RSCNEM1 TO *
 (1602)
 (1603)
 0D1: 8865 1304 0007 20FC ALU RX MINUS RCM = \$40 => NULL TR= NONE SETCC
 (1604)
 0D2: 0000 0004 0008 0404 ALU INC RY => RY TR= NONE ;
 (1605)
 (1606)
 0D3: E800 0604 000C 0002 RR JUMP ON MCNOT TO FOUT
 (1607)
 0D4: F000 0204 0004 00CF CPU TESTS 4,5,6: THESE TESTS VERIFY THAT EACH OF THE REGISTERS
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005: F000 0A04 0004 00CF
 (1608) RR RCM => RX TR= NONE ,GO TO VIRY12
 (1609) *
 (1610) * TEST 7: PARITY ON LEFT SHIFT,ROTATE
 (1611) *
 (1612) ALU CON -1 => RA , EAC LOADSERIALINT
 006: 82CC 1A04 0008 4000
 (1613) * LOGICAL LEFT SHIFT
 (1614) CPU RFLS 7 NX 7 0 M RA ;
 (1615) RF200 RFU1
 007: 5E70 1A54 0000 0000
 (1616) * LOGICAL LEFT ROTATE
 (1617) CPU RFLS 1 NX 8 0 M RA ;
 (1618) RF200 , ;
 (1619) JUMP ON MC TO VIRY12-5
 008: 2680 1A04 0007 10CA
 (1620) * ROTATE 64 TIMES
 (1621) RR RA => RA INCRSC ;
 (1622) JUMP ON RSCNEM1 TO *-1
 009: 0200 1A05 0004 90D8
 (1623) *
 (1624) * TEST 7 (CONT): TEST C BIT FOR SET, LOAD AND RESET
 (1625) * CBIT SHOULD BE SET SO RA IS TESTED AGAINST -2
 (1626) *
 (1627) ALU RA MINUS RCM = -2 + CBIT => RA ;
 (1628) C= BD01 SETCC
 0DA: 9298 1A37 0003 FEEF
 (1629) CPU RF 0 NX MINUS1 L M RP ;
 (1630) RM200 ,SETCC ;
 (1631) JUMP ON NE TO VIRY12-2
 0DB: 02CC 7207 0004 40CD
 (1632) *
 (1633) * TEST '10: WRITE BITS THROUGH REGISTER FILE. CHECK
 PATTERN USING EXCLUSIVE ORS TO VERIFY PROPER
 OPERATION. ZERO OUT FILES.
 (1634) *
 (1635) *
 (1636) *
 (1637) RR RCM = \$FFC0 => RX TR= NX
 0DC: F200 0A04 0005 FF00
 (1638) CPU AL 0 NONE RF 1 RSC 0 ;
 (1639) RY240 ,INCRSC ;
 (1640) JUMP ON EQ TO *+2
 0DD: 8007 0305 0006 40DF
 (1641) CPU BB RY NONE BB L RSC 0 ;
 (1642) RF200 ,SETCC ;
 (1643) GO TO *-1
 0DE: E85F 0A07 0004 00D0
 (1644) RR RCM = \$FFE1 => RY
 0DF: F200 0B04 0003 FFE1
 (1645) ALU INC RY => RY INCRSC ;
 (1646) JUMP ON NE TO *+4
 0E0: 8A65 1305 0004 40E4
 (1647) CPU RF 0 NX INC CBIT RSC 0 ;
 (1648) 200 ,SETCC
 0E1: 0200 0007 0000 0000
 (1649) CPU AL RY NX XOR L RSC 0 ;
 (1650) RF200 ,SETCC ;
 (1651) JUMP ON NE TO *-2
 0E2: 8A6F 0A07 0004 40E0
 (1652) CPU AL RY NX ZERO L M RA ;
 (1653) RF200 ,LOADRSC
 0E3: 8A3C 1A0E 0000 0000
 (1654) RR RM => RP TR= NX
 0E4: EE00 7A04 0000 0000
 (1655) RR RCM = '10 => RY
 0E5: F200 0B04 0002 0008
 (1656) RR ,JUMP ON NE TO FOUT
 0E6: 0200 0004 0004 40FC
 (1657) *
 (1658) * TEST '11: I/O BUS TEST. ALTERNATING ONES AND ZEROS ARE
 (1659) * SENT OUT BOTH BPA AND BPD AND READ BACK IN. THIS
 (1660) * CHECKS CPU LOU C IN THE PATH AND 'STUCK AT' FAULTS ON THE
 (1661) * CONTROLLERS.
 (1662) *
 (1663) CPU BB RCM NX 0 0 RSC 0 ;
 (1664) RYRF240 ,DATA \$A5A5
 0E7: F203 0004 0003 4B45
 (1665) CPU BB RY NX 0 0 RY PIO ;
 (1666) RM200
 0E8: EA02 1204 0000 0000
 (1667) CPU BB BPA NX XOR L RSC DATA ;
 (1668) RY240 ,SETCC ;
 0E9: F66F 2307 0000 0000
 (1669) CPU BB BPD NX XOR L RSC DATA ;
 (1670) RM200 ,SETCC ;
 (1671) JUMP ON NE TO *+4
 0EA: FA6F 2207 0004 40E5
 (1672) CPU RFNS 2 NX 2 0 RSC 0 ;
 (1673) RYRF240 , ;
 (1674) JUMP UN NE TO *+3
 0EB: 4A25 0004 0004 40E5
 (1675) CPU BB BPA NX XOR L RSC DATA ;
 (1676) RY240 ,SETCC ;
 0EC: F66F 2307 0000 0000
 (1677) CPU BB BPD NX XOR L RSC DATA ;
 (1678) RM200 ,SETCC ;
 (1679) JUMP ON EQ TO *+3
 0ED: FA6F 2207 0000 40F0
 (1680) RR RCM = '11 => RY
 0EE: F200 0B04 0002 0109
 (1681) CPU AL 0 NX ZERO L RSC 0 ;

```

(1682) HF200 //GO TO FOUT
DEF: 823F 0A04 0004 00FC
(1683) *
(1684) * TEST '12: MEMORY TEST. LOCATION 5 (UNDER THE REGISTERS)
(1685) * IS TESTED TO SEE IF ONES AND ZEROS CAN BE WRITTEN AND READ.
(1686) * NOTE THAT A MISSING FIRST 8K CAN CAUSE A MISSING MEMORY
(1687) * TRAP.
(1688) *
(1689) RR RCM = 5 => RY
0F0: F200 0804 0002 0105
(1690) CPU BB RM NONE 0 0 M RX ;
(1691) RF200 AWRITE
0F1: EC00 0AF4 0000 0000
(1692) CPU BB RY NONE 0 0 0 0 ;
(1693) RY200
0F2: E800 0804 0000 0000
(1694) CPU //NONE ,,,RMMRDY AREAD
0F3: 0000 07C4 0000 0000
(1695) ALU RX XOR RM => RX SETCC
0F4: 8E6C 0A07 0000 0000
(1696) RR RCM = '12 => RY TR= NONE
0F5: F000 0804 0002 010A
(1697) RR ,,,JUMP ON NE TO FOUT
0F6: 0200 0004 0004 40FC
(1698) *
(1699) *
(1700) * TEST '13: PARITY TEST. AFTER VERIFYING PARITY WORKS IN
(1701) * TESTS 4,5, AND 6, THE REST OF THE TESTS ARE RUN WITH
(1702) * PARITY ENABLED. IF MACHINE CHECK GETS SET DURING THOSE
(1703) * TESTS, '13 WILL FAIL.
(1704) ALU INC RY => RY,, JUMP ON MC TO FOUT
0F7: 8A65 1304 0007 10FC
(1705) *
(1706) *
(1707) * SUCCESSFUL TEST COMPLETION
(1708) *
(1709) CPU BB RCM NX RF 0 M RP ;
0F8: F200 7837 0000 0500
(1710) ALU CON 0 => RM ,JUMP ON EQ TO MC4
0F9: 823C 0204 0006 4034
(1711) RR ,,CLEARFUII JUMP ON FUII TO CASS
0FA: 0200 000F 0005 51E5
(1712) RR ,,,GO TO CPPAR3
0FB: 0200 0004 0004 007E
(1713) *
(1714) *
(1715) * FAILED TEST COMPLETION/RETRY
(1716) FOUT CPU BB RY NONE 0 0 M RA ;
(1717) RF200 ,, ;
(1718) JUMP ON FUII TO F1
0FC: E800 1A04 0005 5000
(1719) ALU CON 0 => RX TR= NONE , GO TO FOUT1
0FD: 803C 0A04 0004 008E
(1720) EJCT

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		(1721)	ORG	\$100	
		(1722)	ENTR	ALU	RS MINUS RY => RY
100:	8A94	3304 0000 0000			
		(1723)	CPU	RF,,,ALL,,,M,RS,RM280,MWWRITE	
101:	0300	3484 0000 0000			
		(1724)	RR	RY => RS JAMF	
102:	E800	3900 0000 0000			
		(1725)	FLX1	RR	RM => RX ,GO TO FLX2
103:	EE00	0A04 0004 012A			
		(1726)	ORG	\$104	
		(1727)	RTN	RR	RS => RY
104:	0200	3804 0000 0000			
		(1728)	CPU	,,ALL,,,RMMRDY,MREAD	
105:	0500	0784 0000 0000			
		(1729)	ALU	INC RM => RY	
106:	8E65	1304 0000 0000			
		(1730)	CPU	BB RM ALL BB L M 11 ;	
		(1731)		RMRFRMDY MREAD SETCC	
107:	EF5C	9587 0000 0000			
		(1732)	RR	11 => RY ,JUMP ON EQ TO *+3	
108:	0200	9804 0006 4108			
		(1733)	RR	RY => RS	
109:	E800	3904 0000 0000			
		(1734)	RR	RM => RP JAMF TR= NX	
10A:	EE00	7A00 0000 0000			
		(1735)	RR	RCM = '75 => RY	
10B:	F200	0804 0002 003D			
		(1736)	RR	RP => RM ,GO TO UII3+1	
10C:	0200	7204 0004 0084			
		(1737)	FGEN	CPU RF 0 NX 0 0 M 0 ;	
		(1738)		RF240 0 NOP GO TO FGEN1	
10D:	0200	0804 0004 0406			
		(1739)	ORG	\$110	
		(1740) *			
		(1741) *		INSTRUCTION EXECUTION SPACE	
		(1742) *			
000420	(1743)	EVMX	EQU	*	
000420	(1744)	ERMX	EQU	*	
000420	(1745)	EVMJ	EQU	*	
000420	(1746)	ERMJ	RR	RP => RY NOP JUMP ON RXM TO RXM	
110:	0200	7804 0007 4068			
		(1747)	CPU	BB RM ALL 0 0 M 13 ;	
		(1748)		RMRFRMDY MREAD NOP ;	
		(1749)		MODAL NOP (TRIGNVKEYS,RXM,EINTM)	
111:	EF00	B584 0008 0411			
		(1750)	RR	RM => RY EAF EAC SETFUII	
112:	EE00	080D 000A 8000			
		(1751)	CPU	AL 0 ALL INC 1 M RP ;	
		(1752)		RMRFRMDY MREAD NOP ;	
		(1753)		JUMP ON RSC12 TO EVMX1	
113:	8304	7584 0005 B1F2			
		(1754)	RR	RM => RP TR= NX	
114:	EE00	7A04 0000 0000			
		(1755)	RR	13 => RM TR= NX ,EAC CLEARCAM	
115:	0200	B204 0009 C000			
		(1756)	RR	,,JAMF TR= ALL MODAL NOP (TRIGNVKEYS,PAM)	
116:	0300	0000 0008 0420			
		(1757)	ERM	,,RESTJAMF MODAL NOP (TRIGNVKEYS,RXM,EINTM)	
117:	0200	0002 0008 0411			
		(1758)	NRM	RCM = 0 => RM C= BD01 LOADRSC	
118:	F000	013E 0002 0100			
		(1759)	CPU	RF 0 ALL 0 0 M RA ;	
		(1760)		200 SOVFL	
119:	0300	1064 0000 0000			
		(1761)	CPU	RFLS 7 NX 3 0 M RB ;	
		(1762)		RF200 LINK ,;	
		(1763)		JUMP ON FCBIT TO *+2	
11A:	3E30	2A44 0004 F11C			
		(1764)	CPU	RFLS 3 ALL 7 0 M RA ;	
		(1765)		RF200 SOVFL INCRSC ;	
		(1766)		JUMP ON RSCNE1 TO *+2	
11B:	2F70	1A65 0004 9119			
		(1767)	CPU	RFRS 0 NX 6 0 M RB ;	
		(1768)		RF200	
11C:	4260	2A04 0000 0000			
		(1769)	RR	RSC => 13	
11D:	E400	B904 0000 0000			
		(1770)	ALU	13 AND RCM = \$3F => (RY,13) TR= TDMX	
11E:	911C	BD04 0002 013F			
		(1771)	RR	,,GO TO OTK+2	
11F:	0200	0004 0004 0194			
		000440	(1772)	EPMX EQU *	
		000440	(1773)	LPMX EQU *	
		000440	(1774)	LPMJ EQU *	
		000440	(1775)	EPMJ RR RP => RY NOP JUMP ON RXM TO RXM	
120:	0200	7804 0007 4068			
		(1776)	CPU	BB RM ALL 0 0 M 13 ;	
		(1777)		RMRFRMDY MREAD ,GO TO ERMJ+2	
121:	EF00	B584 0004 0112			
		(1778)	XEC	,,JUMP ON FETCH1 TO *+2	
122:	0200	0004 0004 A124			
		(1779)	CPU	RF 0 NX 0 0 M RA ;	
		(1780)		CLMCLFCLI MREAD ,GO TO F9	
123:	0200	1F84 0004 0004			
		(1781)	ALU	DEC RP => RP CLEARFUII JUMP ON FUII TO *	
124:	82F0	7A0F 0005 5124			
		(1782)	RR	,,JAMF	
125:	0200	0000 0000 0000			
		(1783)	VIRY	RR ,,REST EAC SETFUII	
126:	0200	0006 000A 8000			

(1784) RR ,,,GO TO VIRY1
 127: 0200 0004 0004 00C4
 (1785) CEA3 EQU *
 (1786) EAA RR RY => RA TR= NX JAMF
 128: E400 1A00 0000 0000
 (1787) FLX CPU ,,,ALL,,,,,RMMRDY MREAD ,GO TO FLX1
 129: 0300 0784 0004 0103
 (1788) FLX2 CPU RFLS 7 NX 3 0 M RX ;
 (1789) RF200 ,JAMF
 12A: 3E30 0A00 0000 0000
 (1790) JEQ ALU INC RA + 0 => NULL SETCC
 12B: 8200 1007 0000 0000
 (1791) RR ,,JAMF JUMP ON EQ TO JMP
 12C: 0200 0000 0006 41D0
 (1792) JNE ALU INC RA + 0 => NULL SETCC
 12D: 8200 1007 0000 0000
 (1793) RR ,,JAMF JUMP ON NE TO JMP
 12E: 0200 0000 0004 41D0
 (1794) JLE ALU INC RA + 0 => NULL SETCC
 12F: 8200 1007 0000 0000
 (1795) RR ,,JAMF JUMP ON LE TO JMP
 130: 0200 0000 0004 71D0
 (1796) JGT ALU INC RA => RA C= ADVFL JAMF DATA 0
 131: 8200 1007 0000 0000
 (1797) RR ,,JAMF JUMP ON GT TO JMP
 132: 0200 0000 0006 71D0
 (1798) AOA ALU INC RA => RA C= ADVFL JAMF DATA 0
 133: 8204 1A70 0002 0100
 (1799) JLT ALU INC RA + 0 => NULL SETCC
 134: 8200 1007 0000 0000
 (1800) RR ,,JAMF JUMP ON LT TO JMP
 135: 0200 0000 0006 61D0
 (1801) JGE ALU INC RA + 0 => NULL SETCC
 136: 8200 1007 0000 0000
 (1802) RR ,,JAMF JUMP ON GE TO JMP
 137: 0200 0000 0004 61D0
 (1803) JDY ALU DEC RX => RX SETCC ;
 (1804) GO TO JNE+1
 138: 62F0 0A07 0004 012E
 (1805) JIX ALU INC RX => RX SETCC ;
 (1806) GO TO JNE+1
 139: 8204 0A07 0004 012E
 (1807) JSX RR RP => RM
 15A: 0000 7104 0000 0000
 (1808) RR RM => RX ,GO TO JMP
 15B: EE00 0A04 0004 0100
 (1809) CREP RR RY => 13
 15C: E800 B904 0000 0000
 (1810) ALU INC RS => RY
 15D: 8204 3304 0000 0000
 (1811) CPU RF 0 ALL 0 0 M RP ;
 (1812) RM280 MWRITE
 15E: 0300 7484 0000 0000
 (1813) RR 13 => RY ,GO TO JMP
 15F: 0200 B804 0004 0100
 (1814) *
 (1815) * UNIMPLEMENTED INSTRUCTION VECTOR (UII)
 (1816) *
 (1817) UII RR RY => EAS TR= ALL
 140: E800 AA04 0000 0000
 (1818) RR RP => RM ,GO TO UII3
 141: 0200 7204 0004 0085
 (1819) * ILLEGAL INSTRUCTION VECTOR (ILL)
 (1820) *
 (1821) *
 (1822) ILL RR RY => EAS TR= NX
 142: EA00 AA04 0000 0000
 (1823) RR RP => RM ,GO TO ILL3
 143: 0200 7204 0004 0085
 (1824) DIV CPU 0 RCM ALL 0 0 0 0 ;
 (1825) RMMRDY MREAD LOADRSC ;
 (1826) DATA -15
 144: 1300 078E 0003 FEF1
 (1827) CPU 0 RM NX XOR L M RA ;
 (1828) 200 ,SETCC GO TO DIV4
 145: 0E6C 1007 0004 00A8
 (1829) DIVER CPU RFRS 0 NX 6 0 M RB ;
 (1830) RF200 0 JAMF
 146: 4260 2A00 0000 0000
 (1831) LDY CPU ,,,ALL,,,,,RMMRDY MREAD
 147: 0300 0784 0000 0000
 (1832) CPU BB RM NX 0 0 XM 0 ;
 (1833) RF200 ,JAMF
 148: EE01 0A00 0000 0000
 (1834) *
 (1835) *
 (1836) * INSTRUCTION EXECUTION. IN THIS SECTION, INSTRUCTIONS
 (1837) * (INDICATED BY THE LABELS) ARE EXECUTED.
 (1838) *
 (1839) *
 (1840) * SEVERAL GEN B INSTRUCTIONS DECODE TO THE SAME PLACE. AS
 (1841) * A RESULT, THEY MUST BE SPECIALLY DECODED BY TESTING FOR DIF-
 (1842) * FERENT OP CODES IN RM.
 (1843) *
 (1844) GENB RR ,,,JUMP ON RSC12 TO RMC
 149: 0200 0004 0005 B1B7
 (1845) RR ,,,JUMP ON RS16 TO GENB1
 14A: 0200 0004 0005 2183
 (1846) HLT RR RP => RY REST GO TO CP1
 14B: 0200 7806 0004 0035

(1847) SUB CPU ,ALL,,,RMMRDY MREAD , JUMP ON DP TO SUB3
 14C: 0300 0784 0005 C16C
 (1848) ALU RA SUB RM => RA C= AUVFL JAMF
 14D: 8E94 1A70 0000 0000
 (1849) JST CPU ,ALL,,,RMMRDY MREAD
 14E: 0300 0784 0000 0000
 (1850) CPU AL RM NX RF 0 M RP ;
 RM200 ,EAC JST
 14F: 8E00 7204 0008 8000
 (1851) JST1 CPU BH RY ALL 0 0 M RP ;
 RF200 MWRITE ,GO TO CASS
 150: EB00 7AB4 0004 01E5
 (1852) EJCT
 (1853) *
 (1854) * PROGRAMMED INPUT/OUTPUT. INA,UTA,SKS,AND UCP ARE
 (1855) * ALL EXECUTED USING THIS COMMON CODE. INSTRUCTION
 (1856) * SPECIFIC CODE IS EXECUTED AFTER TESTING THE TWO HIGH
 (1857) * ORDER BITS OF THE OP CODE. TH TESTS ON DEVICE
 (1858) * ADDRESS 20 ARE TO AVOID TESTING READY, CLEAN UP PARITY
 (1859) * AND NOT SKIP FOR DEVICE 20 DEVICES INCLUDING THE CONTROL
 (1860) * PANEL THE REAL TIME CLOCK, AND THE MASK CHANGE COMMANDS.
 (1861) *
 (1862) *
 (1863) *
 (1864) INA CPU 0 RCM NX 0 0 RY PIO ;
 280 NOP LOADRSC ;
 (1865) DATA 1
 (1866)
 151: 1202 160E 0002 0001
 (1867) CPU RF 0 NX 0 0 RSC 0 ;
 RM200 NOP NOP ;
 (1868) JUMP ON FU1NOT TO SKS
 (1869)
 152: 0203 0204 0005 3157
 (1870) CPU BH BPD NX 0 0 RSC 0 ;
 (1871) KF280 0 NOP ;
 (1872) JUMP ON READYNOTANDNE20 TO INA1
 153: FA03 0C04 0005 7156
 (1873) CPU 0 0 NONE 0 0 RSC STROBE ;
 200 NOP NOP ;
 (1874) JUMP ON BPSP1NOT TO INA2
 (1875)
 154: 0003 8004 0006 318A
 (1876) CPU AL 0 NONE RF 0 RSC 0 ;
 (1877) RM200 NOP NOP ;
 (1878) JUMP ON DANOT20 TO CASS
 155: 8003 0204 0005 61E5
 (1879) INA1 CPU AL RM NONE BH L RSC 0 ;
 (1880) RF200 NOP JAMF
 156: 8C5F 0A00 0000 0000
 (1881) SKS CPU ,NX,,,RSC,0,280,,,JUMP ON READYANDF02 TO SKS1
 157: 0203 0604 0005 81EC
 (1882) CPU ,NX,,,RSC,STROBE,,,GO TO INA1
 158: 0203 8004 0004 0156
 000531 (1883) PIO EQU *
 (1884) UTA RR RM => RY TR= ALL REST JUMP ON OTANOT TO INA
 159: EF00 0806 0005 4151
 (1885) CPU 0 RCM NX 0 0 RY PIO ;
 (1886) 280 0 LOADRSC DATA 1
 15A: 1202 160E 0002 0001
 (1887) CPU RF RCM NX 0 0 RSC 0 ;
 (1888) RM200 NOP LOADRSC DATA 7
 15B: 1203 020E 0002 0007
 (1889) CPU 0 0 NX 0 0 RSC DATA ;
 (1890) 280 NOP NOP ;
 (1891) JUMP ON READYNOTANDNE20 TO F1
 15C: 0203 2604 0005 7000
 (1892) CPU ,,,RSC (DATA,STROBE) 200 ,,JUMP ON DANOT20 TO OTA1
 15D: 0203 A004 0005 615F
 (1893) CPU ,ALL,,,RSC DATA 200 ,JAMF
 15E: 0303 2000 0000 0000
 (1894) OTA1 CPU AL 0 ALL INC 1 RSC DATA ;
 (1895) RF200 NOP EAF ;
 (1896) GO TO F1
 15F: 8307 2A00 0004 0000
 (1897) EJCT

		(1898)	ORG	\$160				
		(1899) LDA3	ALU	INC RY => RY EAF				
160:	8A65 130D 0000 0000	(1900)	CPU	BB RM ALL 0	0	M	RA ;	
		(1901)		RMRFRMDY MREAD				
161:	EF00 1584 0000 0000	(1902)	RR	RM => RB TR= NX		JAMF		
162:	EE00 2A00 0000 0000	(1903)	CPU	BB RCM ALL 0	0	M	VSC ;	
		(1904)		RMRFRMDY MREAD NOP	DATA \$00FF			
163:	F300 6584 0002 01FF	(1905)	CPU	BB RM NX 0	0	M	FLTH ;	
		(1906)		RF200 NOP NOP	GO TO FLD1			
164:	EE00 4A04 0004 0456	(1907)	CPU	0 0 ALL 0	0	0	0 ;	
		(1908)		RMMRDY MREAD NOP	GO TO FAD1			
165:	0300 0784 0004 040H	(1909)	CPU	0 0 ALL 0	0	0	0 ;	
		(1910)		RMMRDY MREAD NOP	GO TO FSB1			
166:	0300 0784 0004 0400	(1911)	CPU	0 0 ALL 0	0	0	0 ;	
		(1912)		RMMRDY MREAD NOP	GO TO FMP1			
167:	0300 0784 0004 0417	(1913)	CPU	0 0 ALL 0	0	0	0 ;	
		(1914)		RMMRDY MREAD NOP	GO TO FDV1			
168:	0300 0784 0004 0428	(1915)	CPU	RF 0 NX 0	0	M	FLTH ;	
		(1916)		RM200 NOP NOP	GO TO FST1			
169:	0200 4204 0004 0464	(1917)	CPU	BB RCM ALL 0	0	M	11 ;	
		(1918)		RMRFRMDY MREAD NOP	DATA \$00FF			
16A:	F300 9584 0002 01FF	(1919)	CPU	BB RM NX XOR L	M	FLTH ;		
		(1920)		280 BD01 SETCC GO TO FCS1				
16B:	EE6C 4637 0004 0468	(1921)	ALU	INC RY => RY EAF				
16C:	8A65 130D 0000 0000	(1922)	CPU	BB RM ALL 0	0	M	13 ;	
		(1923)		RMRFRMDY MREAD				
16D:	EF00 B584 0000 0000	(1924)	ALU	RB MINUS RM => RB SETCC				
16E:	8E94 2A07 0000 0000	(1925)	RR	13 => RM TR= NX , JUMP ON GE SUB+1				
16F:	0200 B204 0004 6140	(1926)	ALU	RB AND RCM = \$7FFF => RB TR= ALL				
170:	931C 2A04 0000 FFFF	(1927)	ALU	RA SUB RM + 0 => RA C= AOVFL JAMF				
171:	8E90 1A70 0000 0000	(1928)	PIM	RA AND RCM = \$8000 => RM				
172:	921C 1204 0001 0100	(1929)	ALU	RB OR RM => RM ,GO TO LDA+1				
173:	8E4C 2204 0004 010F	(1930)	ALU	INC RA => RY + 0 SETCC				
174:	8200 1307 0000 0000	(1931)	ALU	CON -1 => RA ,JUMP ON GE TO XCA+1				
175:	8200 1A04 0004 61A5	(1932)	RR	RY => RB				
176:	E800 2904 0000 0000	(1933)	ALU	RB AND RCM = \$7FFF => RB JAMF				
177:	921C 2A00 0000 FFFF	(1934)	IMA	RA => RM				
178:	0000 1104 0000 0000	(1935)	CPU	BB RM ALL 0	0	M	13 ;	
		(1936)		RMRFRMDY MREAD				
179:	EF00 B584 0000 0000	(1937)	RR	RM => RA TR= NX				
17A:	EE00 1A04 0000 0000	(1938)	CPU	RF 0 ALL 0	0	M	13 ;	
		(1939)		RM280 MWRITE	JAMF			
17B:	0300 B4B0 0000 0000	(1940)	CPU	0 RCM ALL 0	0	M	0 ;	
		(1941)		RMRDY MREAD LOADRSC ;				
		(1942)		DATA -15				
17C:	1300 078E 0003 FEF1	(1943)	CPU	RFRS 5 NX 6	0	M	RA ;	
		(1944)		HY240 LINK				
17D:	5660 1544 0000 0000	(1945)	RR	RY => RB				
17E:	E800 2904 0000 0000	(1946)	RR	RCM = 0 => RA				
17F:	F000 1904 0002 0100	(1947)	CPU	ALRS RM NX ADD 0	M	RA ;		
		(1948)		RF240 LINK ,EAC MPYLOGIC				
180:	CE60 1B44 0008 0000	(1949)	CPU	RFRS 0 ALL 6	0	M	RB ;	
		(1950)		RF200 LINK INCRSC ;				
		(1951)		JUMP ON RSCNEM1 TO *-1				
181:	4360 2A45 0004 9180	(1952)	CPU	AL RM NX SUB 1	M	RA ;		
		(1953)		RF240 AUVFL JAMF EAC MPYLOGIC				
182:	8E94 1B70 0008 C000	(1954)	GENB1	,,JAMF JUMP ON RSC11 TO **1				
183:	0200 0000 0005 A184	(1955)	ALU	VSC AND RCM = \$FF => RM TR= ALL				
184:	931C 6204 0002 01FF	(1956)	SCA	RM => RA JAMF ;				
		(1957)		JUMP ON RS15 TO **1				
185:	EE00 1A00 0005 0186	(1958)	INK	RA OR KEYS => RA DISABLERHBB GO TO F1				
186:	864C 1A08 0004 0000		ALU					

(1959) RMC RR ,,RESTJMF MODAL NOP (TRIGNVKEYS,MCHK)
 187: 0200 0002 0008 0404 EQU *
 (1960) DHL EQU *
 (1961) SGL RR ,,JMF MODAL NOP (TRIGVKEYS,DP)
 188: 0200 0000 0008 0140
 000611 (1962) E16S EQU *
 000611 (1963) E32S EQU *
 000611 (1964) E32R EQU *
 (1965) E64R RR ,,JMF MODAL NOP (TRIGVKEYS,AM1,AM2)
 189: 0200 0000 0008 110C CPU AL RM NX OR L RSC 0 ;
 (1966) INA2 RF200 0 NOP ;
 (1967)
 (1968)
 GO TO CASS
 18A: 8E4F 0A04 0004 01E5 CPU HB RCM NONE ,,,280 ,PUSHBD ;
 (1969) CEA DATA CEA3
 (1970)
 18B: F000 060C 0000 0328 RR RA => RM , GO TO F6
 (1971)
 18C: 0200 1204 0004 0010 RR ,
 000615 (1972) EMCN ENU *
 (1973) LMCM RR ,,JUMP ON RXM TO RXM
 18D: 0200 0004 0007 4068 RR ,,JMF MODAL NOP (TRIGNVKEYS,PARM)
 18E: 0200 0000 0008 0402 RR RY => RB TR= NX ,GO TO LDA+1
 18F: EA00 2A04 0004 01DF RR ,
 000620 (1976) ENH EQU *
 (1977) INH RR ,,JUMP ON RXM TO RXM
 190: 0200 0004 0007 4068 RR ,,JMF MODAL NOP (TRIGNVKEYS,EINTM)
 191: 0200 0000 0008 0410 RR RA => , TR= NX C= BD01 ;
 (1979) OTK EAC PLOADVKEYS TRIGVKEYS
 (1980)
 192: 0200 1034 0004 4100 ALU RA AND RCM = \$FF => RY TR= ALL
 (1981)
 193: 931C 1304 0002 01FF ALU VSC AND RCM = \$FF00 => VSC
 194: 921C 6A04 0003 FF00 ALU VSC OR RY => VSC JMF
 (1983)
 195: 8A4C 6A00 0000 0000
 (1984) *
 (1985) * NON-VISIBLE KEYS ARE TRIGGERED ON CAI BECAUSE THIS
 (1986) * INHIBITS INTERRUPTS FOR THE FOLLOWING INSTRUCTION.
 (1987) * (JST CONCATINATION ALSO PERFORMS THE SAME FUNCTION.
 (1988) *
 000626 (1989) ESIM EQU *
 (1990) EVIM RR ,,JUMP ON RXM TO RXM
 196: 0200 0004 0007 4068 RR ,,JMF MODAL NOP (TRIGNVKEYS,VIM)
 (1991)
 197: 0200 0000 0008 0408 RR RCM = '65 => RY
 (1992) SVC
 198: F200 0804 0002 0135 CPU ,,NONE,,,RMMRDY,AREAD,,GO TO AVECT+1
 199: 0000 07C4 0004 0078 RR SI => RA TR= NX
 (1994) ISI
 19A: E200 1A04 0000 0000 ALU RA AND RCM = \$F => RA TR= 0 RESTJMF
 (1995)
 19B: 901C 1A02 0002 010F RR ,,JUMP ON RXM TO RXM
 (1996) OSI
 19C: 0200 0004 0007 4068 RR RA => , TR= NX JMF EAC LOADSERIALINT
 (1997)
 19D: 0200 1000 0008 4000 RR RCM = 0 => RA TR= NX
 (1998) CRL
 19E: F200 1A04 0002 0100 RR RCM = 0 => RB TR= NX JMF
 (1999) CRH
 19F: F200 2A00 0002 0100 RR RCM = 0 => RA TR= NX JMF
 (2000) CHS
 1A0: 926C 1A00 0001 0100 ALU RA XOR RCM = \$8000 => RA JMF
 (2001) SSP
 1A1: 921C 1A00 0000 FFFF ALU RA AND RCM = \$7FFF => RA JMF
 000642 (2002) IAB EQU *
 (2003) XCA RR RA => RY TR= NX , JUMP ON RS16 TO XCB
 1A2: 0200 1804 0005 21A8
 (2004)
 1A3: EA00 2A04 0004 01CE RR RY => RB TR= NX ,GO TO CRA
 (2005) SUA ALU RA MINUS RCM = 1 => RA C= AOVFL JMF
 1A4: 9294 1A70 0002 0001 CPU AL ,,INC 1 XM 0 RF200 ,SETCC
 (2006) IRX
 1A5: 8205 0A07 0000 0000 RR ,,JMF JUMP ON EQ TO CASS
 (2007)
 1A6: 0200 0000 0006 41E5 RR RCM = 0 ,C= BD01 JMF
 (2008) RCB
 1A7: F200 0030 0002 0100 RR RB => RM TR= NX , JUMP ON RS16 TO IAB2
 (2009) XCB
 1A8: 0200 2204 0005 218F RR RM => RA TR= NX ,GO TO CRB
 (2010)
 1A9: EE00 1A04 0004 019F CPU AL ,,DEC 0 XM 0 RF200 ,SETCC ;
 (2011) DRX GO TO IRX+1
 1AA: 82F1 0A07 0004 01A6 CPU WF ,,RF 0 M RA RF200 ;
 (2013) CAZ ,SETCC GO TO CASS5-2
 (2014)
 1AB: 0200 1A07 0004 01E3 ALU RA AND RCM = \$7FFF => RA C= RF01 JMF
 (2015) CSA
 1AC: 921C 1A50 0000 FFFF CPU AL RCM NX ADD 0 M RA ;
 (2016) A2A RF240 AOVFL JMF DATA 2
 (2017)
 1AD: 9260 1B70 0002 0002 CPU AL RCM NX SUB 1 M RA ;
 (2018) S2A RF240 AOVFL JMF DATA 2
 (2019)

1AE: 9294 1B70 0002 0002
 (2020) CMA ALU NOT RA => RA JAMF
 1AF: 82FC 1A00 0000 0000
 (2021) TCA ALU NOT RA => RA ,GO TO AOA
 1B0: 82FC 1A04 0004 0133
 (2022) SSM ALU RA OR RCM = \$8000 => RA JAMF
 1B1: 924C 1A00 0001 0100
 (2023) SCB RR RCM = \$8000 => RY C= BD01 JAMF
 1B2: F200 0830 0001 0100
 (2024) CAR ALU RA AND RCM = \$FF00 => RA JAMF
 1B3: 921C 1A00 0003 FF00
 (2025) CAL ALU RA AND RCM = \$00FF => RA JAMF
 1B4: 921C 1A00 0002 01FF
 (2026) ICL ALU RA AND RCM = \$FF00 => RA FLIP BYTES JAMF
 1B5: 721C 1A00 0003 FF00
 (2027) ICR ALU RA AND RCM = \$00FF => RA FLIP BYTES JAMF
 1B6: 721C 1A00 0002 01FF
 (2028) STX CPU RF 0 ALL 0 0 XM 0 ;
 (2029) RM280 MWRITE JAMF
 1B7: 0301 0480 0000 0000
 (2030) ACA ALU INC RA + CBIT => RA C= AOVFL JAMF
 1B8: 8208 1A70 0000 0000
 (2031) ICA ALU INC RA + L => RA FLIP BYTES JAMF
 1B9: 620C 1A00 0000 0000
 (2032) *
 (2033) * LOGIC COMMON ENTRY. ALL LOGICIZE INSTRUCTIONS BEGIN HERE.
 (2034) *
 (2035) LOGIC CPU BB RM NX DEC 1 M RA ;
 (2036) 280 ,SETCC S TRUE 16WAYS TO \$1C0
 1BA: EEF4 1607 000C 01C2
 (2037) LRL CPU RFRRS 5 ALL 6 ,M RA RF200 ;
 (2038) LINKS
 1BB: 5760 1A14 0000 0000
 (2039) CPU RFRRS 1 NX 6 ,M RB RF200 ;
 (2040) LINKS INCRSCF ;
 (2041) JUMP ON RSCNEM1 TO **1
 1BC: 4660 2A11 0004 91B8
 (2042) LRS CPU RFRRS 3 ALL 6 ,M RA RF200 ;
 (2043) LINKS
 1BD: 4F60 1A14 0000 0000
 (2044) CPU RFRRS 0 NX 6 ,M RB RF200 ;
 (2045) LINKS INCRSCF ;
 (2046) JUMP ON RSCNEM1 TO **1
 1BE: 4260 2A11 0004 91BD
 (2047) LRR CPU RFRRS 1 NX 6 ,M RB 200 ;
 (2048) LINK
 1BF: 4660 2044 0000 0000
 (2049) CPU RFRRS 1 ALL 6 ,M RA RF200 ;
 (2050) LINKS
 1C0: 4760 1A14 0000 0000
 (2051) CPU RFRRS 1 NX 6 ,M RB RF200 ;
 (2052) LINKS INCRSCF ;
 (2053) JUMP ON RSCNEM1 TO **2
 1C1: 4660 2A11 0004 91BF
 (2054) ARL CPU RFRRS 5 ALL 6 ,M RA RF200 ;
 (2055) LINKS INCRSCF ;
 (2056) JUMP ON RSCNEM1 TO *
 1C2: 5760 1A11 0004 91C2
 (2057) ARS CPU RFRRS 3 ALL 6 ,M RA RF200 ;
 (2058) LINKS INCRSCF ;
 (2059) JUMP ON RSCNEM1 TO *
 1C3: 4F60 1A11 0004 91C3
 (2060) ARR CPU RFRRS 2 ALL 6 ,M RA RF200 ;
 (2061) LINKS INCRSCF ;
 (2062) JUMP ON RSCNEM1 TO *
 1C4: 4860 1A11 0004 91C4
 (2063) LLR CPU RFRLS 3 NX 7 ,M RA 200 ;
 (2064) LINK
 1C5: 2E70 1044 0000 0000
 (2065) CPU RFRLS 3 ALL 7 ,M RB RF200 ;
 (2066) RF01
 1C6: 2F70 2A54 0000 0000
 (2067) CPU RFRLS 3 NX 7 ,M RA RF200 ;
 (2068) RF01 INCRSCF ;
 (2069) JUMP ON RSCNEM1 TO **2
 1C7: 2E70 1A51 0004 91C5
 (2070) EJCT

	(2071)	ORG	\$1C8	
	(2072) LLT	ALU	CON ZERO => RA JAMF ;	
	(2073)		JUMP ON LT TO LT	
1C8: 823C 1A00 0006	61CF			
	(2074) LLE	ALU	CON ZERO => RA JAMF ;	
	(2075)		JUMP ON LE TO LT	
1C9: 823C 1A00 0004	71CF			
	(2076) LNE	ALU	CON ZERO => RA JAMF ;	
	(2077)		JUMP ON NE TO LT	
1CA: 823C 1A00 0004	41CF			
	(2078) LEQ	ALU	CON ZERO => RA JAMF ;	
	(2079)		JUMP ON EQ TO LT	
1CB: 823C 1A00 0006	41CF			
	(2080) LGE	ALU	CON ZERO => RA JAMF ;	
	(2081)		JUMP ON GE TO LT	
1CC: 823C 1A00 0004	61CF			
	(2082) LGT	ALU	CON ZERO => RA JAMF ;	
	(2083)		JUMP ON GT TO LT	
1CD: 823C 1A00 0006	71CF		*	
	000716 (2084) LF	EQU	RCM = 0 => RA TR= NX JAMF	
	(2085) CRA	RR		
1CE: F200 1A00 0002	0100			
	(2086) LT	RR	RCM = 1 => RA TR= NX JAMF	
1CF: F200 1A00 0002	0001			
	(2087) JMP	RR	RY => RP TR= NX JAMF	
1D0: EA00 7A00 0000	0000			
	(2088) LLL	CPU	RFLS 7 ALL 7 ,M RB RF200 ;	
	(2089)		RF01	
1D1: 3F70 2A54 0000	0000			
	(2090)	CPU	RFLS 3 NX 7 ,M RA RF200 ;	
	(2091)		RF01 INCRSCF ;	
	(2092)		JUMP ON RSCNEM1 TO **-1	
1D2: 2E70 1A51 0004	91D1			
	(2093) LLS	RR	RCM = 0 => ,C= BD01	
1D3: F200 0034 0002	0100			
	(2094)	CPU	RFLS 7 NX 3 ,M RB RF200 ;	
	(2095)		LINK	
1D4: 3E30 2A44 0000	0000			
	(2096)	CPU	RFLS 3 ALL 6 ,M RA RF200 ;	
	(2097)		SOVFL INCRSCF ;	
	(2098)		JUMP ON RSCNEM1 TO **-1	
1D5: 2F60 1A61 0004	91D4			
	(2099) ALL	CPU	RFLS 7 ALL 7 ,M RA RF200 ;	
	(2100)		RF01 INCRSCF ;	
	(2101)		JUMP ON RSCNEM1 TO *	
1D6: 3F70 1A51 0004	91D6			
	(2102) ALS	RR	RCM = 0 => ,C= BD01	
1D7: F200 0034 0002	0100			
	(2103)	CPU	RFLS 7 ALL 7 ,M RA RF200 ;	
	(2104)		SOVFL INCRSCF ;	
	(2105)		JUMP ON RSCNEM1 TO *	
1D8: 3F70 1A61 0004	91D8			
	(2106) ALR	CPU	RFLS 1 ALL 8 ,M RA RF200 ;	
	(2107)		RF01 INCRSCF ;	
	(2108)		JUMP ON RSCNEM1 TO *	
1D9: 2780 1A51 0004	91D9			
	(2109)	EJCT		

(2110) SKP CPU BB RCM NX RF O M RA ;
 (2111) RY200 ,SETCC DATA '131620
 1DA: F200 1807 0001 6790
 (2112) *
 (2113) * THE SKIP INSTRUCTION MUST READ THE CONTROL PANEL
 (2114) * SENSE SWITCHES. THIS MEANS THE I/O COMMAND MUST BE
 (2115) * FORMED IN RY AND THE SIGNALS GENERATED. THE SKIP HARD-
 (2116) * WARE WILL WORK CORRECTLY ONLY IF RA IS SELECTED FROM THE
 (2117) * REGISTER FILES, THE CONDITION CODES HAVE BEEN PRESET TO THE
 (2118) * CONTENTS OF RA, AND BD HAS THE SENSE SWITCHES ON IT. IF THE
 (2119) * ABOVE IS TRUE IN ONE CYCLE, THEN FSKIP IS DEFINED TO HAVE
 (2120) * THE CORRECT SENSE FOR TESTING ON THE NEXT CYCLE.
 (2121) *
 (2122) *
 (2123) CPU BB RCM NX ,RY PIO 200 ;
 (2124) ,LOADRSC DATA 1
 1DB: F202 100E 0002 0001
 (2125) CPU BB BPD NX RF O RSC 0 280
 1DC: FA03 0604 0000 0000
 (2126) RR RA => , JAMF ;
 (2127) JUMP ON SKIP TO CASS
 1DD: 0200 1000 0004 81E5
 (2128) LDA CPU ,ALL,,,RMMRDY MREAD ;
 (2129) JUMP ON DP TO LDA3
 1DE: 0300 0784 0005 C160
 (2130) RR RM => RA TR= NX JAMF
 1DF: EE00 1A00 0000 0000
 (2131) CAS CPU AL KEYS ALL BB L M 13 ;
 (2132) RMRFRDY MREAD
 1E0: 875C B584 0000 0000
 (2133) ALU RA MINUS RM => NULL C= ADVFL SETCC
 1E1: 8E94 1077 0000 0000
 (2134) RR 13 => NULL NOP C= RF01 ;
 (2135) JUMP ON FCBIT TO CAS6
 1E2: 0200 B054 0004 F1F1
 (2136) RR ,JAMF JUMP ON LE TO CAS4
 1E3: 0200 0000 0004 71E4
 (2137) CAS4 ALU INC RP => RP JAMF ;
 (2138) JUMP ON NE TO CASS
 1E4: 8204 7A00 0004 41E5
 (2139) CASS ALU INC RP => RP TR= ALL NOP GO TO F1
 1E5: 8304 7A04 0004 0000
 (2140) IRS CPU ,ALL,,,RMMRDY MREAD
 1E6: 0300 0784 0000 0000
 (2141) ALU INC RM => RM SETCC
 1E7: 8E65 1207 0000 0000
 (2142) CPU ,ALL,,,280 MWRITE JAMF JUMP ON EQ TO CASS5
 1E8: 0300 0680 0006 41E5
 (2143) ANA CPU ,ALL,,,RMMRDY MREAD
 1E9: 0300 0784 0000 0000
 (2144) ALU RA AND RM => RA JAMF
 1EA: 8E1C 1A00 0000 0000
 (2145) STA CPU RF 0 ALL 0 0 M RA ;
 (2146) RM280 MWRITE JAMF ;
 (2147) JUMP ON DP TO STA3
 1EB: 0300 14B0 0005 C087
 (2148) SKS1 CPU ,NX,,,RSC STROBE 200 ,GO TO INA2
 1EC: 0203 8004 0004 018A
 (2149) ERA CPU ,ALL,,,RMMRDY MREAD
 1ED: 0300 0784 0000 0000
 (2150) ALU RA XOR RM => RA JAMF
 1EE: 8E6C 1A00 0000 0000
 (2151) ADD CPU ,ALL,,,RMMRDY MREAD ,JUMP ON DP TO ADD3
 1EF: 0300 0784 0005 C089
 (2152) ALU RA ADD RM => RA C= ADVFL JAMF
 1F0: 8E60 1A70 0000 0000
 (2153) CAS6 RR ,JAMF JUMP ON GT TO CAS4
 1F1: 0200 0000 0066 71E4
 (2154) EVMX1 RR RM => 11 TR= NX
 1F2: EE00 9A04 0000 0000
 (2155) RR 13 => RM TR= NX ,EAC CLEARCAM
 1F3: 0200 B204 0009 C000
 (2156) RR 11 => NULL ,MODAL NOP (TRIGNVKEYS,PAM)
 1F4: 0200 9004 0008 0420
 (2157) CPU RF 0 NX 0 0 M 11 ;
 (2158) 280 NOP NOP S ON TRUE BD
 1F5: 0200 9604 000C 0000
 (2159) DFLD CPU ,ALL,,,RMMRDY,MREAD,,GO TO DFLD1
 1F6: 0300 0784 0004 0500
 (2160) DFST CPU RF,,ALL,,,M,FLTH,RM280,MWRITE,,GO TO DFST1
 1F7: 0300 44B4 0004 0507
 (2161) DFAD CPU ,ALL,,,RMMRDY,MREAD,,GO TO DFAD1
 1F8: 0300 0784 0004 050D
 (2162) DFSB CPU ,ALL,,,RMMRDY,MREAD,,GO TO DFSB1
 1F9: 0300 0784 0004 0516
 (2163) DFMP CPU ,ALL,,,RMMRDY,MREAD,,GO TO DFMP1
 1FA: 0300 0784 0004 054B
 (2164) UFDV CPU ,ALL,,,RMMRDY,MREAD,,GO TO UFDV1
 1FB: 0300 0784 0004 0570
 (2165) DFCS CPU ,ALL,,,RMMRDY,MREAD,,GO TO DFCS1
 1FC: 0300 0784 0004 0584
 (2166) CAI RR ,,,JUMP ON RXM TO RXM
 1FD: 0200 J004 0007 4068
 (2167) CPU ,,,RY ICAI,,,JAMF MODAL NOP TRIGNVKEYS
 1FE: 0202 8000 0008 0400
 (2168) EJCT

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(2169) *      P3FLT,U-CODE,MHJ,FEBRUARY 1974
(2170) *      FLOATING POINT PROCESSOR - PRIME COMPUTER
(2171) *      PRIME COMPUTER INC.,SRCC0769.001
(2172) *      COPYRIGHT 1974,PRIME COMPUTER INC.,NATICK MASS.
(2173) *
(2174) *
(2175) *
(2176) *
000002  (2177) P300 XSET    2
(2178)     CLOCK
(2179)     RRCLK
(2180)     ALUCLK
(2181)     ORG    $400
(2182) *
(2183) *      FLOATING POINT GENERICS DECODE TO THIS GENERAL
(2184) * AREA.  FLOATING SKIPS ARE FIRST.
(2185) *
002000  (2186) FGEN2 EQU    *
(2187) FSEQ  RR    ,JAMF   JUMP ON EQ TO CASS
400: 0200 0600 0006 41E5
(2188) FSNE  RR    ,JAMF   JUMP ON NE TO CASS
401: 0200 0600 0004 41E5
(2189) FSMI  RR    ,JAMF   JUMP ON LT TO CASS
402: 0200 0600 0006 61E5
(2190) FSPL  RR    ,JAMF   JUMP ON GE TO CASS
403: 0200 0600 0004 61E5
(2191) FSLE  RR    ,JAMF   JUMP ON LE TO CASS
404: 0200 0600 0004 71E5
(2192) FSGT  RR    ,JAMF   JUMP ON GT TO CASS
405: 0200 0600 0006 71E5
(2193) FGEN1 RR    RCM = $37 => 11
406: F200 9A04 0002 0037
(2194)     ALU    11 AND RM => 11 C= BD01 TR= ALL
407: 8F1C 9A34 0000 0000
(2195)     ALU    11 OR   RCM = FGEN2 => RM TR= ALL
408: 934C 9204 0000 0900
(2196)     CPU    BB   RM   NX   0    0    0    0 ;
(2197)
409: EE00 0004 0000 0000
(2198)     CPU    BB   RM   NX   RF   0    M    FLTH ;
(2199)
(2200)
40A: EE00 4607 000C 0000
(2201) FAD1  CPU    BB   RCM  0    0    0    0    0 ;
(2202)
40B: F000 060C 0000 095A
(2203)     ALU    INC   RY => RY TR= ALL ,GO TO LOAD
40C: 8865 1304 0004 0419
(2204) FSB1  CPU    BB   RCM  0    0    0    0    0 ;
(2205)
40D: F000 060C 0000 095F
(2206)     ALU    INC   RY => RY TR= ALL ,GO TO LOAD
40E: 8865 1304 0004 0419
(2207) *
(2208) *      FLOATING COMPLEMENT INSTRUCTION
(2209) *
(2210)     ORG    (FGEN2 .OR. $10)
(2211) FCM   ALU    NOT FLTL => FLTL ,JUMP ON FCBIT TO FLEX
410: 82FC 5B04 0004 F4CE
(2212)     ALU    FLTL ADD RCM = 1 => FLTL C= COUT SETCC
411: 9260 5A27 0002 0001
(2213)     ALU    NOT FLTH => FLTH TR= ALL ;
(2214)
412: 83FC 4B04 0004 444B
(2215)     CPU    AL RCM  NX   INC   1    M    FLTH ;
(2216)
413: 9204 4B77 0004 044B
(2217) FRN   ALU    FLTL ADD RCM = $80 => FLTL C= COUT
414: 9260 5A24 0002 0080
(2218)     CPU    AL RCM  NX   INC   C    M    FLTH ;
(2219)
415: 9208 4B77 0004 044B
(2220) FLOT1 RR    RM => FLTL ,GO TO NRML
416: EE00 5B04 0004 044B
(2221) FMP1  CPU    BB   RCM  0    0    0    0    0 ;
(2222)
417: F000 060C 0000 087A
(2223)     ALU    INC RY => RY TR= ALL ,GO TO LOAD
418: 8865 1304 0004 0419
(2224) *
(2225) *
(2226) *      LOAD SUBROUTINE.  THIS ROUTINE ASSUMES RM CONTAINS THE
(2227) * FIRST WORD FROM MEMORY, RY CONTAINS THE ADDRESS OF THE SECOND
(2228) * WORD, AND THE STACK CONTAINS THE RETURN ADDRESS.  THE FIRST
(2229) * WORD IS PUT INTO 13 AS IS.  THE SECOND WORD IS BROKEN INTO
(2230) * THE REST OF THE FRACTION AND THE EXPONENT AND PLACED INTO
(2231) * RY AND 11 FOR THE EXPONENT, AND 12 AND RM FOR THE LOW
(2232) * ORDER PART OF THE FRACTION.
(2233) *
(2234) *
(2235) LOAD  CPU    BB   RM   ALL  0    0    M    13 ;
(2236)
419: EF00 B584 0000 0000
(2237)     RR    RCM = $FF00 => 12
41A: F200 AA04 0005 F000
(2238)     RR    RCM = $00FF => 11
41B: F200 9A04 0002 01FF
(2239)     ALU    11 AND RM => (11,RY)
41C: 8E1C 9004 0000 0000
(2240)     ALU    12 AND RM => 12 CLEARFUII

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41D: 8E1C AA0F 0000 0000
 (2241) RR 12 => RM TR= ALL ,S ON TRUE, POP
 41E: 0300 A404 000C 0004
 (2242) ORG (FGEN2 .OR. \$20)
 (2243) FLOT RR RCM = 128+30 => VSC C= BD01
 420: F200 6A34 0002 009E
 (2244) CPU RFLS 7 NX 7 0 M RB RM200
 421: 3E70 2204 0000 0000
 (2245) RR RA => RY
 422: 0200 1804 0000 0000
 (2246) RR RY => FLTH , GO TO FLOT1
 423: EA00 4B04 0004 0416
 (2247) INT ALU VSC MINUS RCM = 127 => NULL SETCC C= AOVFL
 424: 9294 6077 0002 007F
 (2248) CPU RFRS 5 NX 6 0 M FLTL ;
 (2249) RY240 NOP NOP ;
 (2250) JUMP ON LE TO CRL
 425: 5660 5304 0004 719E
 (2251) ALU VSC MINUS RCM = 128+30 => RM SETCC TR= ALL
 426: 9394 6207 0002 009E
 (2252) CPU RF RM NX 0 0 M FLTH ;
 (2253) RM200 NOP LOADRSC JUMP ON FCBIT TO CRL
 427: 0E00 420E 0004 F19E
 (2254) INT1 RR RM => RA ,JUMP ON GT TO FLEX9
 428: EE00 1804 0006 74CB
 (2255) CPU AL RY ALL BB L M RB ;
 (2256) RF240 BD01 SETCC ;
 (2257) JUMP ON LT TO INT2
 429: 8B5C 2B37 0006 64BF
 (2258) RR ,,,GO TO F1
 42A: 0200 0604 0004 0000
 (2259) FDV1 CPU BB RCM 0 0 0 0 0 ;
 (2260) 280 NOP PUSHBD DATA FDV4
 42B: F000 060C 0000 0980
 (2261) ALU INC RY => RY ,GO TO LOAD TR= ALL
 42C: AB65 1304 0004 0419
 (2262) NRM7 CPU RFRRS 1 NX 6 0 M FLTL ;
 (2263) HF200 NOP NOP
 42D: 4660 5A04 0000 0000
 (2264) ALU 11 7 RSC + L => RY
 42E: 867C 9304 0000 0000
 (2265) ALU VSC MINUS RY => VSC C= AOVFL ,GO TO FLEX8
 42F: 8A94 6B74 0004 04CD
 (2266) ORG (FGEN2 .OR. \$30)
 (2267) FRAC ALU VSC MINUS RCM = 128-31 => NULL SETCC C= AOVFL
 430: 9294 6077 0002 0061
 (2268) CPU RFRRS 5 NX 6 0 M FLTL ;
 (2269) RY240 ,,,JUMP ON LE TO CRL
 431: 5660 5304 0004 719E
 (2270) ALU VSC MINUS RCM = 128 => RM SETCC TR= ALL
 432: 4394 6207 0002 0080
 (2271) CPU AL RM NX SUB 1 XM DISABLE ;
 (2272) RM280 NOP LOADRSC ;
 (2273) GO TU FRAC1
 433: 8E95 140E 0004 0452
 (2274) *
 (2275) * DOUBLE PRECISION FLOATING POINT COMPLEMENT
 (2276) *
 (2277) DFCM ALU NOT FLTL => FLTL ,JUMP ON FCBIT TO DFLEX
 434: 82FC 5B04 0004 F5C8
 (2278) ALU NOT RB => RB
 435: 82FC 2A04 0000 0000
 (2279) ALU INC RB => RB C= COUT SETCC
 436: 8204 2A27 0000 0000
 (2280) ALU NOT FLTH => FLTH , JUMP ON NE TO DNRML
 437: 82FC 4B04 0004 453A
 (2281) ALU INC FLTL + C => FLTL C= COUT
 438: 8208 5A24 0000 0000
 (2282) ALU INC FLTH + C => FLTH C= AOVFL ;
 (2283) SETCC GO TO DNRML
 439: 8208 4B77 0004 053A
 (2284) *
 (2285) *
 (2286) * ADJUST SUBROUTINE. THIS SUBROUTINE TAKES THE TWO NUMBERS
 (2287) * FOUND IN THE FLOATING ACCUMULATOR AND THE RESULTS OF THE LOAD
 (2288) * SUBROUTINE AND MAKES THE EXPONENTS THE SAME SO THEY CAN BE ADDED
 (2289) * OR SUBTRACTED. THE TWO NUMBERS ARE LEFT IN THE FLOATING
 (2290) * ACCUMULATOR AND IN 12,13, AND RM FOR THE LOW ORDER HALF.
 (2291) * THE VSC CONTAINS THE FINAL ADJUSTED EXPONENT.
 (2292) *
 (2293) *
 (2294) ADJUST ALU VSC SUB RY => RY ,JUMP ON FCBIT TO ADJ9
 43A: 8A94 6304 0004 F443
 (2295) RR RY => NULL LOADRSC S ON EQ, POP
 43B: EA00 060E 000E 4004
 (2296) RR RCM = 32 => YSAVE
 43C: F200 CA04 0002 0020
 (2297) CPU AL RY NX SUB 1 XM DISABLE ;
 (2298) RY240 NOP NOP ;
 (2299) JUMP ON LE TO ADJ8
 43D: 8A95 1304 0004 7444
 (2300) *
 (2301) * ABOVE BRANCH IS TAKEN IF THE ACCUMULATOR MUST BE RIGHT SHIFTED.
 (2302) *
 (2303) * NOW TEST THE SHIFT COUNTER AGAINST 31 TO SEE IF
 (2304) * THE TWO NUMBERS ARE WITHIN RANGE, AND IF SO LOAD RSC AND
 (2305) * UNNORMALIZE THE NEW ARGUMENT.
 (2306) *
 (2307) *
 (2308) ALU YSAVE ADD RY => NULL SETCC ;

(2309) C= AOVFL
 43E: 8A60 C077 0000 0000
 (2310) RR RY => NULL LOADRSC
 43F: EA00 000E 0000 0000
 (2311) CPU RFRS 3 ALL 6 0 M 13 ;
 (2312) RF240 LINK NOP ;
 (2313) JUMP ON LE TO NRM1
 440: 4F60 8B44 0004 7448
 (2314) CPU RFRS 1 NX 6 0 M 12 ;
 (2315) RF240 NOP INCRSC ;
 (2316) JUMP ON RSCNEM1 TO *-1
 441: 4660 AB05 0004 9440
 (2317) RR 12 => RM ,S ON TRUE, POP
 442: 0200 A404 000C 0004
 (2318) *
 (2319) * NEW ARGUMENT IS GREATER OR EQUAL TO ACC.
 (2320) *
 (2321) *
 (2322) ADJ9 ALU ZERO MINUS RY => RY ,GO TO MOVE
 443: 8A95 1304 0004 0449
 (2323) ADJ8 ALU INC 13 + 0 => NULL SETCC
 444: 8200 B007 0000 0000
 (2324) ALU YSAVE SUB RY => NULL SETCC ;
 (2325) S ON EQ POP
 445: 8A94 C607 000E 4004
 (2326) CPU RFRS 3 ALL 6 0 M FLTH ;
 (2327) RF240 LINK NOP ;
 (2328) JUMP ON LE TO MOVE
 446: 4F60 4B44 0004 7449
 (2329) CPU RFRS 1 NX 6 0 M FLTL ;
 (2330) RF240 NOP INCRSC ;
 (2331) JUMP ON RSCNEM1 TO *-1
 447: 4660 5B05 0004 9446
 (2332) ALU VSC ADD RY => VSC ,S ON TRUE,POP
 448: 8A60 6B04 000C 0004
 (2333) MOVE CPU BB RCM NX ZERO L M FLTL ;
 (2334) RF200 ,,DATA 0
 449: F23C 5A04 0002 0100
 (2335) CPU AL 0 NX ZERO L M FLTH ;
 (2336) RF240 ,,GO TO MOVE-1
 44A: 823C 4B04 0004 0448
 (2337) *
 (2338) *
 (2339) * NORMALIZE SUBROUTINE. THIS ROUTINE TAKES THE FLOATING
 (2340) * ACCUMULATOR AND NORMALIZES THE RESULTS, ADJUSTING THE
 (2341) * VSC AS NEEDED. THE ROUTINE EXPECTS THE CARRY BIT TO
 (2342) * BE SET IF THE ACCUMULATOR IS ALREADY OVER SHIFTED. THAT
 (2343) * IS, THE VALUE MUST BE RIGHT SHIFTED ONE PLACE.
 (2344) * IF THE CBIT CAN BE SET, THEN THE CONDITION CODE MUST ALSO
 (2345) * BE SET TO REFLECT THE VALUE OF THE FACUM.
 (2346) * IF OVERFLOW OCCURRED, THE CONDITION CODE WILL IN FACT SHOW
 (2347) * THE REVERSE OF THE CORRECT SIGN. NRML DEPENDS ON THIS.
 (2348) * THE ROUTINE THEN EXITS TO THE FETCH CYCLE.
 (2349) *
 (2350) *
 (2351) NRML CPU RFLS 3 ALL 7 0 M FLTH ;
 (2352) RY240 SOVFL ,JUMP ON FCBIT TO NRM10
 44B: 2F70 4364 0004 F452
 (2353) ALU CON 0 => RY C= BD01 ,JUMP ON FCBIT TO F1
 44C: 823C 0334 0004 F000
 (2354) RR RCM = -32 => 11 LOADRSC
 44D: F200 9A0E 0003 FEE0
 (2355) NRM18 CPU RFLS 7 ALL 7 0 M FLTL ;
 (2356) RF240 LINK ,JUMP ON FCBIT TO NRM7
 44E: 3F70 5B44 0004 F420
 (2357) CPU RFLS 3 NX 7 0 M FLTH ;
 (2358) RF240 NOP INCRSC ;
 (2359) JUMP ON RSCNEM1 TO NRM17
 44F: 2E70 4B05 0004 9451
 (2360) RR RCM = 0 => VSC C= BD01 JAMF
 450: F200 6A30 0002 0100
 (2361) NRM17 CPU RFLS 3 ALL 7 0 M FLTH ;
 (2362) RY240 SOVFL ,GO TO NRM18
 451: 2F70 4364 0004 044E
 (2363) NRM10 ALU VSC PLUS RCM = 1 => VSC C= AOVFL
 452: 9260 6A74 0002 0001
 (2364) CPU RFRS 5 ALL 6 0 M FLTH ;
 (2365) RF240 LINK NOP ;
 (2366) JUMP ON LT TO *+2
 453: 5760 4B44 0006 6455
 (2367) ALU FLTH OR RCM = \$8000 => FLTH
 454: 924C 4A04 0001 0100
 (2368) CPU RFRS 1 ALL 6 0 M FLTL ;
 (2369) RF240 NOP JAMF ;
 (2370) JUMP ON FCBIT TO FLEX
 455: 4760 5B00 0004 F4CE
 (2371) *
 (2372) *
 (2373) * EXECUTION OF THE FLOATING POINT MEMORY REFERENCE
 (2374) * INSTRUCTIONS.
 (2375) *
 (2376) *
 (2377) FLD1 ALU INC RY => RY
 456: 8A65 1304 0000 0000
 (2378) CPU BB RCM ALL 0 0 M FLTL ;
 (2379) RMRFMRDY MREAD ,DATA \$FF00
 457: F300 5584 0003 FF00
 (2380) ALU FLTL AND RM => FLTL
 458: 8E1C 5A04 0000 0000
 (2381) ALU VSC AND RM => VSC JAMF

459: 8E1C 6A00 0000 0000
 (2382) FAD4 CPU BB RCM 0 0 0 0 0 ;
 (2383) 280 NOP PUSHBD DATA FAD6
 45A: F000 060C 0000 095C
 (2384) ALU VSC MINUS RY => NULL SETCC C= AOVFL GO TO ADJUST
 45B: 8A94 6677 0004 043A
 (2385) FAD6 ALU FLTL ADD RM => FLTL C= COUT
 45C: 8E60 5A24 0000 0000
 (2386) RR 13 => RM
 45D: 0200 B204 0000 0000
 (2387) ALU FLTH ADD RM + C => FLTH C= AOVFL SETCC ;
 (2388) GO TO NRML
 45E: 8E68 4B77 0004 044B
 (2389) FSB4 CPU BB RCM 0 0 0 0 0 ;
 (2390) 280 NOP PUSHBD DATA FSB6
 45F: F000 060C 0000 0661
 (2391) ALU VSC MINUS RY => NULL SETCC C= AOVFL GO TO ADJUST
 460: 8A94 6677 0004 043A
 (2392) FSB6 ALU FLTL SUB RM => FLTL C= COUT
 461: 8E94 5A24 0000 0000
 (2393) RR 13 => RM
 462: 0200 B204 0000 0000
 (2394) ALU FLTH SUB RM + C => FLTH C= AOVFL SETCC ;
 (2395) GO TO NRML
 463: 8E98 4B77 0004 044B
 (2396) FST1 ALU VSC AND RCM = \$FF00 => NULL SETCC C= MWRITE TR= ALL
 464: 931C 6087 0003 FF00
 (2397) ALU INC RY => RY
 465: 8A65 1304 0000 0000
 (2398) ALU VSC AND RCM = \$00FF => RM C= B001
 466: 921C 6234 0002 01FF
 (2399) RR RM => 11
 467: EE00 9A04 0000 0000
 (2400) ALU FLTL AND RCM = \$FF00 => RM
 468: 921C 5204 0003 FF00
 (2401) ALU 11 OR RM => RM C= MWRITE TR= ALL ;
 (2402) JAMF JUMP ON NE TO FLEX1
 469: BF4C 9480 0004 44CF
 (2403) FDV13 CPU AL RM NX DEC 0 M VSC ;
 (2404) RF240 AOVFL ,GO TO FCM
 46A: BEF0 6B74 0004 0410
 (2405) *
 (2406) *
 (2407) * FLOATING COMPARE. THIS INSTRUCTION MUST COMPARE: FIRST,
 (2408) * SIGN, THEN EXPONENT, FINALLY UPPER THEN LOWER MAGNITUDE.
 (2409) FCS1 ALU INC RY => RY ,JUMP ON LT TO FCS2
 46B: 8A65 1304 0006 6477
 (2410) * SIGNS ARE EQUAL
 (2411) CPU BB RM ALL BB L M 13 ;
 (2412) RMRFRMDY MREAD SETCC
 46C: EF5C B587 0000 0000
 (2413) ALU 11 AND RM => RY ,JUMP ON LT TO FCS3
 46D: 8E1C 9304 0006 64C8
 (2414) * EXPONENT TEST IS BACKWARDS FOR NEG #'S.
 (2415) * TEST FOR ZERO IN EITHER ARGUMENT.
 (2416) ALU INC FLTH + 0 => NULL SETCC JUMP ON EQ TO FCS7
 46E: 8200 4607 0006 4479
 (2417) ALU VSC MINUS RY => NULL SETCC C= AOVFL ;
 (2418) TR= ALL JUMP ON EQ TO FCS2+1
 46F: 8894 6677 0006 4478
 (2419) FCS4 ALU 11 7 RM => 11 ,JUMP ON FCBIT TO FCS2+1
 470: 8E7C 9804 0004 F478
 (2420) RR RX => RX ,JUMP ON GT TO F1
 471: 0200 0804 0006 7000
 (2421) FCS5 RR 13 => RM NOP JUMP ON NE TO FCS2+1
 472: 0200 8404 0004 4478
 (2422) * EXPONENTS EQUAL
 (2423) ALU FLTH MINUS RM => NULL SETCC
 473: 8E94 4007 0000 0000
 (2424) RR 11 => RM NOP TR= ALL JUMP ON GT TO F1
 474: 0300 9404 0006 7000
 (2425) ALU FLTL MINUS RM => NULL C= COUT SETCC ;
 (2426) JUMP ON LT TO FCS2+1
 475: 8E94 5627 0006 6478
 (2427) * HIGH ORDER MAGNITUDES ARE EQUAL
 (2428) RR ,,,JUMP ON EQ TO CASS
 476: 0200 0604 0006 41E5
 (2429) FCS2 RR RX => RX ,JUMP ON FCBIT TO F1
 477: 0200 0804 0004 F000
 (2430) ALU RP PLUS RCM = 2 => RP JAMF
 478: 9260 7A00 0002 0002
 (2431) FCS7 RR RX => RX JAMF JUMP ON EQ TO CASS
 479: 0200 0800 0006 41E5
 (2432) *
 (2433) *
 (2434) * FLOATING POINT MULTIPLY. THE ALGORITHM USED IS BASICALLY THAT
 (2435) * OF SHIFT AND ADD. ONLY 24 ITERATIONS ARE REQUIRED FOR FULL
 (2436) * ACCURACY. IN ADDITION, THE FIRST 7 ITERATIONS ARE SINGLE
 (2437) * PRECISION ONLY. THE REMAINING 16 ARE FULL DOUBLE
 (2438) * PRECISION.
 (2439) *
 (2440) *
 (2441) FMP4 ALU 11 MINUS RCM = 128 => RY
 47A: 4294 9304 0002 0050
 (2442) ALU VSC PLUS RY => VSC C= AOVFL
 47B: 8A60 6A74 0000 0000
 (2443) RR FLTH => RM
 47C: 0200 4204 0000 0000
 (2444) RR FLTL => RY ,JUMP ON FCBIT TO FLEX
 47D: 0200 5304 0004 F4CE

(2445) CPU AL RCM ALL ZERO L M FLTH ;
 (2446) RF200 NOP LOADRSC DATA -7

47E: 933C 4A0E 0003 FFF9
 (2447) CPU ALFB 0 NONE RF 0 M 12 ;
 (2448) RF200

47F: 6000 AA04 0000
 (2449) CPU RFRS 0 NONE 6 0 M 12 ;
 (2450) RF200 LINK

480: 4060 AA44 0000
 (2451) * STD MPY FOR FIRST 7 BITS. (SORT OF)

(2452) CPU ALRS RM NX ADD 0 M FLTH ;
 (2453) RF240 NOP ,EAC MPYLOGIC

481: CE60 4B04 0008 C000
 (2454) CPU RFRS 0 ALL 6 0 M 12 ;
 (2455) RF240 LINKS INCRSC ;
 (2456) JUMP ON RSCNEM1 TO *+1

482: 4360 AH15 0004 9481
 (2457) * CBIT = RF16 = LAST BIT FROM 12 (NEW LOW)

(2458) CPU AL RCM ALL ZERO L M FLTL ;
 (2459) RF200 NOP LOADRSC ;
 (2460) DATA -16

483: 933C 5A0E 0003 FFFF
 (2461) * SET UP FOR FULL DOUBLE PRECISION MULTIPLY FOR THE

(2462) * REMAINING PORTION OF THE LOOP. (16 TIMES + SUB)

(2463) *

(2464) RR ,,, JUMP ON FCBIT TO FMPS

484: 0200 0604 0004 F487
 (2465) * SHIFT ONLY

(2466) CPU RFRS 3 ALL 6 0 M FLTH ;
 (2467) RF240 LINK NOP GO TO FMP7

485: 4F60 4B44 0004 0489
 (2468) FMP6 CPU RFRS 5 ALL 6 0 M 13 ;
 (2469) RF280 NOP NOP ;
 (2470) JUMP ON NOTRF16 TO *+1

486: 5760 BC04 0007 7485
 (2471) FMPS ALU FLTL PLUS RY => FLTL C= COUT

487: 8A60 5A24 0000 0000
 (2472) CPU ALRS RM ALL 6 C M FLTH ;
 (2473) RF240 LINK NOP

488: CF68 4B44 0000 0000
 (2474) FMP7 CPU RFRS 1 ALL 6 0 M FLTL ;
 (2475) RF240 NOP INCRSC ;
 (2476) JUMP ON RSCNEM1 TO FMP6

489: 4760 5B05 0004 9486
 (2477) *TEST FOR LAST MOVE == ZERO CBIT

(2478) CPU RF 0 NX 0 0 M 13 ;
 (2479) RF280 BD01 NOP ;
 (2480) JUMP ON NOTRF16 TO NRML

48A: 0200 BC34 0007 744B
 (2481) * FINAL SUBTRACT

(2482) ALU FLTL MINUS RY => FLTL C= COUT

48B: 8A94 5A24 0000 0000
 (2483) ALU FLTH MINUS RM + C => FLTH C= AOVFL ;
 (2484) SETCC GO TO NRML

48C: 8E98 4B77 0004 044H
 (2485) *

(2486) *

(2487) * DIVIDE INSTRUCTION. ROUTINE EXECUTES A NON-PREFORMING

(2488) * STYLE DIVIDE. BEFORE STARTING THE LOOP, THE NUMBERS ARE

(2489) * BOTH MADE POSITIVE. THERE ARE 31 ITERATIONS OF THE

(2490) * DIVIDE LOOP BUT ONLY 17 OF THEM ARE IN FACT FULL DOUBLE

(2491) * PRECISION, THE REST BEING SINGLE PRECISION.

(2492) *

(2493) *

(2494) *

(2495) FDV4 ALU INC 13 + 0 => RM SETCC

48D: 8200 B207 0000 0000
 (2496) ALU FLTH XOR RM => NULL SETCC ;
 (2497) JUMP ON EQ TO FLEX2

48E: 8E6C 4B07 0006 4401
 (2498) * DIVISION BY ZERO OVERFLOW EXIT.

(2499) * NOW MOVE EXPONENT TO RY

(2500) RR RCM = -17 => NULL LOADRSC

48F: F200 000E 0003 FEEF
 (2501) * DO EXPONENT CALCULATION

(2502) ALU 11 MINUS RCM = 129 => RY

490: 9294 4304 0002 0181
 (2503) ALU VSC MINUS RY => VSC C= AOVFL ;
 (2504) , JUMP ON GE TO *+2

491: 8A94 6B74 0004 6493
 (2505) * SET FUII AS A 'COMPLEMENT RESULTS' FLAG

(2506) RR ,,,EAC SETFUII

492: 0200 0004 000A 8000
 (2507) * SKIP ON LIKE SIGNS, SET UP FOR RM CUMP TEST.

(2508) ALU INC RM + 0 => NULL SETCC ;
 (2509) JUMP ON FCBIT TO FLEX

493: 8E61 1607 0004 F4CE
 (2510) RR 12 => RY , JUMP ON GE TO FDV5

494: 0200 A304 0004 6498
 (2511) * MUST TWO'S COMPLEMENT RM|RY .

(2512) ALU ZERO MINUS RY => NULL C= COUT

495: 8A95 1024 0000 0000
 (2513) ALU ZERO MINUS RM + C => RM SETCC

496: 8E99 1207 0000 0000
 (2514) ALU ZERO MINUS RY => RY , JUMP UN LT TO FDV13

497: 8A95 1304 0006 646A
 (2515) * ABOVE EXIT IS FOR -(1/2)*N---COMPLEMENT THE ACCUMULATOR

(2516) * AND EXIT

(2517) * TEST ACC FOR NEG

(2518) FDV5 ALU INC FLTH + 0 => NULL SETCC

498: 8200 4007 0000 0000
 (2519) ALU CON 0 => 12 , JUMP ON GE TO FDV6
 499: 823C AB04 0004 64AA
 (2520) * COMPLEMENT ACC
 (2521) ALU NOT FLTL => FLTL
 49A: 82FC 5A04 0000 0000
 (2522) ALU INC FLTL => FLTL SETCC
 49B: 8204 5A07 0000 0000
 (2523) ALU NOT FLTH => FLTH , JUMP ON NE TO FDV6
 49C: 82FC 4B04 0004 44AA
 (2524) ALU INC FLTH => FLTH SETCC
 49D: 8204 4A07 0000 0000
 (2525) RR RX => RX , JUMP ON GE TO FDV6
 49E: 0200 0B04 0004 64AA
 (2526) ALU VSC PLUS RCM = 1 => VSC C= ADVFL
 49F: 9260 6A74 0002 0001
 (2527) CPU RFRS 5 ALL 6 0 M FLTH ;
 (2528) RF240 , JUMP ON FCBIT TO FLEX
 4A0: 5760 4B04 0004 F4CE
 (2529) RR RX => RX , GO TO FDV6
 4A1: 0200 0B04 0004 04AA
 (2530) * FINNALLY DOUBLE PRECISION DIVIDE LOOP CAN BE EXECUTED.
 (2531) *
 (2532) * TEST FOR SUB OR SHIFT AND SHIFT IN
 (2533) * A QUOTIENT BIT FROM THE LAST ITTERATION.
 (2534) *
 (2535) FDV10 CPU RFLS 3 NX 3 0 M 13 ;
 (2536) RF240 NOP INCRSC ;
 (2537) JUMP ON LT TO FDV7
 4A2: 2E30 BB05 0006 64A5
 (2538) * IF SHIFT, GO TO SHIFT. THEN, TEST LOW ORDER HALF.
 (2539) * ABORT LOW TEST IF HIGH TEST WAS CONCLUSIVE.
 (2540) ALU FLTL MINUS RY => NULL , ;
 (2541) C= COUT JUMP ON GT TO FDV8
 4A3: 8A94 5624 0006 74A7
 (2542) * LOW TEST REQUIRED - SHIFT ON LT
 (2543) RR , JUMP ON FCBIT TO FDV8
 4A4: 0200 0B04 0004 F4A7
 (2544) * SHIFT STEP PROCESSING -- NO SUBTRACT
 (2545) *
 (2546) FDV7 CPU RFLS 7 NX 7 0 M FLTL ;
 (2547) RF200 LINK NOP
 4A5: 3E70 5A44 0000 0000
 (2548) CPU RFLS 3 ALL 7 0 M FLTH ;
 (2549) RF240 LINK NOP GO TO FDV6
 4A6: 2F70 4B44 0004 04AA
 (2550) * PERFORM SUBTRACT AND SHIFT
 (2551) FDV8 ALU FLTL MINUS RY => FLTL C= COUT
 4A7: 8A94 5A24 0000 0000
 (2552) CPU RFLS 7 ALL 7 0 M FLTL ;
 (2553) RF200 LINK NOP
 4A8: 3F70 5A44 0000 0000
 (2554) CPU ALLS RM ALL SUB C M FLTH ;
 (2555) RF240 LINK
 4A9: AF98 4B44 0000 0000
 (2556) FDV6 ALU FLTH MINUS RM => NULL SETCC ;
 (2557) JUMP ON RSCNEM1 TO FDV10
 4AA: 8E94 4B07 0004 94A2
 (2558) CPU RFLS 3 NX 3 0 M FLTL ;
 (2559) RF200
 4Ab: 2E30 5A04 0000 0000
 (2560) *DOUBLE PRECISION HALF FINISHED. NOW DO SINGLE PRECISIONPART.
 (2561) FDV11 RR RCM = -15 => NULL LOADRSC
 4AC: F200 000E 0003 FEF1
 (2562) CPU AL RCM NX AND L M 13 ;
 (2563) RY240 NOP SETCC DATA \$FFFF
 4AD: 921C B307 0000 FFFF
 (2564) CPU ALLS RM ALL SUB 1 M FLTH ;
 (2565) RF280 LINK , EAC DIVLOGIC
 4AE: AF94 4C44 0009 0000
 (2566) CPU RFLS 3 ALL 7 0 M FLTL ;
 (2567) RF240 LINK INCRSC ;
 (2568) JUMP ON RSCNEM1 TO *-1
 4AF: 2F70 5B45 0004 94AE
 (2569) *RESULTS OF DIVIDE NOW IN RY AND FLTL
 (2570) RR RY => FLTH C= BD01 , JUMP ON FUII TO FCM
 4B0: EA00 4B34 0005 5410
 (2571) CPU RFLS 3 ALL 7 0 M FLTH ;
 (2572) RY240 SOVFL ,GO TO NRML+1
 4B1: 2F70 4364 0004 044C
 (2573) * PATCH SPACE
 (2574) FRAC1 RR RY => RB TR= ALL C= BD01
 4B2: EB00 2A34 0000 0000
 (2575) RR FLTH => RY ,JUMP ON LE TO FRAC3
 4B3: 0200 4304 0004 74BC
 (2576) RR RY => RA
 4B4: EA00 1A04 0000 0000
 (2577) ALU VSC MINUS RCM = 128+31 => NULL ;
 (2578) SETCC TR= ALL
 4B5: 9594 6007 0002 014F
 (2579) RR RM => NULL LOADRSC JUMP ON GT TO CRL
 4B6: EE00 0B0E 0006 719E
 (2580) CPU RFLS 7 ALL 3 0 M RB ;
 (2581) RF200 LINK
 4B7: 5F30 2A44 0000 0000
 (2582) CPU RFLS 3 NX 3 0 M RA ;
 (2583) RF240 NOP INCRSC ;
 (2584) JUMP ON RSCNEM1 TO *-1
 4B8: 2E30 1B05 0004 94B7
 (2585) FRAC2 ALU RA XOR RCM = \$8000 => NULL SETCC

4B9: 926C 1007 0001 0100
 (2586) ALU INC RB + 0 => NULL SETCC ;
 (2587) JUMP ON NE TO F1
 4BA: 8200 2607 0004 4000
 (2588) RR RX => RX JAMF JUMP ON EQ TO CRA.
 4BB: 0200 0800 0006 41CE
 (2589) FRAC3 CPU BB RY ALL ZERO L M RA ;
 (2590) RF240 NOP SETCC ;
 (2591) JUMP ON EQ TO FRAC2
 4BC: EB3C 1807 0006 44B9
 (2592) CPU RFRS 3 ALL 6 0 M RA ;
 (2593) RF200 LINK
 4BD: 4F60 1A44 0000 0000
 (2594) CPU RFRS 0 NX 6 0 M RB ;
 (2595) RF240 NOP INCRSCF ;
 (2596) JUMP ON RSCNEM1 TO *=1
 4BE: 4260 2801 0004 94BD
 (2597) INT2 CPU RFRS 3 ALL 6 0 M RA ;
 (2598) RF240 LINK ,JUMP ON FCBIT TO INT6
 4BF: 4F60 1B44 0004 F4C7
 (2599) CPU RFRS 0 NX 6 0 M RB ;
 (2600) RF240 LINKS INCRSC ;
 (2601) JUMP ON RSCNEM1 TO *=1
 4C0: 4260 2815 0004 94BF
 (2602) ALU CON ZERO => NULL C= BD01 ,JUMP ON FCBIT TO INT4
 4C1: 823C 0634 0004 F4C6
 (2603) INT5 RR ,,JAMF JUMP ON LT TO *=1
 4C2: 0200 0600 0006 64C3
 (2604) ALU RB PLUS RCM = 1 => RB C= AOVFL
 4C3: 9260 2A74 0002 0001
 (2605) ALU INC RA + C => RA
 4C4: 8208 1A04 0000 0000
 (2606) ALU RB AND RCM = \$7FFF => RB C= BD01 JAMF
 4C5: 921C 2A30 0000 FFFF
 (2607) INT4 ALU INC RA + 0 => NULL SETCC GO TO INT5
 4C6: 8200 1607 0004 04C2
 (2608) INT6 ALU INC RA + 0 => NULL SETCC GO TO INT2+1
 4C7: 8200 1607 0004 04C0
 (2609) FCS3 ALU VSC MINUS RY => NULL C= AOVFL SETCC
 4C8: 8A94 6077 0000 0000
 (2610) ALU 11 7 RM => 11 , JUMP ON FCBIT TO F1
 4C9: 8E7C 9B04 0004 F000
 (2611) RR RX => RX JAMF JUMP ON GE TO FC85
 4CA: 0200 0B00 0004 0472
 (2612) * FLOATING POINT EXCEPTION VECTOR. ENTRY POINTS ARE:
 (2613) * FLEX OVERFLOW
 (2614) * FLEX1 STORE EXCEPTION
 (2615) * FLEX2 DIVIDE BY ZERO
 (2616) * FLEX9 INT EXCEPTION
 (2617) *
 (2618) * REGISTER 11 IS USED TO SHOW THE TYPE OF EXCEPTION:
 (2619) * \$100 OVERFLOW
 (2620) * \$101 DIVIDE BY ZERO
 (2621) * \$102 STORE EXCEPTION REGISTER 12 = EFFECTIVE ADDRESS
 (2622) * \$103 INT EXCEPTION
 (2623) *
 (2624) * IF 74 IS ZERO, THE VECTOR ABORTS, EXECUTING THE NEXT
 (2625) * SEQUENTIAL INSTRUCTION WITH THE CBIT SET.
 (2626) * . THE ABSOLUTE MAPPED VECTOR HANDLING
 (2627) * IS IDENTICAL TO THAT OF THE UII.
 (2628) *
 (2629) *
 (2630) FLEX9 RR RCM = \$FFFC C= BD01 TR= ALL => 11
 4C8: F300 9A34 0003 FFEC
 (2631) RR ,,GO TO FLEX4
 4C9: 0200 0604 0004 04D2
 (2632) FLEX8 RR ,,JAMF JUMP ON FCBIT TO FLEX
 4C0: 0200 0600 0004 F4CE
 (2633) FLEX ALU CON MINUS1 => 11 C= BD01 , GO TO FLEX4
 4CE: 8200 9B34 0004 04D2
 (2634) FLEX1 PR RCM = \$FFFD => 11 C= BD01
 4CF: F200 9A34 0003 FEFD
 (2635) PR RY => 12 , GO TO FLEX4
 4D0: EA00 A804 0004 04D2
 (2636) FLEX2 RR RCM = \$FFFF => 11 C= BD01
 4D1: F200 9A34 0005 FEFE
 (2637) FLEX4 ALU 11 XOR RCM = \$FEFF => 11
 4D2: 9260 9A04 0001 F0FF
 (2638) FLEX5 RR RCM = '74 => RY
 4D3: F200 0804 0002 013C
 (2639) CPU AL 0 ALL DEC 0 M EAS ;
 (2640) RMRFMRDY ARREAD ,EAC CLRNVKEYS TRIGNVKEYS
 4D4: B3F0 A5C4 0004 0400
 (2641) CPU AL RM NX BB L 0 0 ;
 (2642) RY240 NOP SETCC
 4D5: 8E5C 0307 0000 0000
 (2643) CPU AL RY NX INC 0 M RP ;
 (2644) RM280 NOP JAMF ;
 (2645) JUMP ON NE TO JST1
 4D6: 8A00 7400 0004 4150
 (2646) *
 (2647) * DOUBLE PRECISION EXECUTION SPACE. FOR EASE OF DEBUG,
 (2648) * EXECUTION BEGINS AT \$500.
 (2649) *
 (2650) ORG \$500
 500: 8A65 1304 0000 0000
 (2651) DFLD1 ALU INC RY => RY
 (2652) CPU BB RM ALL 0 0 M FLTH ;
 (2653)
 501: EF00 4584 0000 0000

502: 8A65 1304 0000 0000 (2654) ALU INC RY => RY
 (2655) CPU BB RM ALL 0 0 M FLTL ;
 (2656) RMRFMRDY MREAD
 503: EF00 5584 0000 0000 (2657) ALU INC RY => RY
 504: 8A65 1304 0000 0000 (2658) CPU BB RM ALL 0 0 M RB ;
 (2659) RMRFMRDY MREAD
 505: EF00 2584 0000 0000 (2660) RR RM => VSC , GO TO F1
 506: E600 6B04 0004 0000 (2661) DFST1 ALU INC RY => RY
 507: 8A65 1304 0000 0000 (2662) CPU RF,,ALL,,,M,FLTL,RM280,MWRITE
 508: 0300 54B4 0000 0000 (2663) ALU INC RY => RY
 509: 8A65 1304 0000 0000 (2664) CPU RF,,ALL,,,M,RB,RM280,MWRITE
 50A: 0300 24B4 0000 0000 (2665) ALU INC RY => RY
 50B: 8A65 1304 0000 0000 (2666) CPU RF,,ALL,,,M,VSC,RM280,MWRITE,JAMF
 50C: 0300 64B0 0000 0000 (2667) DFAD1 CPU BB RCM NONE 0 0 0 0 ;
 (2668) 280 ,PUSHBD DATA DFAD4
 50D: F000 060C 0002 050F (2669) ALU INC RY => RY ,GO TO DGET
 50E: 8A65 1304 0004 051F (2670) DFAD4 CPU BB RCM NONE 0 0 0 0 ;
 (2671) 280 ,PUSHBD DATA DFAD6
 50F: F000 060C 0002 0811 (2672) ALU VSC MINUS RM => RM SETCC C= AOVFL ;
 (2673) GO TO DFIX
 510: 8E94 6477 0004 0524 (2674) DFAD6 ALU RB PLUS RY => RB C= COUT
 511: 8A60 2A24 0000 0000 (2675) RR 12 => RM
 512: 0200 A204 0000 0000 (2676) ALU FLTL PLUS RM + C' => FLTL C= COUT TR= ALL
 513: 8F68 5A24 0000 0000 (2677) RR 13 => RM
 514: 0200 B204 0000 0000 (2678) ALU FLTH PLUS RM + C => FLTH C= AOVFL ;
 (2679) SETCC GO TO DNRML
 515: 8E68 4B77 0004 053A (2680) DFSB1 CPU BB RCM NONE 0 0 0 0 ;
 (2681) 280 ,PUSHBD DATA DFSB4
 516: F000 060C 0002 0818 (2682) ALU INC RY => RY ,GO TO DGET
 517: 8A65 1304 0004 051F (2683) DFSB4 CPU BB RCM NONE 0 0 0 0 ;
 (2684) 280 ,PUSHBD DATA DFSB6
 518: F000 060C 0002 0A1A (2685) ALU VSC MINUS RM => RM C= AOVFL ;
 (2686) SETCC GO TO DFIX
 519: 8E94 6477 0004 0524 (2687) DFSB6 ALU RB MINUS RY => RB C= COUT TR= ALL
 51A: 8B94 2A24 0000 0000 (2688) RR 12 => RM
 51B: 0200 A204 0000 0000 (2689) ALU FLTL MINUS RM + C => FLTL C= COUT TR= ALL
 51C: 8F98 5A24 0000 0000 (2690) RR 13 => RM
 51D: 0200 B204 0000 0000 (2691) ALU FLTH MINUS RM + C => FLTH C= AOVFL ;
 (2692) SETCC GO TO DNRML
 51E: 8E98 4B77 0004 053A (2693) *
 (2694) *
 (2695) * SUBROUTINE DLOAD. ROUTINE LOADS THE FULL 4 WORD
 (2696) * FLOATING POINT ARGUMENT INTO 13,12,11,AND RM, RESPECTIVLY.
 (2697) * THE SUBROUTINE EXPECTS THE FIRST WORD TO BE IN RM. RY IS
 (2698) * ASSUMED TO CONTAIN A POINTER TO THE SECOND WORD IN MEMORY.
 (2699) * NOTE THAT THE EXPONENT IS LEFT IN RM.
 (2700) *
 (2701) *
 (2702) DGET CPU BB RM ALL 0 0 M 13 ;
 (2703) RMRFMRDY MREAD
 51F: EF00 6584 0000 0000 (2704) ALU INC RY => RY
 520: 8A65 1304 0000 0000 (2705) CPU BB RM ALL 0 0 M 12 ;
 (2706) RMRFMRDY MREAD
 521: EF00 A584 0000 0000 (2707) ALU INC RY => RY
 522: 8A65 1304 0000 0000 (2708) CPU BB RM ALL 0 0 M 11 ;
 (2709) RMRFMRDY MREAD ,S UN TRUE, POP
 523: EF00 9584 000C 0004 (2710) *
 (2711) *
 (2712) * ADJUST SUBROUTINE. CALLED DFIX, THIS ROUTINE ADJUSTS TWO
 (2713) * NUMBERS OF UNEQUAL EXPONENTS BY 'UN-NORMALIZING' THE
 (2714) * NUMBER WITH SMALLER EXPONENT. IF THE TWO NUMBERS ARE TOO
 (2715) * FAR APART, AND THE NEW ARGUMENT IS SMALLER, THE ROUTINE
 (2716) * ABORTS, RETURNING TO THE FETCH CYCLE. IF THE OLD ARGUMENT
 (2717) * IS THE SMALLER, THEN IT IS ZEROD, AND THE EXPONENT (VSC)
 (2718) * IS MADE EQUAL TO THAT OF THE NEW ARGUMENT.
 (2719) *

(2720) * IF THE TWO NUMBERS CAN BE COMBINED, VSC IS SET TO THE
 (2721) * LARGER EXPONENT, AND THE SMALLER NUMBER IS SHIFTED RIGHT.
 (2722) *
 (2723) * RY IS ALWAYS LOADED WITH THE LSW OF THE NEW ARGUMENT.
 (2724) *
 (2725) DFIX ALU ZERO MINUS RM => RM LOADRSC TR= ALL ;
 (2726) JUMP ON FC8IT TO DFIX1
 524: 8F95 140E 0004 F5EF
 (2727) RR 11 => RY TR= ALL ,S ON EQ TO POP
 525: 0300 9304 000E 4004
 (2728) RR RCM = 48 => YSAVE
 526: F200 CA04 0002 0130
 (2729) DFIX3 ALU INC 13 + 0 => NULL SETCC ;
 (2730) JUMP ON LT TO DFIX2
 527: 8200 8607 0006 0552
 (2731) * NEW ARGUMENT IS SMALLER, SHIFT IT RIGHT OR ABORT.
 (2732) *
 (2733) ALU INC FLTH + 0 => NULL SETCC
 528: 8200 4007 0000 0000
 (2734) ALU YSAVE PLUS RM => NULL SETCC TR= ALL ;
 (2735) JUMP ON EQ TO DFIX4-1
 529: 8F60 C607 0006 4556
 (2736) ALU ZERO PLUS RM => NULL C= ADVFL ;
 (2737) LOADRSC JUMP ON LE TO DNRML
 52A: 8E61 167E 0004 753A
 (2738) *
 (2739) * DE-NORMALIZE CAN BE DONE.
 (2740) *
 (2741) CPU RFRS 3 ALL 6 0 M 13 ;
 (2742) RF200 LINK
 52B: 4F60 5A44 0000 0000
 (2743) CPU RFRS 1 NX 6 0 M 12 ;
 (2744) RF200 LINK
 52C: 4660 AA44 0000 0000
 (2745) CPU RFRS 1 NX 6 0 M 11 ;
 (2746) RF240 NOP INCRSC ;
 (2747) JUMP ON RSCNEM1 TO **2
 52D: 4660 9B05 0004 952B
 (2748) RR 11 => RY , S ON TRUE, POP
 52E: 0200 9304 000C 0004
 (2749) * IF EXPONENT OVERFLOW IS DETECTED HERE, ONE OF THE
 (2750) * TWO NUMBERS WILL BE PRESERVED UNCHANGED BECAUSE THE
 (2751) * EXPONENTS ARE TOO FAR APART FOR AN ADD OR SUBTRACT.
 (2752) * THEREFORE, FORCE THE SIGN THE RIGHT WAY AND ALSO FORCE
 (2753) * THE MAXIMUM EXPONENT DIFFERENCE ALLOWED TO BE ZERO
 (2754) * TO ALLOW THE REST OF THE ADJUST ROUTINE TO ACT CORRECTLY.
 (2755) *
 (2756) *
 (2757) DFIX1 RR RCM = \$8000 => YSAVE
 52F: F200 CA04 0001 0100
 (2758) ALU YSAVE MINUS RM => NULL SETCC
 530: 8E94 C007 0000 0000
 (2759) RR 11 => RY , GO TO DFIX3
 531: 0200 9304 0004 0527
 (2760) *
 (2761) *
 (2762) * TEST FOR VALID ALIGN. IF VALID, UN-NORMALIZE THE
 (2763) * FACC. IF NOT VALID, ZERO THE FACC AND RETURN.
 (2764) * IN BOTH CASES, ADD THE EXPONENT DIFFERENCE TO THE
 (2765) * VSC.
 (2766) *
 (2767) *
 (2768) DFIX2 ALU YSAVE MINUS RM => NULL SETCC TR= ALL ;
 (2769) S UN EQ, POP
 532: 8F94 C607 000E 4004
 (2770) CPU RFRS 3 ALL 6 0 M FLTH ;
 (2771) RF240 LINK NOP ;
 (2772) JUMP ON LE TO DFIX4
 533: 4F60 4B44 0004 7537
 (2773) CPU RFRS 1 NX 6 0 M FLTL ;
 (2774) RF200 LINK
 534: 4660 5A44 0000 0000
 (2775) CPU RFRS 1 NX 6 0 M RB ;
 (2776) RF240 NOP INCRSC ;
 (2777) JUMP ON RSCNEM1 TO **2
 535: 4660 2B05 0004 9555
 (2778) ALU VSC PLUS RM => VSC ,S ON TRUE, POP
 536: 8E60 6804 000C 0004
 (2779) * ZERO OUT THE FACC
 (2780) *
 (2781) DFIX4 ALU CON 0 => FLTH
 537: 823C 4A04 0000 0000
 (2782) ALU CON 0 => FLTL
 538: 823C 5A04 0000 0000
 (2783) ALU CON 0 => RB , GO TO DFIX4-1
 539: 823C 2B04 0004 0536
 (2784) *
 (2785) *
 (2786) * NORMALIZE SUBROUTINE. THIS DOUBLE PRECISION NORMALIZE
 (2787) * ROUTINE OPERATES EXACTLY AS THE SINGLE PRECISION ROUTINE
 (2788) * DOES. IF THE C8IT IS SET COMMING INTO THE ROUTINE, THE
 (2789) * VALUE IS TAKEN TO BE OVERSHIFTED, AND THE NUMBER IS
 (2790) * RIGHT SHIFTED ONE PLACE. THE SIGN BIT IS RECONSTRUCTED
 (2791) * FROM THE CONDITION CODE AT ENTRY. THE CODE IS ASSUMED
 (2792) * TO BE THE OPPOSITE SIGN OF THE PROPER NUMBER.
 (2793) *
 (2794) * IF THE NUMBER IS ALREADY NORMALIZED, A RETURN TO FETCH IS
 (2795) * DONE. OTHERWISE, THE FACC IS SHIFTED LEFT UNTIL
 (2796) * THE NUMBER IS NORMALIZED, THE EXPONENT IS REDUCED
 (2797) * APPROPRIATELY, AND A RETURN TO FETCH IS DONE.

(2798) *
 (2799) *
 (2800) DNRML RR RCM = -48 => NULL LOADRSC
 53A: F200 000E 0003 FED0
 (2801) CPU RFLS 3 ALL 7 0 M FLTH ;
 (2802) RY240 SOVFL , JUMP ON FCBIT TO DNRM1
 53B: 2F70 4364 0004 F540
 (2803) CPU RFLS 7 NX 7 0 M RB ;
 (2804) RF240 LINK , JUMP ON FCBIT TO DNRM2
 53C: 3E70 2B44 0004 F545
 (2805) CPU RFLS 3 ALL 7 0 M FLTL ;
 (2806) RF200 LINK
 53D: 2F70 5A44 0000 0000
 (2807) CPU RFLS 3 NX 3 0 M FLTH ;
 (2808) RF240 NOP INCRSC ;
 (2809) JUMP ON RSCNEM1 TO *+3
 53E: 2E30 4B05 0004 953B
 (2810) ALU LCN 0 => VSC C= B001 , GO TO F1
 53F: 823C 6B34 0004 0000
 (2811) DNRM1 ALU VSC PLUS RCM = 1 => VSC C= AOVFL
 540: 9260 6A74 0002 0001
 (2812) CPU RFRS 5 ALL 6 0 M FLTH ;
 (2813) RF240 LINK NOP ;
 (2814) JUMP ON LT TO *+2
 541: 5760 4B44 0006 6543
 (2815) ALU FLTH OR RCM = \$8000 => FLTH
 542: 924C 4A04 0001 0100
 (2816) CPU RFRS 1 ALL 6 0 M FLTL ;
 (2817) RF200 LINK
 543: 4760 5A44 0000 0000
 (2818) CPU RFRS 1 NX 6 0 M RB ;
 (2819) RF240 NOP JAMF ;
 (2820) JUMP ON FCBIT TO DFLEX
 544: 4660 2B00 0004 F5C8
 (2821) DNRM2 RR RCM = \$FFC0 => 11
 545: F200 9A04 0003 FFC0
 (2822) CPU RFRS 1 ALL 6 0 M RB ;
 (2823) RF200 NOP NOP
 546: 4760 2A04 0000 0000
 (2824) ALU 11 OR RSC => 11
 547: 864C 9A04 0000 0000
 (2825) ALU 11 PLUS RCM = 48 => RY
 548: 9260 9304 0002 0150
 (2826) ALU VSC MINUS RY => VSC C= AOVFL
 549: 8A94 6A74 0000 0000
 (2827) RR ,,JAMF JUMP ON FCBIT TO DFLEX
 54A: 0200 0600 0004 F5C8
 (2828) *
 (2829) *
 (2830) * DOUBLE PRECISION FLOATING POINT MULTIPLY. TECHNIQUE USED IS
 (2831) * A SIMPLE EXTENSION OF THE SINGLE PRECISION MULTIPLY.
 (2832) * THE EXPONENT IS UPDATED FIRST, THEN 16 BITS OF SINGLE
 (2833) * PRECISION MULTIPLY, THEN 16 BITS OF DOUBLE PRECISION,
 (2834) * AND FINALLY 15 BITS OF TRIPLE PRECISION SHIFT AND/OR
 (2835) * MULTIPLY. FINALLY, A TRIPLE PRECISION SUBTRACT
 (2836) * IS DONE, IF NECESSARY, FOLLOWED BY NORMALIZE AS NEEDED
 (2837) *
 (2838) *
 (2839) DFMP1 CPU BH RCM NONE 0 0 0 0 ;
 (2840) 280 NOP PUSHBD DATA DFMP4
 54B: F000 060C 0002 0540
 (2841) ALU INC RY => RY , GO TO DGET
 54C: 8A65 1304 0004 051F
 (2842) *
 (2843) * FIRST, FIX THE EXPONENT
 (2844) *
 (2845) DFMP4 ALU VSC MINUS RCM = 128 => VSC C= AOVFL
 54D: 9294 6A74 0002 0080
 (2846) ALU VSC PLUS RM => VSC C= AOVFL , ;
 (2847) JUMP ON FCBIT TO DFMP1
 54E: 8E60 6B74 0004 F55C
 (2848) DFMP2 RR FLTL => RY , JUMP ON FCBIT TO DFLEX
 54F: 0200 5304 0004 F5C8
 (2849) RR FLTH => RM
 550: 0200 4204 0000 0000
 (2850) CPU AL RCM ALL ZERO L M FLTH ;
 (2851) RF200 ,LOADRSC DATA -16
 551: 933C 4A0E 0003 FFF0
 (2852) CPU RFRS 5 NX 6 0 M 11 ;
 (2853)
 552: 5660 9A44 0000 0000
 (2854) CPU ALRS RM NX ADD 0 M FLTH ;
 (2855) RF240 NOP , EAC MPYLOGIC
 553: CE60 4B04 0008 C000
 (2856) CPU RFRS 5 ALL 6 0 M 11 ;
 (2857) RF240 LINKS INCRSC ;
 (2858) JUMP ON RSCNEM1 TO *-1
 554: 5760 9B15 0004 9553
 (2859) *
 (2860) * SINGLE PRECISION PART DONE, DO DOUBLE PRECISION.
 (2861) *
 (2862) CPU AL RCM ALL ZERO L M FLTL ;
 (2863) RF200 NOP LOADRSC DATA -16
 555: 933C 5A0E 0003 FFF0
 (2864) CPU RFRS 5 NX 6 0 M 12 ;
 (2865)
 (2866) JUMP ON NOTRF16 TO DFMP3
 556: 5660 AC14 0007 155B
 (2867) ALU FLTL PLUS RY => FLTL C= COUT
 557: 8A60 5A24 0000 0000

(2868) CPU ALRS RM ALL ADD C M FLTH ;
 (2869) RF240 LINK
 558: CF68 4B44 0000 0000
 (2870) DFMS CPU RFRS 1 NX 6 0 M FLTL ;
 (2871) RF240 NOP INCRSC ;
 (2872) JUMP ON RSCNEM1 TO *-3
 559: 4660 5B05 0004 9556
 (2873) RR RY => 11 , GO TO DFM4
 55A: EA00 9B04 0004 055E
 (2874) *
 (2875) * SHIFT PORTION OF DOUBLE PRECISION PART
 (2876) *
 (2877) DFM3 CPU RFRS 3 ALL 6 0 M FLTH ;
 (2878) RF240 LINK NOP GO TO DFMS
 55B: 4F60 4B44 0004 0559
 (2879) *
 (2880) * EXPONENT OVERFLOW TESTS
 (2881) *
 (2882) DFM1 ALU CUN 0 => NULL C= BD01 , JUMP ON FCBIT TU DFM2
 55C: 823C 0634 0004 F54F
 (2883) RR ,,,GO TU DFLEX
 55D: 0200 0604 0004 05CA
 (2884) *
 (2885) * FINALLY DO TRIPLE PRECISION MULTIPLY
 (2886) *
 (2887) DFM4 RR RCM = -15 => NULL LOADRSC
 55E: F200 000E 0003 FEF1
 (2888) DFM7 CPU RFRS 5 NX 6 0 M 13 ;
 (2889) RF280 LINKS NOP ;
 (2890) JUMP ON NOTRF16 TO DFM8
 55F: 5660 BC14 0007 756F
 (2891) RR RB => RY
 560: 0200 2B04 0000 0000
 (2892) ALU 12 PLUS RY => 12 C= COUT
 561: 8A60 AA24 0000 0000
 (2893) RR 11 => RY
 562: 0200 9B04 0000 0000
 (2894) ALU FLTL PLUS RY + C => FLTL C= COUT
 563: 8A68 5A24 0000 0000
 (2895) CPU ALRS RM ALL ADD C M FLTH ;
 (2896) RF240 LINK
 564: CF68 4B44 0000 0000
 (2897) DFM6 CPU RFRS 1 ALL 6 0 M FLTL ;
 (2898) RF200 LINK
 565: 4760 5A44 0000 0000
 (2899) CPU RFRS 1 NX 6 0 M 12 ;
 (2900) RF240 NOP INCRSC ;
 (2901) JUMP ON RSCNEM1 TO DFM7
 566: 4660 AB05 0004 955F
 (2903) * NOW DO FINAL SUBTRACT
 (2904) *
 (2905) CPU RF 0 ALL 0 0 M 13 ;
 (2906) RF280 BD01 NOP ;
 (2907) JUMP ON NOTRF16 TO DFM9
 567: 0300 BC34 0007 7560
 (2908) RR RB => RY
 568: 0200 2B04 0000 0000
 (2909) ALU 12 MINUS RY => 12 C= COUT
 569: 8A94 AA24 0000 0000
 (2910) RR 11 => RY
 56A: 0200 9B04 0000 0000
 (2911) ALU FLTL MINUS RY + C => FLTL C= COUT
 56B: 8A98 5A24 0000 0000
 (2912) ALU FLTH MINUS RM + C => FLTH C= AOVFL SETCC
 56C: 8E98 4A77 0000 0000
 (2913) DFM9 RR 12 => RM
 56D: 0200 A204 0000 0000
 (2914) RR RM => RB , GO TO DNRM1
 56E: EE00 2B04 0004 053A
 (2915) *
 (2916) * SHIFT PART OF TRIPLE PRECISION MPY LOOP.
 (2917) *
 (2918) DFM8 CPU RFRS 3 ALL 6 0 M FLTH ;
 (2919) RF240 LINK NOP GO TO DFM6
 56F: 4F60 4B44 0004 0565
 (2920) *
 (2921) *
 (2922) * DIVIOF -- DOUBLE PRECISION FLOATING POINT
 (2923) *
 (2924) DFDV1 CPU BB RCM 0 0 0 0 0 0 ;
 (2925) 280 NUP PUSHBD DATA DDV4
 570: F000 060C 0002 0AC7
 (2926) ALU INC RY => RY ,GO TO DGET
 571: 8A65 1304 0004 051F
 (2927) * DIVIDE BY ZERO TEST
 (2928) DDV30 ALU FLTH XOR RY => NULL SETCC ;
 (2929) JUMP ON EQ TO DFLEX1
 572: 8A6C 4607 0006 45CA
 (2930) ALU VSC PLUS RCM = 129 => VSC C= AOVFL ;
 (2931) CLEARFUII
 573: 9260 6A7F 0002 0181
 (2932) RR RX => RX NUP JUMP ON GE TO *+2
 574: 0200 0B04 0004 B576
 (2933) * SET FUII FOR NEGATIVE RESULTS
 (2934) RR ,,,EAC SETFUII
 575: 0200 0004 000A 8000
 (2935) * EXPONENT CALCULATION
 (2936) ALU VSC MINUS RM => VSC C= AOVFL TR= ALL ;
 (2937) JUMP ON FCBIT TO DDVS

576: 8F94 6B74 0004 F5A5
 (2938) * EXPONENTS DONE EXCEPT FOR OVERFLOW
 (2939) * TEST NOW TO SEE IF EITHER OF THE TWO ARGUMENTS
 (2940) * IS NEGATIVE. IF IT IS, THEN COMPLEMENT IT
 (2941) *
 (2942) DDV6 ALU INC 13 + 0 => RM SETCC ;
 (2943) JUMP ON FCBIT TO DFLEX
 577: 8200 B407 0004 F5C8
 (2944) ALU INC FLTH + 0 => NULL SETCC ;
 (2945) JUMP ON GE TO DDV7
 578: 8200 4607 0004 6570
 (2946) * COMPLEMENT NEW ARGUMENT
 (2947) *
 (2948) ALU NOT 11 => 11
 579: 82FC 9A04 0000 0000
 (2949) ALU NOT 13 => RM
 57A: 82FC B204 0000 0000
 (2950) ALU INC 11 => 11 C= COUT
 57B: 8204 9A24 0000 0000
 (2951) ALU NOT 12 => 12 , TR= ALL ;
 (2952) JUMP ON FCBIT TO DDV8
 57C: 83FC A804 0004 F5A7
 (2953) * NOW TEST NEW ARGUMENT
 (2954) *
 (2955) DDV7 RR 12 => RY ,JUMP ON GE TO DDV11 TR= ALL
 57D: 0300 A304 0004 6582
 (2956) * COMPLEMENT ACCUMULATOR
 (2957) *
 (2958) ALU NOT RB => RB
 57E: 82FC 2A04 0000 0000
 (2959) ALU NOT FLTL => FLTL
 57F: 82FC 5A04 0000 0000
 (2960) ALU INC RB => RB C= COUT TR= ALL
 580: 8304 2A24 0000 0000
 (2961) ALU NOT FLTH => FLTH , JUMP ON FCBIT TO DDV10
 581: 82FC 4804 0004 F5A8
 (2962) * NOW SET UP AND EXECUTE 16 ITTERATIONS OF
 (2963) * THE TRIPPLE PRECISION DIVIDE LOOP.
 (2964) *
 (2965) DDV11 ALU FLTH MINUS RM => NULL SETCC TR= ALL
 582: 8F94 4007 0000 0000
 (2966) RR RCM = -17 => NULL LOADRSC
 583: F200 000E 0003 FEEF
 (2967) * RM=NH/RY,12=NM/11=NL/13=POSITIVE
 (2968) *
 (2969) *
 (2970) * COMPARE PART OF NON-PERFORMING DIVIDE
 (2971) *
 (2972) DDV15 CPU RFLS 3 ALL 3 0 M 13 ;
 (2973) RF240 NOP INCRSC ;
 (2974) JUMP ON LT TO DDV13
 584: 2F30 BB05 0006 5581
 (2975) ALU FLTL MINUS RY => NULL SETCC ;
 (2976) C= COUT JUMP ON GT TO DDV14
 585: 8A94 5627 0006 75C6
 (2977) RR 11 => RY , JUMP ON FCBIT TO **2
 586: 0200 9304 0004 FS88
 (2978) RR 12 => RY , GO TO DDV13
 587: 0200 A304 0004 05A1
 (2979) ALU RB MINUS RY => NULL C= COUT , ;
 (2980) JUMP ON NE TO DDV12
 588: 8A94 2624 0004 45A5
 (2981) RR RX => RX , JUMP ON FCBIT TO DDV12
 589: 0200 0804 0004 F588
 (2982) RR 12 => RY , GO TO DDV13
 590: 0200 A304 0004 05A1
 (2983) *END OF DIVIDE TEST.
 (2984) *
 (2985) * SUBTR ACT -- SHIFT
 (2986) *
 (2987) DDV12 ALU RB MINUS RY => RB C= COUT
 588: 8A94 2A24 0000 0000
 (2988) CPU RF 0 ALL ZERO L M 12 ;
 (2989) RY200 NOP SETCC
 58C: 033C A807 0000 0000
 (2990) ALU FLTL MINUS RY + C => FLTL C= COUT
 58D: 8A94 5A24 0000 0000
 (2991) CPU RFLS 7 ALL 7 0 M RB ;
 (2992) RF200 LINK
 58E: 3F70 2A44 0000 0000
 (2993) CPU RFLS 3 NX 7 0 M FLTL ;
 (2994) RF200 LINK
 58F: 2E70 5A44 0000 0000
 (2995) CPU ALLS RM ALL SUB C M FLTH ;
 (2996) RF240 LINK
 590: AF98 4844 0000 0000
 (2997) *
 (2998) * START OF NEXT ITTERATION
 (2999) *
 (3000) DDV9 ALU FLTH MINUS RM => NULL SETCC ;
 (3001) JUMP ON RSCNEM1 TO DDV15
 591: 8E94 4507 0004 45A4
 (3002) * DOUBLE PERECISION DIVIDE. SIMILAR TO THAT IN FDV.
 (3003) *
 (3004) * ON ENTRY: RM=NH,RY=NM,13=HIGH ANSWER,LINK=16TH QUOTIENT BIT.
 (3005) *
 (3006) RR RCM = -17 => NULL LOADRSC
 592: F200 000E 0003 FEEF
 (3007) *
 (3008) * HIGH ORDER CONDITION CODE ALREADY TESTED UPON ENTRY

(3009) *
 (3010) DDV23 CPU PFLS 3 NX 7 0 M 12 ;
 (3011) RF240 NOP INCRSC ;
 (3012) JUMP UN LT TO DDV21
S45: 2E70 A005 0000 6596
 (3013) ALU FLTL MINUS RY => NULL C= COUT , ;
 (3014) JUMP ON GT TO DDV24
S46: 8A94 5624 0000 7598
 (3015) RR RX => RX , JUMP ON FCBIT TO DDV24
S47: 0200 0804 0004 F595
 (3016) * DOUBLE WORD SHIFT
 (3017) DDV21 CPU RFLS 7 NX 7 0 M FLTL ;
 (3018) RF200 LINK
S48: 3E70 5A44 0000 0000
 (3019) CPU RFLS 3 ALL 7 0 M FLTH ;
 (3020) RF240 LINK NOP ;
 (3021) GO TO DDV20
S49: 2F70 4B44 0004 0596
 (3022) DDV24 ALU FLTL MINUS RY => FLTL C= COUT
S50: 8A94 5A24 0000 0000
 (3023) CPU RFLS 7 ALL 7 0 M FLTL ;
 (3024) RF200 LINK
S51: 3F70 5A44 0000 0000
 (3025) CPU ALLS RM ALL SUB C M FLTH ;
 (3026) RF240 LINK
S52: AF94 4B44 0000 0000
 (3027) DDV20 ALU FLTH MINUS RM => NULL SETCC ;
 (3028) JUMP ON RSCNEM1 TO DDV23
S53: 8E94 4607 0004 9593
 (3029) *
 (3030) * FINISHED DOUBLE PART. NOW DO SINGLE PART.
 (3031) *
 (3032) *
 (3033) * LINK CONTAINS 32ND QUOTIENT BIT. RM=NH,13=Q1,12=Q2
 (3034) * BUILD Q3 IN RB. PUT 13 IN RY, INITIALIZE AND DIVIDE FLTH/RM
 (3035) *
 (3036) CPU RF RCM ALL ZERO L M RB ;
 (3037) RF200 NOP LOADRSC ;
 (3038) DATA -15
S54: 133C 2A0E 0003 FFFF
 (3039) CPU RFLS 3 NX 7 0 M RB ;
 (3040) RF200 LINK
S55: 2E70 2A44 0000 0000
 (3041) CPU AL RCM ALL AND L M 13 ;
 (3042) RF240 NOP SETCC DATA \$7FFF
S56: 931C B307 0000 FFFF
 (3043) * SINGLE PRECISION DIVIDE LOOP
 (3044) *
 (3045) CPU ALLS RM ALL SUB 1 M FLTH ;
 (3046) RF240 LINK ,EAC DIVLOGIC
S57: AF94 4C44 0004 0000
 (3047) CPU RFLS 3 NX 7 0 M RB ;
 (3048) RF240 LINK INCRSC ;
 (3049) JUMP ON RSCNEM1 TO --1
S58: 2E70 2B45 0004 959F
 (3050) * DONE WITH DIVIDE
 (3051) *
 (3052) * RESULTS IN RY,12,RB
 (3053) *
 (3054) RR RY => FLTH C= B001
S59: EA00 4A34 0000 0000
 (3055) RR 12 => RM TR= ALL ,JUMP ON FUII TO --2
S60: 0300 4404 0005 5A44
 (3056) RR RM => FLTL ,GU TO DNRML
S61: EE00 5B04 0004 053A
 (3057) ALU NOT RM => FLTL ,GO TO DFCLM+1
S62: BEAC 5B04 0004 0435
 (3058) *
 (3059) * ASSURED DIVIDE NON-STRAIGHT LINE CODE
 (3060) *
 (3061) DDVS ALU CON 0 => NULL C= B001 , ;
 (3062) JUMP UN FCBIT TO DDV6
S63: 823C 0634 0004 F577
 (3063) RR ,,,GO TO DFLEX
S64: 0200 0604 0004 053A
 (3064) DDVB ALU INC 12 + C => 12 C= COUT
S65: 8208 AA24 0000 0000
 (3065) ALU INC RM + C => RM SETCC
S66: BE69 1207 0000 0000
 (3066) ALU INC FLTH + 0 => NULL SETCC ;
 (3067) JUMP ON GE TO DDV7
S67: 8200 4607 0004 6570
 (3068) CPU AL RCM NX DEC 0 M VSC ;
 (3069) PF240 AOVFL , GU TO DFCLM
S68: 92F0 5B74 0004 0434
 (3070) *
 (3071) * FINISH COMPLEMENT
 (3072) *
 (3073) DDV10 ALU INC FLTL + C => FLTL C= COUT
S69: 8208 5A24 0000 0000
 (3074) ALU INC FLTH + C => FLTH SETCC
S70: 8208 4A07 0000 0000
 (3075) ALU FLTH MINUS RM => NULL SETCC TR= ALL ;
 (3076) JUMP ON GE DDV11+1
S71: 8F94 4607 0004 5505
 (3077) ALU VSC PLUS RCM = 1 => VSC C= AOVFL
S72: 9260 5A74 0002 0001
 (3078) CPU RFRS 5 ALL 6 0 M FLTH ;
 (3079) RF240 NOP NOP ;
 (3080) JUMP UN FCBIT TO DFLEX

SAE: 5760 4804 0004 F5C8
 (3081) ALU FLTH MINUS RM => NULL SETCC GO TO DDV11+1
 SBU: 8E94 4607 0004 0583
 (3082) *
 (3083) * SHIFT STEP -- TRIPPLE SUBTRACT
 (3084) *
 (3085) DDV13 CPU RFLS 7 ALL 7 0 M RB ;
 (3086) RF200 LINK
 SB1: 5F70 2A44 0000 0000
 (3087) CPU RFLS 3 NX 7 0 M FLTL ;
 (3088) RF200 LINK
 SB2: 2E70 5A44 0000 0000
 (3089) CPU RFLS 3 ALL 7 0 M FLTH ;
 (3090) RF240 LINK NOP ;
 (3091) GO TO DDV9
 SB3: 2F70 4B44 0004 0591
 (3092) *
 (3093) * DOUBLE PRECISION COMPARE
 (3094) *
 (3095) ORG \$5B4
 (3096) DFC81 CPU BB RM NX XOR L M FLTH ;
 (3097) 200 BD01 SETCC
 SB4: EE6C 4037 0000 0000
 (3098) ALU INC RY => RY , JUMP ON LT TO FCS2
 SB5: 8A65 1304 0006 6477
 (3099) CPU BB RM ALL BB L M 13 ;
 (3100) RMRFRMDY MREAD SETCC
 SB6: EF5C B587 0000 0000
 (3101) RR RY => 12
 SB7: EA00 AA04 0000 0000
 (3102) ALU 12 PLUS RCM = 2 => RY
 SB8: 9260 A304 0002 0002
 (3103) * FOR NEG REVERSE EXPONENT TEST
 (3104) CPU BB RM ALL 0 0 M 11 ;
 (3105) RMRFRMDY MREAD NOP ;
 (3106) JUMP ON LT TO CS1
 SB9: EF00 9584 0006 65C5
 (3107) *
 (3108) * EXPONENT TEST
 (3109) *
 (3110) ALU INC FLTH + 0 => NULL SETCC JUMP ON EQ TO FCS7
 S8A: 8200 4607 0006 4479
 (3111) ALU VSC MINUS RM => RM SETCC ;
 (3112) C= ADVFL JUMP ON EQ TO FCS2+1
 SB8: 8E94 6477 0006 4478
 (3113) * IF OVERFLOW - REVERSE TEST
 (3114) RR 13 => RM , JUMP ON FCBIT TO CS3
 S8C: 0200 9404 0004 F5C5
 (3115) *
 (3116) ALU INC 12 => RY , JUMP ON GT TO F1
 S8D: 8204 A304 0006 7000
 (3117) *
 (3118) * EXPONENTS EQUAL
 (3119) *
 (3120) CS4 ALU FLTH MINUS RM => NULL SETCC ;
 (3121) JUMP ON NE TO FCS2+1
 S8E: 8E94 4607 0004 4476
 (3122) RR 11 => RM , JUMP ON GT TO F1
 S8F: 0200 9404 0006 7000
 (3123) ALU FLTL MINUS RM => NULL SETCC TR= ALL C= COUT ;
 (3124) JUMP ON LT TO FCS2+1
 SC0: 8F94 5627 0006 6478
 (3125) *
 (3126) * HIGH ORDER PART EQUAL -- TEST MIDDLE
 (3127) *
 (3128) CPU ,,,ALL,,,RMMRDY MREAD NOP JUMP ON NE TO FCS2
 SC1: 0300 0784 0004 4477
 (3129) ALU RR MINUS RM => NULL C= COUT SETCC GO TO FCS2-1
 SC2: 8E94 2627 0004 0476
 (3130) * NEGATIVE EXPONENTS, REVERSE TEST
 (3131) CS1 ALU VSC MINUS RM => NULL SETCC C= ADVFL
 SC3: 8E94 6077 0000 0000
 (3132) * IF OVERFLOW, DO NOT REVERSE TEST.
 (3133) RR 13 => RM , JUMP ON FCBIT TO CAS4-1
 SC4: 0200 9404 0004 F1E3
 (3134) * REVERSE TEST
 (3135) CS3 ALU INC 12 => RY JAMP JUMP ON GE TO CS4
 SC5: 8204 A300 0004 059E
 (3136) * PATCH SPACE
 (3137) DDV14 RR 11 => RY , GO TO DDV12
 SC6: 0200 9304 0004 05MB
 (3138) DDV4 ALU INC 13 + 0 => RY SETCC GO TO DDV30
 SC7: 8200 5307 0004 0572
 (3139) *
 (3140) * DOUBLE PRECISION FLOATING EXCEPTION
 (3141) *
 (3142) DFLEX RR RCM = \$200 => 11
 SCA: F200 9A04 0000 0500
 (3143) ALU CON -1 => NULL C= BD01 , GO TO FLEX5
 SC9: 8200 0634 0004 0403
 (3144) DFLEX1 RR RCM = \$201 => 11
 SCA: F200 9A04 0000 0401
 (3145) ALU CON -1 => NULL C= BD01 , GO TO FLEX5
 SC8: 8200 0634 0004 0403
 002714 (3146) END

A2A	01AD	A	2017									
ACA	01B8	A	2030									
ADD	01EF	A	2151									
ADD3	00B9	A	1510	2151								
ADJM	0444	A	2299	2323								
ADJ9	0443	A	2294	2322								
ADJUST	043A	A	2294	2384	2391							
ALL	01D9	A	2101									
ALR	01D9	A	2108									
ALS	01D7	A	2102									
ANA	01EY	A	2143									
AOA	0133	A	1798	2021								
ARL	01C2	A	2056									
ARR	01C4	A	2042									
ARS	01C3	A	2059									
AVECT	0077	A	0965	1563	1385	1417	1993					
AVECT1	0077	A	1520	1346	1365	1394	1507					
BOOT	0091	A	1015	1436								
BOOT1	0094	A	1440	1452								
CAI	01FD	A	2156									
CAL	01B4	A	2025									
CAR	01B3	A	2024									
CAS	01EV	A	2132									
CAS4	01E4	A	2136	2138	2153	3133						
CASS	01E5	A	1370	1711	1853	1878	1968	2007	2014	2127	2138	2451
			2139	2142	2187	2188	2189	2190	2191	2192	2428	
CAS6	01F1	A	2135	2153								
CAZ	01AB	A	2014									
CEA	01BB	A	1970									
CEAS	0128	A	1745	1970								
CMS	01A0	A	2000									
CMA	01AF	A	2020									
CP1	0035	A	1009	1046	1115	1369	1846					
CP10	0022	A	1011									
CP11	0023	A	1012									
CP12	0024	A	1013									
CP13	0025	A	1019									
CP14	0026	A	1026									
CP15	0027	A	1019	1031								
CP16	0028	A	1033									
CP17	002A	A	1057									
CP18	002B	A	1039									
CP19	002C	A	1012	1041								
CP2	0036	A	1116									
CP3	0037	A	1037	1039	1041	1117						
CP4	0038	A	1120									
CP5	0039	A	1122									
CP6	003A	A	1124									
CP7	003B	A	1127									
CP8	0020	A	0996	0998	1007	1127						
CP9	0021	A	1009	1011								
CPPAR	006A	A	1324									
CPPARS	007E	A	1384	1712								
CRA	01CE	A	2004	2085	2588							
CRH	019F	A	1999	2010								
CREP	013C	A	1809									
CRL	019E	A	1995	2250	2253	2269	2574					
CS1	05C3	A	3106	3131								
CS3	05C5	A	3114	3135								
CS4	05BE	A	3121	3135								
CSA	01AC	A	2015									
D8L	0188	A	1960									
DDV10	05AB	A	2901	3073								
DDV11	05B2	A	2955	2955	3076	3081						
DDV12	05B8	A	2980	2981	2987	3137						
DDV13	05B1	A	2974	2978	2982	3086						
DDV14	05C6	A	2976	3137								
DDV15	05B4	A	2974	3001								
DDV20	059B	A	3021	3028								
DDV21	0596	A	3012	3018								
DDV23	0593	A	3012	3028								
DDV24	0598	A	3014	3015	3022							
DDV30	0572	A	2929	3138								
DDV4	05C7	A	2925	3138								
DDV5	05A5	A	2937	3062								
DDV6	0577	A	2943	3062								
DDV7	0570	A	2945	2955	3067							
DDV8	05A7	A	2952	3064								
DDV9	0591	A	3001	3091								
DFAD	01F8	A	2161									
DFAU1	050D	A	2161	2668								
DFAU4	050F	A	2665	2671								
DFAD6	0511	A	2671	2674								
DFCM	0434	A	2277	3057	3069							
DFCS	01FC	A	2165									
DFCS1	05B4	A	2165	3097								
DFDU	01FB	A	2154									
DFDU1	0570	A	2154	2925								
DFIX	0524	A	2673	2686	2726							
DFIX1	052F	A	2726	2757								
DFIX2	0532	A	2730	2759								
DFIX3	0527	A	2730	2759								
DFIX4	0537	A	2735	2772	2781	2783						
DFLU	01F6	A	2159									
DFLU1	0500	A	2159	2651								
DFLEX	05C8	A	2277	2820	2827	2848	2883	2943	3063	3080	3142	
DFLEX1	05CA	A	2929	3144								
DFM1	055C	A	2847	2882								
DFM2	054F	A	2845	2882								

DFM3	0558	A	2866	2878
DFM4	055E	A	2873	2887
DFMS	0559	A	2872	2878
DFM6	0565	A	2898	2919
DFM7	055F	A	2890	2901
DFM8	056F	A	2890	2919
DFM9	0560	A	2907	2913
DFMP	01FA	A	2163	
DFMP1	0545	A	2163	2840
DFMP4	0540	A	2840	2845
DFSB	01F9	A	2162	
DFSB1	0516	A	2162	2681
DFSB4	0518	A	2681	2684
DFSH6	051A	A	2684	2687
DFST	01F7	A	2100	
DFST1	0507	A	2160	2661
DGET	051F	A	2669	2682 2703 2841 2926
DIN	004F	A	1210	1221 1231
DIN1	0053	A	1231	1244 1405
DIV	0144	A	1826	
DIV17	009E	A	1458	1479
DIV27	009C	A	1454	1477
DIV4	00A8	A	1479	1828
DIVER	0146	A	1461	1483 1830
DMA	004B	A	1153	1207
DMA1	0047	A	1184	1222 1238
DMC	004B	A	1190	1207
DMC1	005C	A	1190	1268
DMC2	0069	A	1401	1405
DMC3	0086	A	1275	1399
DMT	003E	A	1148	1191
DMX1	0070	A	1340	
DMX2	003C	A	1131	1341
DNRM1	0540	A	2802	2811
DNRM2	0545	A	2804	2821
DNRML	053A	A	2280	2283 2679 2692 2737 2800 2914 3056
DOU1	0054	A	1235	1247
DOU11	0058	A	1213	1228 1247 1403
DRX	01AA	A	2012	
E16S	0189	A	1962	
E32R	0189	A	1964	
E32S	0189	A	1903	
E64R	0189	A	1905	
EAA	0128	A	1786	
EMCM	018D	A	1972	
ENB	0190	A	1976	
ENTR	0100	A	1722	
EPMJ	0120	A	1775	
EPMJ0	0116	A	1756	
EPMX	0120	A	1772	
ERA	01E0	A	2149	
ERM	0117	A	1757	
ERMJ	0110	A	1746	1777
ERMX	0110	A	1744	
ESIM	0196	A	1989	
EVIM	0196	A	1990	
EVMJ	0110	A	1745	
EVMX	0110	A	1743	
EVMX1	01F2	A	1753	2154
F1	0000	A	0663	1570 1718 1891 1896 1958 2139 2258 2353
			2420	2424 2429 2587 2610 2660 2810 3116 3122
F10	0005	A	0892	
F11	0006	A	0898	
F12	0007	A	0404	
F13	0008	A	0892	0907
F14	0009	A	0913	
F16	000A	A	0919	
F16A	000B	A	0925	
F16d	000C	A	0931	
F17	000D	A	0907	0936
F18	000E	A	0942	
F18A	000F	A	0943	
F19	0014	A	0935	0964
F20	0015	A	0970	
F3	0001	A	0869	1007
F4	0002	A	0875	
F5	0003	A	0881	
F6	0010	A	0881	0904 0931 0948 0970 1971
F6A	0011	A	0951	0957 0958
F7	0012	A	0957	
F7A	0013	A	0958	
F9	0004	A	0869	0887 1780
FAU	0165	A	1908	
FAU1	0406	A	1908	2202
FAU4	045A	A	2202	2383
FAU6	045C	A	2353	2385
FCM	0410	A	2211	2404 2570
FCS	015A	A	1918	
FCS1	046B	A	1920	2409
FCS2	0477	A	2409	2418 2419 2421 2426 2429 3098 3112 3121
			3124	3128 3129
FCS5	04C8	A	2415	2609
FCS4	0470	A	2419	
FCS5	0472	A	2421	2611
FCS7	0479	A	2416	2431 3110
FDv	0164	A	1914	
FDv1	0428	A	1914	2200
FDv10	0442	A	2537	2557
FDv11	0440	A	2501	
FDv15	045A	A	2404	2514

LLL	01D1	A	2089
LLR	01C5	A	2064
LLS	01D3	A	2093
LLT	01C8	A	2073
LMCM	01B0	A	1973
LNE	01CA	A	2077
LOAD	0419	A	2203
LOGIC	01E4	A	2036
LPMJ	0120	A	1774
LPMX	0120	A	1713
LRL	01B8	A	2038
LRR	01BF	A	2048
LRS	01B0	A	2043
LT	01CF	A	2073
MC1	0031	A	1077
MC2	0052	A	1080
MC3	0033	A	1083
MC4	0034	A	1086
MEMP3	008C	A	1331
MEMPAR	006C	A	1330
M11	00BF	A	0976
M12	001C	A	0993
MMOD	006E	A	1335
MOVE	0449	A	2322
MPY	017C	A	1942
NRM	0118	A	1758
NRM10	0452	A	2352
NRM17	0451	A	2359
NRM18	044E	A	2356
NRM7	0420	A	2263
NRML	044B	A	2214
			2216
			2219
			2220
			2313
			2352
			2388
			2395
			2480
NVECT	001A	A	0979
OSI	019C	A	1996
OTA	0159	A	1684
OTA1	015F	A	1892
OTK	0192	A	1771
PAGE	007C	A	1293
PAGE3	0063	A	1301
PAGE4	0080	A	1301
PAGE7	0083	A	1387
PFL	0075	A	1351
PID	0174	A	1930
PIM	0172	A	1928
PIU	0159	A	1883
RCB	01A7	A	2008
READ	0064	A	1306
REST	0059	A	1184
RMC	0167	A	1844
RIN	0104	A	1727
RXM	0068	A	1319
S2A	01AE	A	2019
SCA	0145	A	1957
SCB	01B2	A	2023
SGL	01B8	A	1981
SKP	01DA	A	2111
SKS	0157	A	1869
SK81	01EC	A	1881
SDA	01A4	A	2005
SSM	01B1	A	2022
SSP	01A1	A	2001
SIA	01EB	A	2147
STAS	0087	A	1513
STX	01B7	A	2029
SUH	014C	A	1847
SUB3	016C	A	1647
SVC	0198	A	1992
ICA	01B0	A	2021
TEXIT	004A	A	1160
TIN	0040	A	1157
TINI	0042	A	1149
TOUT	0043	A	1168
TOUT1	0046	A	1148
UII	0140	A	1817
UIIS	0083	A	1504
VIRY	0126	A	1783
VIRY1	00C4	A	1083
VIRY12	00CF	A	1600
WRITE	0062	A	1298
WRITEP	0072	A	1345
XCA	01A2	A	1931
XCB	01A8	A	1476
XEC	0122	A	1776
IDNT [MACRO]			
CPU [MACRO]			
RR [MACRO]			
ALU [MACRO]			
FROS [MACRO]			
EMITS [MACRO]			
SETB [MACRO]			
GENS [MACRO]			
LSTIS [MACRO]			
CNTS [MACRO]			
RRSVS [MACRO]			
AVFS [MACRO]			
GPRS [MACRO]			
ORG [MACRO]			
SYMS [MACRO]			
SYMS1 [MACRO]			
CLSTS [MACRO]			

APPENDIX D
TRAPS - INTERRUPTS SUMMARY

Traps

There are 12 different μ -code traps that cause the μ -code to break normal sequence. They are:

1. 60 FPAGE Trap.

The CAM must be filled with the new page pointer if available. If not, generate a Page Fault interrupt identical to page trap except F01 and F02 are loaded.

2. 62 Write Address Trap.

Put RM into the appropriate RF instead of HSM.

3. 64 Read Address Trap.

Put RF into RM as appropriate instead of HSM to RM.

4. 66 Fetch Read Address Trap

Same as 3, but load R01 and F02 also.

5. 68 Restricted Execution Trap.

Generates RXM vector.

6. 6A CP Parity.

Machine Check generates the Machine Check Interrupt.

7. 6C Memory Parity.

Generates Memory Parity interrupt.

8. 6E Missing Memory Module.

Generates Missing Module interrupt.

9. 70 DMX.

Performs a DMX transfer without changing user execution flow.

10. 72 Page Write Violation.

Generates a Page Write Violation interrupt.

11. 7C Page Trap

Identical to 1 only F01 and F02 are not changed.

Interrupt Vector Summary

<u>Loc</u>	<u>Name</u>	<u>Deposited P Counter</u>	<u>Vector Type</u>	<u>Register 11</u>	<u>Register 12</u>
60	PFAIL	Next	Absolute ¹	(none)	(none)
62	Restrict Ex Violation	This	Absolute	(none)	(none)
63	Ext INT	Next	Absolute ¹	(none)	(none)
64	Page Fault	This	Absolute	(none)	effective addr
65	SVC	Next	Absolute	(none)	(none)
66	UII	This	Absolute	Next P	effective addr
67	Mem Parity	Next ²	Absolute	(none)	(none)
70	CPU Parity	Next ²	Absolute	(none)	(none)
71	Missing Mem Mod	Next ²	Absolute	(none)	(none)
72	ILL	This	Absolute	Next P	effective addr
73	Page Write	This	Absolute	(none)	effective addr
74	FLEX	Next	Absolute ³	Flag Reg ⁴	effective addr
75	PSU	This	Absolute	(none)	(none)

¹External interrupts are inhibited automatically.

²Next is true only if the error occurred during code execution.
DMA or DMC errors can abort an instruction in mid-execution.

³Identical to other vectors except that non-implementation
([74] = 0) causes the vector to not be executed and the
instruction sequence is continued with C Bit = 1.

⁴Flag Register:

Left byte:

Single precision Floating Point = 1
Double precision Floating Point = 2

Right byte:

Overflow/Underflow	= 0
Divide by Zero	= 1
Store exception	= 2
INT exception	= 3

APPENDIX E

INSTRUCTIONS FOR USE OF PROM, μ -CODE PROGRAM

1. This program will handle up to 512 μ -code words.
2. See comment at beginning of listing.
3. Legal responses to "MODULE" must be followed by a carriage return and are as follows:
 - a) Any legal CPU or XCS module. (1-1L, 1-2L, , 7-2U)
 - b) The letter "N" (next) may be used for sequential module selection except before the first module of a bank. (1-1L or 1-1U)
 - c) The letter "Q" (quit) returns user to operating system.
4. A legal response causes the system to "answer back" the legal module. At this time, the inputs to the PROM Writer are valid and PROM may be verified or programmed.

See enclosed example of a typical working session.

APPENDIX E (Cont)

THE FOLLOWING IS AN EXAMPLE OF A WORKING SESSION WHERE THE REQUIREMENTS ARE TO PROGRAM MODULES 1-1L THROUGH 3-1U AND MODULES 6-1U, 7-1U, AND 7-2U.

NOTE: THE SYSTEM PRINTS THE PROMPT 'MODULE = ' AND THE USER RESPONDS WITH THE MODULE NAME OR WITH 'N' TO SPECIFY THE NEXT MODULE NAME IN THE SEQUENCE.

```
MODULE = 1-1L
1-1L
MODULE = N
1-2L
MODULE = N
2-1L
MODULE = N
2-2L
MODULE = N
3-1L
MODULE = N
3-2L
MODULE = N
4-1L
MODULE = N
4-2L
MODULE = N
5-2L
MODULE = N
6-1L
MODULE = N
6-2L
MODULE = N
7-1L
MODULE = N
7-2L
MODULE = 1-1U
MODULE = N
```

APPENDIX E (Cont)

THE FOLLOWING IS AN EXAMPLE OF A WORKING SESSION WHERE THE

```
1-2U  
MODULE = N  
2-1 L  
MODULE = N  
2-2U  
MODULE = N  
3-1U  
MODULE = 5-1L      (SINCE 5-1L IS NOT A LEGAL MODULE THE RESPONSE IS NOT ACCEPTED  
MODULE = 6-1U  
6-1U  
MODULE = 7-1U  
7-1U  
MODULE = N  
7-2U  
MODULE = Q
```

(0001) * PROM, U-CODE, JMG-KRR, 11 JUNE 74
(0002) * PROGRAM OR VERIFY P-ROM FOR WCS OR CENTRAL PROCESSOR
(0003) * PRIME COMPUTERS INC., SRCXXXX. 000
(0004) * COPYRIGHT 1974, PRIME COMPUTERS INC., NATICK MASS
(0005) *
(0006) *
(0007) * THIS ROUTINE IS A DOS COMMAND TO PROGRAM OR VERIFY P-ROM.
(0008) *
(0009) * THE DOS COMMAND IS:
(0010) * PROM FILENAME
(0011) *
(0012) * FILENAME MUST BE A 'SAVE' FILE WITH A LOW OF '10000.
(0013) *
000221 (0014) ENT X COMMON FOR RDCOM
(0015) *
(0016) REL
(0017) *
010000 (0018) BUFF EQU '10000 BUFFER FOR CODE TO BE LOADED TO WCS
000024 (0019) DEV EQU '24 WCS DEVICE CODE
(0020) *
000006: (0021) BEGN ELM
(0022) *
000001: 10. 000000E (0023) CALL CMREAD GET FILE NAME
000002: 00. 010000A (0024) DAC BUFF
(0025) *
000003: 10. 000000E (0026) CALL SEARCH CLOSE UNIT 1
000004: 00. 000227 (0027) DAC =4
000005: 00. 000230 (0028) DAC =0
000006: 00. 000231 (0029) DAC =1
000007: 000000 (0030) OCT 0
(0031) *
000010: 10. 000000E (0032) CALL SEARCH OPEN UNIT 1 FOR READING
000011: 00. 000231 (0033) DAC =1
000012: 00. 010003A (0034) DAC BUFF+3
000013: 00. 000231 (0035) DAC =1
000014: 000000 (0036) OCT 0
(0037) *
000015: 10. 000000E (0038) CALL PRWFIL READ FILE INTO MEMORY

000016:	00. 000231	(0039)	DAC	=1	KEY TO READ
000017:	00. 000231	(0040)	DAC	=1	
000026:	00. 000232	(0041)	DAC	=BUFF	
000021:	00. 000233	(0042)	DAC	=2048	
000022:	00. 000234	(0043)	DAC	=9	STEP PAST SAVE VECTOR
000023:	00. 000235	(0044)	DAC	=ALT	MOST READS WILL BE SHORT
000024:	000000	(0045)	OCT	0	
		(0046) *			
000025:	10. 00000E	(0047)	ALT	CALL	SEARCH CLOSE UNIT 1
000026:	00. 000227	(0048)	DAC	=4	
000027:	00. 000230	(0049)	DAC	=0	
000030:	00. 000231	(0050)	DAC	=1	
000031:	000000	(0051)	OCT	0	
		(0052) *			
		(0053) *	DETERMINE NEXT MODULE TO BE LOADED INTO WCS		
		(0054) *			
000032:	000000	(0055)	NEXTMODULE	EQU *	CHOOSE A MODULE
		(0056) *			
000032:	10. 00000E	(0057)	CALL	TNOUA	ASK FOR MODULE
000033:	00. 000236	(0058)	DAC	=C'MODULE =	
000034:	00. 000234	(0059)	DAC	=9	
000035:	000000	(0060)	OCT	0	
		(0061) *			
000036:	10. 00000E	(0062)	CALL	RDCOM	GET RESPONSE
000037:	00. 000317	(0063)	DAC	CMBUFF	
		(0064) *			
000040:	02. 000317	(0065)	LDA	CMBUFF	VERIFY 1ST CHAR VALID
000041:	141050	(0066)	CAL		
000042:	11. 000243	(0067)	CAS	=R'Q'	QUIT, RETURN TO OPERATING SYSTEM
000043:	100000	(0068)	SKP		
000044:	01. 000125	(0069)	JMP	DONE	
000045:	11. 000244	(0070)	CAS	=R'N'	NEXT-USE NEXT SEQUENTIAL MODULE
000046:	100000	(0071)	SKP		
000047:	01. 000131	(0072)	JMP	NEXT	
000050:	11. 000245	(0073)	CAS	='260	MUST BE INTEGER 1-7
000051:	11. 000246	(0074)	CAS	='270	
000052:	01. 000032	(0075)	JMP	NEXTMODULE	NON VALID RESPONSE
000053:	01. 000032	(0076)	JMP	NEXTMODULE	

000054:	141340	(0077)	ICA		
000055:	140104	(0078)	XCA		SAVE THIS CHARACTER IN LEFT HALF OF B-REG
		(0079) *			
000056:	02. 000320	(0080)	LDA	CMBUFF+1	2ND CHAR MUST BE '-'
000057:	141050	(0081)	CAL		
000060:	05. 000247	(0082)	ERA	=R'-'	
000061:	100000	(0083)	SZE		
000062:	01. 000032	(0084)	JMP	NEXTMODULE	
		(0085) *			
000063:	02. 000321	(0086)	LDA	CMBUFF+2	3RD CHAR MUST BE 1 OR 2
000064:	11. 000245	(0087)	CAS	='260	
000065:	11. 000250	(0088)	CAS	='263	
000066:	01. 000032	(0089)	JMP	NEXTMODULE	
000067:	01. 000032	(0090)	JMP	NEXTMODULE	
000070:	05. 000002A	(0091)	ERA	2	VALID MODULE
000071:	04. 000226	(0092)	STA	MODULE	SAVE FOR MODULE CHECK
		(0093) *			
000072:	02. 000322	(0094)	LDA	CMBUFF+3	4TH CHAR MUST BE 'U' OR 'L'
000073:	141050	(0095)	CAL		
000074:	11. 000251	(0096)	CAS	=R'U'	
000075:	100000	(0097)	SKP		
000076:	01. 000106	(0098)	JMP	NM20	
000077:	11. 000252	(0099)	CAS	=R'L'	
000100:	01. 000032	(0100)	JMP	NEXTMODULE	
000101:	100000	(0101)	SKP		
000102:	01. 000032	(0102)	JMP	NEXTMODULE	
000103:	04. 000224	(0103)	STA	UL	SAVE FOR TYPE-OUT
000104:	140040	(0104)	CRA		
000105:	01. 000110	(0105)	JMP	NM40	
		(0106) *			
000106:	04. 000224	(0107)	NM20	STA	UL
000107:	02. 000253	(0108)	LDA	='2000	SAVE FOR TYPE-OUT
000110:	04. 000225	(0109)	NM40	STA	SPECIFY UPPER CONTROL BANK
		(0110) *			SAVE FOR BASE CALCULATION
000111:	35. 000316	(0111)	LDX	TBLCNT	CHECK FOR VALID MODULE NAME
000112:	02. 000254	(0112)	LDA	=TABLE	
000113:	04. 000223	(0113)	STA	TBLPT	TABLE POINTER AT START OF MODULE TABLE
000114:	42. 000223	(0114)	NM50	LDA*	FETCH MODULE NAME

000115:	05. 000226	(0115)	ERA	MODULE	
000116:	101040	(0116)	SNZ		
000117:	01. 000141	(0117)	JMP	MODULELOAD	MATCH, GO LOAD WCS
000120:	12. 000223	(0118)	IRS	TBLPT	BUMP TWICE TO POINT AT NEXT ENTRY
000121:	12. 000223	(0119)	IRS	TBLPT	
000122:	140114	(0120)	IRX		
000123:	01. 000114	(0121)	JMP	NM50	
000124:	01. 000032	(0122)	JMP	NEXTMODULE	NO MATCH, INVALID RESPONSE
	(0123) *				
	000125	(0124) DONE	EQU	*	RETURN TO OPERATING SYSTEM
000125:	031724	(0125)	OCP	'1700+DEV	LEAVE WCS BOARD INITIALIZED
000126:	10. 000000E	(0126)	CALL	EXIT	
000127:		(0127)	ELM		
000130:	01. 000000	(0128)	JMP	BEGN	RESTART
	(0129) *				
000131:	02. 000223	(0130) NEXT	EQU	*	USE NEXT SEQUENTIAL MODULE
000132:	140304	(0131)	LDA	TBLPT	
000133:	04. 000223	(0132)	A2A		
000134:	11. 000255	(0133)	STA	TBLPT	
000135:	11. 000256	(0134)	CAS	=TABLE-1	MUST BE WITHIN TABLE BOUNDS
000136:	01. 000032	(0135)	CAS	=TBLCNT	
000137:	01. 000032	(0136)	JMP	NEXTMODULE	
000140:	01. 000141	(0137)	JMP	NEXTMODULE	
	(0138)		JMP	MODULELOAD	
	(0139) *				
	(0140) *				LOAD MODULE POINTED AT BY TBLPT INTO WCS
	(0141) *				
000141:	0142) MODULELOAD	EQU *			
	(0143) *				
000141:	35. 000257	(0144)	LDX	==256	1K CHIP IS 256X4
000142:	02. 000232	(0145)	LDA	=BUFF	SET BASE TO START OF UPPER OR LOWER BANK
000143:	06. 000225	(0146)	ADD	ULBASE	
000144:	04. 000222	(0147)	STA	BASE	
000145:	031724	(0148)	OCP	'1700+DEV	INITIALIZE WCS
	(0149) *				
000146:	02. 000223	(0150)	ML10	LDA	FETCH START BIT OF THIS 64 BIT ENTRY
000147:	141206	(0151)	A1A		
000150:	42. 0000001A	(0152)	LDA*	1	

000151:	040074	(0153)	LRL	4	SPLIT INTO 16 BIT WORD AND BIT WITHIN WORD
000152:	06. 000222	(0154)	ADD	BASE	
000153:	04. 000220	(0155)	STA	TEMP	SAVE WORD
000154:	140040	(0156)	CRA		
000155:	041074	(0157)	LLL	4	GET BIT POSITION BACK
000156:	06. 000260	(0158)	ADD	=3	MAKE INTO A POSITIVE SHIFT COUNT
000157:	140407	(0159)	TCA		
000160:	03. 000261	(0160)	ANA	='77	NEGATIVE SHIFT COUNT IN 6 BITS
000161:	06. 000262	(0161)	ADD	='041600	ALR WITH CALCULATED COUNT
000162:	04. 000164	(0162)	STA	ML20	
000163:	42. 000220	(0163)	LDA*	TEMP	FETCH WORD
000164:	000000	(0164)	ML20	OCT	SHIFT
000165:	170124	(0165)	OTA	'100+DEV	LOAD RAM
000166:	000000	(0166)	HLT		
000167:	170124	(0167)	OTA	'100+DEV	
000170:	000000	(0168)	HLT		
000171:	170124	(0169)	OTA	'100+DEV	
000172:	000000	(0170)	HLT		
000173:	170124	(0171)	OTA	'100+DEV	
000174:	000000	(0172)	HLT		
	(0173) *				
000175:	02. 000222	(0174)	LDA	BASE	MOVE BASE BY 64 BITS
000176:	06. 000227	(0175)	ADD	=4	
000177:	04. 000222	(0176)	STA	BASE	
000200:	140114	(0177)	IRX		
000201:	01. 000146	(0178)	JMP	ML10	GO LOOP
	(0179) *				
000202:	02. 000263	(0180)	LDA	='40000	LET PROM DEVICE ACCESS RAM
000203:	170324	(0181)	OTA	'300+DEV	
000204:	000000	(0182)	HLT		
	(0183) *				
000205:	42. 000223	(0184)	LDA*	TBLPT	TYPE MODULE NUMBER TO USER
000206:	040070	(0185)	LRL	8	
000207:	10. 000000E	(0186)	CALL	T10B	
000216:	02. 000247	(0187)	LDA	=R'--'	
000211:	10. 000000E	(0188)	CALL	T10B	
000212:	041070	(0189)	LLL	8	
000213:	10. 000000E	(0190)	CALL	T10B	

```

000214: 02. 000224 (0191)      LDA    UL
000215: 10. 000000E (0192)     CALL   T10B
000216: 10. 000000E (0193)     CALL   TONL
000217: 01. 000032 (0194)      JMP    NEXTMODULE READY FOR NEXT REQUEST
000218:          (0195) *
000219:          (0196) *      STORAGE
000220: 000000 (0198) TEMP OCT  0
000221: 000000 (0199) X OCT  0
000222: 000000 (0200) BASE OCT  0
000223: 000000 (0201) TBLPT OCT  0
000224: 000000 (0202) UL OCT  0
000225: 000000 (0203) UBASE OCT  0
000226: 000000 (0204) MODULE OCT  0
000227:          (0205) *
000228: 00. 000004A (0206)      FIN
000229: 00. 000000A
000230: 00. 000001A
000231: 00. 010000A
000232: 00. 004000A
000233: 00. 000011A
000234: 00. 000025
000235: 00. 146717A
000236: 00. 142325A
000237: 00. 146305A
000238: 00. 120275A
000239: 00. 120240A
000240: 00. 000321A
000241: 00. 000316A
000242: 00. 000260A
000243: 00. 000270A
000244: 00. 000255A
000245: 00. 000263A
000246: 00. 000325A
000247: 00. 000314A
000248: 00. 0002000A
000249: 00. 000264
000250: 00. 000263

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000251: 00. 000316
000252: 00. 177400A
000253: 00. 000003A
000254: 00. 000077A
000255: 00. 041600A
000256: 00. 040000A
000257:          (0207) *
000258:          (0208) *
000259: 000264 (0209) TABLE EQU   *      CONTAINS MODULE NAME AND 1ST BIT OF 64 FOR THAT MODULE
000260:          (0210) *
000261: 130661 (0211)      DATA   C'11',1
000262: 000001
000263: 130662 (0212)      DATA   C'12',5
000264: 000005
000265: 000267: 131261 (0213)      DATA   C'21',9
000266: 000005
000267: 000011
000268: 131262 (0214)      DATA   C'22',13
000269: 000015
000270: 131661 (0215)      DATA   C'31',17
000271: 000021
000272: 131662 (0216)      DATA   C'32',21
000273: 000025
000274: 000015
000275: 132261 (0217)      DATA   C'41',25
000276: 000031
000277: 132262 (0218)      DATA   C'42',29
000278: 000035
000279: 132662 (0219)      DATA   C'52',45
000280: 000055
000281: 133261 (0220)      DATA   C'61',49
000282: 000061
000283: 133262 (0221)      DATA   C'62',53
000284: 000065
000285: 133661 (0222)      DATA   C'71',57
000286: 000071
000287: 133662 (0223)      DATA   C'72',61
000288: 000075
000289:          (0224) *

```

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000316:	177763	(0225) TBLCNT DATA	(TABLE-*)/2	NEGATIVE NUMBER OF ENTRIES IN TABLE
		(0226) *		
000317:		(0227) CMBUFF BSS	81	USER RESPONSE BUFFER
		(0228) *		
	000440	(0229) END	BEGN	

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0000 ERRORS <PMA-1080.013>

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